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ON A DEGENERATE PARABOLIC BOUNDARY VALUE PROBLEM

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A nonlinear degenerate parabolic boundary value problem is considered in the form

$$(E) \quad \alpha(x) \frac{\partial u}{\partial t} - \sum_{i=1}^N \frac{\partial}{\partial x_i} a_i(x, u, \nabla u) + a_0(x, u, \nabla u) = f(x, t)$$

on  $\Omega \times (0, T) \geq 0$  where  $\Omega \subset \mathbb{R}^N$  is a bounded domain and  $\alpha(x) \geq 0$  is a measurable function on  $\Omega$ . A corresponding Dirichlet boundary condition and initial condition  $u(x, 0) = u_0(x)$  is assumed.

Together with (E) a corresponding parabolic variational inequality is considered. The problems of the existence uniqueness of the solution in the corresponding functional spaces is solved. Two cases are considered:

- I.  $\alpha(x) > 0$  for a.e.  $x \in \Omega$
- II.  $\alpha(x) = 0$  in  $\Omega_2 \subset \Omega$  ( $\Omega_2$  is an open subset in  $\Omega$ )  
and  $\alpha(x) > 0$  a.e. in  $\Omega_1 = \bar{\Omega} - \Omega_2$  where the boundaries  $\partial\Omega, \partial\Omega_1, \partial\Omega_2$  are Lipschitz continuous.

The problem (E) and the corresponding variational inequality we set in an abstract form.

Case I. Let  $X$  be reflexive  $B$ -space with its dual  $X^*$  with the corresponding norms  $\|\cdot\|_X, \|\cdot\|_{X^*}$ . The duality between  $X^*$  and  $X$  we denote by  $\langle \cdot, \cdot \rangle$ . Let  $H_1, H_2$  be the real Hilbert spaces with the corresponding norms  $\|\cdot\|_1, \|\cdot\|_2$ . Suppose that  $[\cdot, \cdot]$  is a continuous bilinear form between the elements of  $H_1$  and  $H_2$  satisfying

$$| [u, v] | \leq \|u\|_2 \|v\|_1 \quad \text{for } u \in H_2, v \in H_1.$$

We identify  $H_1, H_2$  with their duals. A linear operator  $G \in L(H_1, H_2)$  is considered. Let  $A : X \rightarrow X^*$  be a monotone operator. We assume that  $X \cap H_1$  is a nonempty  $B$ -space with the standard norm  $\|\cdot\|_{V \cap H_1} = \|\cdot\|_X + \|\cdot\|_1$ . Moreover we assume that  $\|u\|_1 = 0$

implies  $\|u\|_X = 0$  for  $u \in V \cap H_1$ . By  $I$  we denote the interval  $\langle 0, T \rangle$ ,  $T < \infty$ .

Problem  $P_1$ . Let  $u_0 \in X \cap H_1$  and  $f \in C(I, H_2)$ .

Find a  $u \in L_\infty(I, X \cap H_1) \cap C(I, H_1)$  such that  $u(0) = u_0$

$\frac{du}{dt} \in L_\infty(I, H_1)$  and the identity

$$(1) \quad \left[ G \frac{du(t)}{dt}, v \right] + \langle A u(t), v \rangle = [f(t), v]$$

holds for every  $v \in X \cap H_1$  and a.e.  $t \in I$ .

Problem  $P'_1$ . Let  $K$  be a closed convex subset in  $X \cap H_1$ ,  $u_0 \in K$  and  $f \in C(I, H_2)$ . Find a  $u \in L_\infty(I, K) \cap C(I, H_1)$  such that

$u(0) = u_0$ ,  $\frac{du}{dt} \in L_\infty(I, H_1)$  and the inequality

$$(1') \quad \left[ G \frac{du(t)}{dt}, v - u(t) \right] + \langle A u(t), v - u(t) \rangle \leq [f(t), v - u(t)]$$

holds for all  $v \in K$  and a.e.  $t \in I$ .

The identity (1) can be interpreted as the corresponding operator equation in  $X^* + H_2$ . When  $X \cap H_1$  is a dense set in  $X$  and  $H_1$  then the corresponding operator equation can be interpreted in  $H_2$ .

