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ALGEBRAIC CHARACTERIZATION OF THE DIMENSION
OF DIFFERENTIAL SPACES

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This work is a continuation of our previous investigations of the dimension problem for the tangent space to a differential space at a point [1]. Here we present a full characterization of the tangent space dimension basing on algebraic properties of the linear ring of all smooth functions on a differential space in the sense of Sikorski [7],[8].

1. PRELIMINARIES. Let M be any set and let C be any non-empty set of real functions on M . By τ_C we shall denote the weakest topology on M in which all functions from C are continuous. For any subset $A \subset M$, let C_A be the set of all real functions β on A such that, for any $p \in A$, there exist an open neighbourhood $U \in \tau_C$ of p and a function $\alpha \in C$ such that $\beta|_{A \cap U} = \alpha|_{A \cap U}$. By scC we shall denote the family of all real functions on M of the form $\omega \cdot (\alpha_1, \dots, \alpha_n)$, where $\omega \in \mathcal{C}_n$, $\alpha_1, \dots, \alpha_n \in C$, $n \in \mathbb{N}$, and $\mathcal{C}_n = C^{\infty}(\mathbb{R}^n)$.

A family C of real functions on M is called the differential structure (shortly a d -structure) on M if $C = C_M = scC$ [8]. The pair (M, C) is said to be a differential space (shortly a d -space); the family C is then a linear ring [8] and its elements are called smooth functions on M . For an arbitrary set C_0 of real functions on M , the set $(scC_0)_M$ is the smallest differential structure on M containing C_0 . A differential structure C is said to be generated by C_0 if $C = (scC_0)_M$.

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By a tangent vector to a d -space (M, C) at a point $p \in M$ we shall mean any linear mapping $v: C \rightarrow \mathbb{R}$ which satisfies the condition

$$v(\alpha \cdot \beta) = v(\alpha) \cdot \beta(p) + \alpha(p) \cdot v(\beta)$$

for $\alpha, \beta \in C$. By $T_p M$ we shall denote the linear space of all tangent vectors to (M, C) at $p \in M$, called the tangent space to (M, C) at $p \in M$. The C -module of all derivations of the linear ring C will be denoted by $\mathfrak{X}(M)$. In the pointwise interpretation $\mathfrak{X}(M)$ is the C -module of all smooth vector fields tangent to (M, C) [7], [8]. A sequence $W_1, \dots, W_n \in \mathfrak{X}(M)$ is said to be a vector basis of the C -module $\mathfrak{X}(M)$ if for every point $p \in M$ the sequence $W_1(p), \dots, W_n(p)$ is a basis of $T_p M$. We say that the differential space (M, C) is of constant differential dimension n if every point $p \in M$ has a neighbourhood $U \in \tau_C$ such that there is a vector basis of $\mathfrak{X}(U)$ composed of n vector fields.

2. MAIN RESULTS. Let (M, C) be a differential space. For any $p \in M$ we shall denote by σ_p the set of all smooth functions $f \in C$ for which there exists an open neighbourhood $U \in \tau_C$ of p and functions $f_1, \dots, f_n \in C$, $\omega \in \mathfrak{E}_n$, for some $n \in \mathbb{N}$, such that

$$f|U = \omega \circ (f_1, \dots, f_n)|U$$

and $\omega'_{ij}(f_1(p), \dots, f_n(p)) = 0$ for $j = 1, \dots, n$.

It can easily be seen that σ_p is a linear subspace of C .

Let C/σ_p be the quotient linear space and $[f]_p$ the equivalence class of $f \in C$.

LEMMA 1. Let (M, C) be a d -space, $p \in M$ an arbitrary point. Then

$$1^\circ \quad [\theta \cdot (\alpha_1, \dots, \alpha_n)]_p = \sum_{i=1}^n \theta'_{i1}(\alpha_1(p), \dots, \alpha_n(p)) [\alpha_i]_p$$

for any $\alpha_1, \dots, \alpha_n \in C$, $\theta \in \mathfrak{E}_n$, $n \in \mathbb{N}$.

$$2^\circ \quad [\alpha \cdot \beta]_p = \alpha(p) \cdot [\beta]_p + [\alpha]_p \cdot \beta(p) \text{ for any } \alpha, \beta \in C.$$

3^o If $f, g \in C$ and $f|U = g|U$ for a neighbourhood $U \in \tau_C$ of p , then $[f]_p = [g]_p$.

$$4^\circ \quad \text{If } k \in C \text{ is a constant function then } [k]_p = 0.$$

Proof. 1^o It is enough to show that

$$\theta \circ (\alpha_1, \dots, \alpha_n) = \sum_{i=1}^n \theta'_{li}(\alpha_1(p), \dots, \alpha_n(p)) \cdot \alpha_i \in \mathcal{O}_p.$$

Let $\omega \in \mathcal{E}_n$ be a function given by the formula

$$\omega(x_1, \dots, x_n) = \theta(x_1, \dots, x_n) - \sum_{i=1}^n \theta'_{li}(\alpha_1(p), \dots, \alpha_n(p)) \cdot x_i$$

for $(x_1, \dots, x_n) \in \mathbb{R}^n$. We see that

$$\omega \circ (\alpha_1, \dots, \alpha_n) = \theta(\alpha_1, \dots, \alpha_n) - \sum_{i=1}^n \theta'_{li}(\alpha_1(p), \dots, \alpha_n(p)) \cdot \alpha_i$$

and

$$\omega'_{li}(\alpha_1(p), \dots, \alpha_n(p)) = 0 \quad \text{for } i = 1, \dots, n.$$

Hence

$$\theta \circ (\alpha_1, \dots, \alpha_n) = \sum_{i=1}^n \theta'_{li}(\alpha_1(p), \dots, \alpha_n(p)) \cdot \alpha_i \in \mathcal{O}_p.$$

2° follows from 1° if we take $\theta \in \mathcal{E}_2$, given by $\theta(x_1, x_2) = x_1 \cdot x_2$ for $(x_1, x_2) \in \mathbb{R}^2$. 3° and 4° are obvious.

Let $v \in T_p M$ be any vector tangent to (M, C) at $p \in M$. Note that $v|_{\mathcal{O}_p} = 0$. Hence v induces a linear functional $l_v \in (C/\mathcal{O}_p)^*$ defined by

$$(1) \quad l_v([f]_p) := v(f) \quad \text{for any } f \in C.$$

PROPOSITION 1. The mapping $I: T_p M \rightarrow (C/\mathcal{O}_p)^*$ defined by

$$(2) \quad I(v) := l_v \quad \text{for any } v \in T_p M$$

is an isomorphism of linear spaces.

Proof. The linearity of the mapping I is clear. Obviously if $l_v = 0$ for some $v \in T_p M$, then $v = 0$. Hence I is a monomorphism. Now we shall show that I is an epimorphism. For any $l \in (C/\mathcal{O}_p)^*$, let $v_l: C \rightarrow \mathbb{R}$ be the mapping defined by

$$(3) \quad v_l(f) := l([f]_p) \quad \text{for } f \in C.$$

It follows from condition 2° of Lemma 1 that v_l is a tangent vector to (M, C) at p such that $I(v_l) = l$.

COROLLARY 1. Let (M, C) be a d -space and $p \in M$. Then for any $n \in \mathbb{N}$, $\dim T_p M = n$ if and only if $\dim C/\mathcal{O}_p = n$. In particular $\dim T_p M = 0$ iff $C = \mathcal{O}_p$.

COROLLARY 2. Let (M, C) be a d -space and $p \in M$. If $f \in C$ satisfies $v(f) = 0$ for each $v \in T_p M$, then $f \in \mathcal{O}_p$.

Proof. If $v(f) = 0$ for any $v \in T_p M$, then for an arbitrary

linear functional $l \in (C/\alpha_p)^*$, $l([f]_p) = v_1(f) = 0$. Hence we get $[f]_p = 0$ or equivalently $f \in \alpha_p$.

DEFINITION 1. A set $\mathcal{F} \subset C$ is said to be a local basis (1-basis for short) of the differential structure C on M at $p \in M$ if any function $f \in C$ can be uniquely expressed in the form

$$f = \lambda^1 \cdot f_1 + \dots + \lambda^n \cdot f_n + g,$$

where $f_1, \dots, f_n \in \mathcal{F}$, $\lambda^1, \dots, \lambda^n \in \mathbb{R} \setminus \{0\}$, $g \in \alpha_p$.