Remark. As an application for the problem (E) we set  $H_1 = L_2(\Omega, \alpha)$ ,  $H_2 = L_2(\Omega, \alpha^{-1})$  (weighted spaces with respect to  $\alpha, \alpha^{-1}$ , respectively). We put  $[u, v] = \int_{\Omega} u v dx$ ,  $G u = \alpha(x)u$  and  $A : X \rightarrow X^*$

we define by the form

$$\langle A u, v \rangle = \int_{\Omega} \left\{ \sum_{i=1}^N \frac{\partial v}{\partial x_i} a_i(x, u, \nabla u) + v a_0(x, u, \nabla u) \right\} dx$$

$$\text{for } u, v \in X \equiv W_p^1(\Omega)$$

under the assumption  $|a_i(x, \xi)| \leq C(1 + |\xi|^{p-1})$  ( $p > 1$ )

for  $i=0, 1, \dots, N$ . In general case  $H_1$  is not necessarily separable and  $X \cap H_1$  is not dense set in  $X$  and  $H_1$ .

When  $\int_{\Omega} \alpha(x) |x_1|^{i_1} \dots |x_N|^{i_N} dx < \infty$  for all  $0 \leq i_j < \infty$ ,

$i = 1, \dots, N$ , then the space  $H_1$  is separable and  $X \cap H_1$  is a dense set in  $X$  and  $H_1$ .

The problems  $P_1$  and  $P'_1$  we solve under the following assumptions:

- (2)  $A : X \rightarrow X^*$  is bounded and demicontinuous;  
 (3)  $\langle Au - Av, u - v \rangle \geq 0$  for  $u, v \in X$ ;  
 (4)  $f \in C(I, H_2)$  with  $\text{Var}_I(f, H_2) < \infty$ ,

where  $\text{Var}_I(f, H_2) = \sup_{\{t_i\}_0^m} \sum_{i=1}^m \|f(t_i) - f(t_{i-1})\|_2$  and  $\{t_i\}_0^m$

is a finite division of  $I$ .

- (5)  $(\langle Au, u \rangle + \alpha \|u\|_1^2) / \|u\|_X \rightarrow \infty$  for  $\|u\|_X \rightarrow \infty$ ,  
 for suitable  $\alpha \geq 0$ .

In the case of the problem  $P'_1$  we replace (5) by the assumption

- (5')  $\exists v_0 \in K : \langle Au, u - v_0 \rangle / [u]_X \rightarrow \infty$  for  $[u] \rightarrow \infty$

where  $[u]$  is a seminorm in  $X$  satisfying:  $\exists \beta > 0$  such that  
 $[u]_X + \beta \|u\|_1 \geq C \|u\|_X$  for  $u \in X \cap H_1$ .

We assume

- (6)  $[Gu, v] \leq \|u\|_1 \|v\|_1$  and  $[Gu, u] = \|u\|_1^2$ .

### Theorem 1.

i/ Let  $u_0 \in X \cap H_1$  and let (2) - (6) be satisfied. If

- (7)  $\sup_{\|v\|_1 \leq 1, v \in X \cap H_1} |\langle Au_0, v \rangle| < \infty$

holds then there exists the unique solution of the problem  $P_1$ .

ii/ Let  $u_0 \in K$  and let (2) - (7) be satisfied.

Then there exists the unique solution of the problem  $P'_1$ .

The method of the proof is based on Rothés method /method of lines/. Let  $u_i (i=1, \dots, n)$  be corresponding problems

- (8)  $[Gu, v] + h \langle Au, v \rangle = h [f(t_1), v] - [Gu_{i-1}, v]$

- (8')  $([Gu, v - u] + h \langle Au, v - u \rangle \geq h [f(t_1), v - u] - [Gu_{i-1}, v - u])$

where  $h = \frac{T}{n}$ ,  $t_j = jh (j = 1, \dots, n)$ . By means of  $u_i (i=1, \dots, n)$  we construct the function

$$u_n(t) = u_{j-1} + h^{-1}(t-t_{j-1})(u_j - u_{j-1}), \quad t_{j-1} \leq t \leq t_j, \\ j = 1, \dots, n.$$

On the base of (8) ((8')) using (3) - (7) we obtain (similarly as in [2-4]) the a priori estimates

$$\| \frac{du_n(t)}{dt} \|_1 \leq C, \quad \| u_n(t) \|_{X \cap H_1} \leq C \quad (C \text{ is independent on } t \text{ and } n)$$

which allows us to take limit for  $n \rightarrow \infty$  in the approximate identity

$$(9) \quad \left[ G \frac{du_n(t)}{dt}, v \right] + \langle A \bar{u}_n(t), v \rangle = \langle f_n(t), v \rangle$$

which we obtain from (7) where  $\bar{u}_n(t) = u_j$  for  $t_{j-1} < t \leq t_j$ ,  $\bar{u}_n(0) = u_0$  is the step function. Analogously we construct  $\bar{f}_n(t)$ . Similarly we proceed in (8').