PROPOSITION 2. Let (M, C) be a d -space with the differential structure C generated by a set C_0 . Then, for any $p \in M$, there exists an 1-basis \mathcal{F} of C at p such that $\mathcal{F} \subset C_0$.

Proof. Consider the quotient space C/α_p . It can easily be seen that the set $\{[f]_p : f \in C_0\}$ generates the linear space C/α_p . Let $B := \{[f_s]_p : f_s \in C_0, s \in S\}$, where S is a set of indices, be a basis of C/α_p . Then the set $\mathcal{F} := \{f_s : s \in S\}$ is clearly an 1-basis of the differential structure C at p .

LEMMA 2. Let (M, C) be a d -space with C generated by C_0 . Then, for any $p \in M$, in the definition of α_p we can take f_i to belong to C_0 (see the beginning of this section).

The proof of this lemma is obvious.

LEMMA 3. The set α_p is a differential structure on M such that $\tau_{\alpha_p} = \tau_C$.

Proof. Let $f_1, \dots, f_n \in \alpha_p$. We shall show that $\omega \cdot (f_1, \dots, f_n) \in \alpha_p$. Indeed, from condition 1° of Lemma 1 it follows that

$$[\omega \cdot (f_1, \dots, f_n)]_p = \sum_{i=1}^n \omega'_{i1}(f_1(p), \dots, f_n(p)) \cdot [f_i]_p = 0,$$

or equivalently $\omega \cdot (f_1, \dots, f_n) \in \alpha_p$.

In order to show that $\tau_{\alpha_p} = \tau_C$ observe that

$$A := \{(f - f(p))^3 : f \in C\} \subset \alpha_p \subset C.$$

It is trivial that $\tau_A = \tau_C$. Since $A \subset \alpha_p \subset C$ implies

$$\tau_A \subset \tau_{\alpha_p} \subset \tau_C, \text{ we see that } \tau_{\alpha_p} = \tau_C.$$

LEMMA 4. Let (M, C) be a d -space and let \mathcal{F} be an 1-basis of the d -structure C at $p \in M$. For any function $u_0 : \mathcal{F} \rightarrow \mathbb{R}$ there exists exactly one tangent vector $u : C \rightarrow \mathbb{R}$ at p such that $u|_{\mathcal{F}} = u_0$.

Proof. Let $u: C \longrightarrow R$ be a mapping given by the formula

$$(5) \quad u(f) = \sum_{i=1}^n \lambda^i \cdot u_0(f_i) \text{ for } f \in C,$$

where $f_1, \dots, f_n \in \mathcal{F}$, $\lambda^1, \dots, \lambda^n \in R$ are elements such that

$f = \sum_{i=1}^n \lambda^i \cdot f_i + g$, where $g \in \alpha_p$. It can easily be noticed that u is a linear mapping and $u|_{\alpha_p} = 0$, hence $u \in T_p M$, and $u|_{\mathcal{F}} = u_0$. The uniqueness of u is clear.

LEMMA 5. All 1-bases of a differential structure C at $p \in M$ are of the same cardinality. If C_0 generates C then, for any 1-basis \mathcal{F} of C at $p \in M$, $\text{Card } \mathcal{F} \leq \text{Card } C_0$.

Proof. Let \mathcal{F}_1 and \mathcal{F}_2 be two 1-basis of C at p . Then the sets $[\mathcal{F}_1]_p := \{[f]_p : f \in \mathcal{F}_1\}$ and $[\mathcal{F}_2]_p := \{[f]_p : f \in \mathcal{F}_2\}$ are bases of the linear space C/α_p , and $\text{Card } \mathcal{F}_1 = \text{Card } [\mathcal{F}_1]_p$ for $i = 1, 2$. Obviously, $\text{Card } [\mathcal{F}_1]_p = \text{Card } [\mathcal{F}_2]_p$. Hence $\text{Card } \mathcal{F}_1 = \text{Card } \mathcal{F}_2$. The second assertion follows from the first and Proposition 2.

PROPOSITION 3. Let (M, C) be a d -space and let $\mathcal{F} \subset C$ be an 1-basis of C at $p \in M$. Then the mapping $\phi: T_p M \longrightarrow R$ defined by

$$(6) \quad \phi(u) := u|_{\mathcal{F}} \quad \text{for } u \in T_p M$$

is an isomorphism of linear spaces.

Proof. This follows immediately from Lemma 4.

COROLLARY 3. Let (M, C) be a d -space and let \mathcal{F} be an 1-basis of C at $p \in M$. Then

$$(a) \quad \text{Card } \mathcal{F} < \infty \implies \text{Card } \mathcal{F} = \dim T_p M$$

$$(b) \quad \text{Card } \mathcal{F} = \infty \implies 2^{\text{Card } \mathcal{F}} = \dim T_p M.$$

PROPOSITION 4. A d -space (M, C) is of constant differential dimension n if and only if, for any $p \in M$, there exist a neighbourhood $U \in \tau_C$ of p and a subset $\{f_1, \dots, f_n\} \subset C$ which forms an 1-basis of C at any point of U .

Proof. " \implies " Assume that (M, C) is of constant dimension n . Then for any point p there exist an open neighbourhood $V \in \tau_C$ of p and a vector basis $\{w_1, \dots, w_n\} \subset \mathcal{X}(V)$ of the C_V -module $\mathcal{X}(V)$ [7], [8]. It can easily be seen [8] that there exist an open subset $U \subset V$ containing p and functions $f_1, \dots, f_n \in C$ such that

$$(7) \quad W_i(q)(f_j) = \delta_{ij} \quad \text{for } q \in U, i, j = 1, \dots, n.$$

We shall show that the set $\{f_1, \dots, f_n\}$ is an 1-basis at any $q \in U$. Since $\{W_1(q), \dots, W_n(q)\}$ is a basis of the linear space $T_q M$, $I(\{W_1(q), \dots, W_n(q)\})$ is a basis of the linear space $(C/\sigma_q)^*$, where I is the isomorphism given by (2). From (1) and (7) we obtain $I(W_i(q)) = [f_i]_q^*$ for $q \in U, i = 1, \dots, n$. Hence $\{[f_1]_q, \dots, [f_n]_q\}$ is a basis of the linear space C/σ_q for $q \in U$. Let $f \in C$. Then, for $q \in U$, the element $[f]_q$ has a unique decomposition $[f]_q = \lambda^1 \cdot [f_1]_q + \dots + \lambda^n \cdot [f_n]_q$, where $\lambda^1, \dots, \lambda^n \in \mathbb{R} \setminus \{0\}$ or equivalently $f = \lambda^1 \cdot f_1 + \dots + \lambda^n \cdot f_n + g$, where $g \in \sigma_q$. Thus the set $\{f_1, \dots, f_n\}$ is an 1-basis of the d-structure C at any point of U .

" \Leftarrow " Let $p \in M$ and let $U \in \tau_C$ be a neighbourhood of p such that the set $\{f_1, \dots, f_n\} \subset C$ is an 1-basis of C at all $q \in U$. Let W_i , for $i = 1, \dots, n$, be a vector field on U satisfying the condition $W_i(q)(f_j) = \delta_{ij}$ for $q \in U, j = 1, \dots, n$. The uniqueness of the fields W_1, \dots, W_n follows from Lemma 4. We shall show that the vector fields W_1, \dots, W_n are smooth. Each function $f \in C$ has a unique decomposition in the form

$$f = \lambda^1 \cdot f_1 + \dots + \lambda^n \cdot f_n + g,$$

where $\lambda^1, \dots, \lambda^n \in \mathbb{R} \setminus \{0\}$ and $g \in \sigma_p$. One can easily see that $W_i(f|U) = \lambda^i$, for $i = 1, \dots, n$. This demonstrates the smoothness of the vector fields W_1, \dots, W_n . It can easily be seen that $\{W_1(q), \dots, W_n(q)\}$ is a basis of the linear space $T_q M$, for $q \in U$. Thus the d-space (M, C) is of constant differential dimension n .

EXAMPLE. Let C be the d-structure on \mathbb{R} generated by the set of real functions $C_0 := \{f_n : n \in \mathbb{N}\}$, where $f_n(x) := x^{1/(2n-1)}$. Then $\sigma_0 = C$ and $\dim T_x \mathbb{R} = 1$ for $x \in \mathbb{R} \setminus \{0\}$, $\dim T_x M = 0$ for $x=0$.

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