Theorem 2.

Let (2-7) be satisfied and  $f: I \rightarrow H_2$  is Lipschitz continuous, i.e.,  $\| f(t) - f(t') \| \leq C |t - t'|$ .

Then the estimate holds

$$\| u_n(t) - u(t) \|_{C(I, H_1)}^2 \leq \frac{C}{n}$$

where  $u(t)$  is the solution of the problem  $P_1(P'_1)$ .

The case II. To give an abstract formulation corresponding to this case we follow the concept of [1].

Let  $A, G, H_1, H_2$  and  $X$  be as in the case I. In the case II. they correspond to the subset  $\Omega_1$ . Let  $Y$  be a reflexive space with its dual  $Y^*$  and duality  $\langle \cdot, \cdot \rangle_*$ . We consider a demicontinuous, coercive and strongly monotone operator  $B: Y \rightarrow Y^*$  satisfying

$$(10) \quad \langle B u - B v, u - v \rangle_* \geq C \| u - v \|_Y^p \quad (p > 1)$$

$$(11) \quad \langle B y, y \rangle_* / \| y \|_Y + \infty \quad \text{for } \| y \|_Y \rightarrow \infty$$

( $Y$  and  $B$  correspond to the subset  $\Omega_2$ ). We define Cartesian product  $W = X \cap H_1 \times Y$  with the standard norm. Let  $T: W \rightarrow W^*$  be the operator defined by the form

$$(T u, v) = \langle A u_1, v_1 \rangle + \langle B u_2, v_2 \rangle_* \\ \text{for } u = \{u_1, u_2\}, v = \{v_1, v_2\} \in W.$$

We denote by  $(f, v) = [f_1, v_1] + \langle f_2, v_2 \rangle_*$  for  $f_1 \in H_2, f_2 \in Y^*$ . Let  $V$  be a (suitable) nonempty subspace of  $W$ .

Problem P<sub>2</sub>. Let  $f_1 \in C(I, H_2)$ ,  $f_2 \in C(I, Y^*)$ ,  $u_0 \in X \cap H_1$ . To look for  $u \in L_\infty(I, V)$  ( $u(t) = \{u_1(t), u_2(t)\}$ ) such that

$$\frac{du_1}{dt} \in L_\infty(I, H_1), u_1(0) = u_0 \text{ and the identity}$$

$$\left[ G \frac{du_1(t)}{dt}, v_1 \right] + (T u(t), v) = (f(t), v) \text{ for all } v \in V.$$

Analogously (as in the case I) we define problem P'<sub>2</sub> corresponding to the variational inequality.

Example. Considering problem (E) under the growth assumption

$|a_i(x, \xi)| \leq C(1 + |\xi|^{p-1})$  ( $i = 0, 1, \dots, N$ ;  $p > 1$ , we set:

$$H_1 = L_2(\Omega_1, \alpha), \quad H_2 = L_2(\Omega_1, \alpha^{-1}),$$

$$X = \{v \in W_p^1(\Omega_1) : v=0 \text{ on } \partial\Omega \cap \partial\Omega_1\}$$

$$Y = \{v \in W_p^1(\Omega_2) : v=0 \text{ on } \partial\Omega \cap \partial\Omega_2\}$$

$$\langle Au_1, v_1 \rangle = \int_{\Omega_1} \left\{ \sum_{i=1}^N a_i(x, u_1, \nabla u_1) \frac{\partial v_1}{\partial x_i} + a_0(x, u_1, \nabla u_1) v_1 \right\} dx$$

$$\langle Bu_2, v_2 \rangle = \int_{\Omega_2} \left\{ \sum_{i=1}^N a_i(x, u_2, \nabla u_2) \frac{\partial v_2}{\partial x_i} + a_0(x, u_2, \nabla u_2) v_2 \right\} dx$$

The elements  $u = \{u_1, u_2\} \in W$  we represent as a function on  $\Omega$  such that  $u = u_1$  on  $\Omega_1$  and  $u = u_2$  on  $\Omega_2$ . We define  $V \equiv W_p^1(\Omega) \cap L_2(\Omega_1, \alpha)$ .

Theorem 3.

Let (2) - (7), (10), (11) be satisfied. If  $\text{Var} \int_I (f_1, H_2) < \infty$ ,  $\|f_2(t) - f_2(t')\|_{Y^*} \leq C|t - t'|$  ( $t, t' \in I$ ) holds then there exists the unique solution of the problem P<sub>2</sub>.

Similar result can be obtained for the problem P'<sub>2</sub> corresponding to the variational inequality.

R E F E R E N C E S

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