

# EQUADIFF 6

---

Valter Šeda

## Surjectivity and boundary value problems

In: Jaromír Vosmanský and Miloš Zlámal (eds.): Equadiff 6, Proceedings of the International Conference on Differential Equations and Their Applications held in Brno, Czechoslovakia, Aug. 26 - 30, 1985. J. E. Purkyně University, Department of Mathematics, Brno, 1986. pp. [161]--170.

Persistent URL: <http://dml.cz/dmlcz/700167>

### Terms of use:

© Masaryk University, 1986

Institute of Mathematics of the Academy of Sciences of the Czech Republic provides access to digitized documents strictly for personal use. Each copy of any part of this document must contain these *Terms of use*.



This paper has been digitized, optimized for electronic delivery and stamped with digital signature within the project *DML-CZ: The Czech Digital Mathematics Library* <http://project.dml.cz>

# SURJECTIVITY AND BOUNDARY VALUE PROBLEMS

V. ŠEDA

*Faculty of Mathematics and Physics, Comenius University  
Mlynská dolina, 842 15 Bratislava, Czechoslovakia*

In the paper we shall deal with an initial and a boundary problem for the functional differential equation with deviating argument  $x'(t) = f[t, x_{\omega}(t)]$  in a Banach space whereby the functions of the state space are defined in the interval  $(-\infty, 0]$  as well as with the generalized boundary value problem for a system of differential equations in  $\mathbb{R}^n$ . The main tool for proving the existence of a solution to these problems will be some theorems on surjectivity of an operator.

## 1. Surjectivity of an operator.

Let  $(E, \|\cdot\|)$  be a real Banach space,  $\phi \neq X \subset E$  and  $S : X \rightarrow E$ . We recall that  $S$  is *compact* if  $S$  is continuous and maps bounded sets into relatively compact sets. Similarly  $T : X \rightarrow E$  is said to be a *condensing* map if  $T$  is continuous, bounded (i.e. maps bounded sets into bounded sets) and for every bounded set  $A \subset X$  which is not relatively compact we have  $\alpha(T(A)) < \alpha(A)$  where  $\alpha$  is the Kuratowski measure of noncompactness. A simple example of a condensing map is one of the form  $U + V$  where  $U : X \rightarrow E$  is a strict contraction and  $V : X \rightarrow E$  is a compact map.

Let  $G \neq \phi$  be an open subset of  $E$  and denote by  $\bar{G}$  the closure of  $G$ . Let  $T : \bar{G} \rightarrow E$  be a condensing map,  $a \in E$ . If the set  $\tilde{A} = \{x \in G : x - T(x) = a\}$  is compact (possibly empty), then the degree  $\deg(I - T, G, a)$  is defined in the sense of Nussbaum [6] whereby  $I$  is the identity. Notice that  $\tilde{A}$  will certainly be compact if  $G$  is bounded and  $T$  is such that  $x - T(x) \neq a$  for all  $x \in \partial G$  (boundary of  $G$ ) ([6], p. 744). If  $T$  is compact, then the degree above agrees with the classical Leray-Schauder degree.

Denote  $B$  the real Banach space of all continuous functions  $x : [0, \infty) \rightarrow E$  such that there exists  $\lim_{t \rightarrow \infty} x(t) = x(\infty)$  ( $\in E$ ) for  $t \rightarrow \infty$ . The norm in  $B$  is defined by  $\|x\|_2 = \sup\{|x(t)| : 0 \leq t < \infty\}$  for each  $x \in B$ . Let, further,  $U(r) = \{x \in E : |x| < r\}$ . Using the degree theory for condensing perturbations of identity, the topological principle in [8], p. 241, can be generalized as follows (for proof, see [9],[10]).

**Theorem 1.** Let  $g : E \rightarrow B$  be a continuous mapping. Denote by  $g(x, t)$

the value of  $g(x) \in B$  at the point  $t \in [0, \infty]$  ( $g(x, \infty) = \lim_{t \rightarrow \infty} g(x, t)$  for  $t \rightarrow \infty$ ). Assume that

- (i)  $v(x) = \inf\{|g(x, t)| : 0 \leq t \leq \infty\} \rightarrow \infty$  for  $|x| \rightarrow \infty$ ;
- (ii) the mapping  $I - g(\cdot, t)$  is condensing for each  $t \in [0, \infty]$ ;
- (iii) for each  $y \in E$  there is an  $r_0 > 0$  such that

$$\deg(g(\cdot, 0) - y, U(r_0), 0) \neq 0;$$

- (iv)  $g(x, \cdot)$  is continuous in  $t$ , uniformly in  $x \in \overline{U(r)}$  for each  $r > 0$ . Then for each  $t \in [0, \infty]$ 

$$g(E, t) = E.$$

*Proof.* Let  $y \in E$ ,  $t_0 \in [0, \infty]$ . By (i), there is an  $r_0 > 0$ ,  $|y| < r_0$ , such that  $y \notin g(\partial U(r_0), t)$  for each  $t \in [0, \infty]$ . Hence the mapping  $G : \overline{U(r_0)} \times [0, \infty] \rightarrow E$  defined by  $G(x, t) = x - g(x, t) + y$  is continuous and  $G(x, t) \neq x$  for  $x \in \partial U(r_0)$ ,  $t \in [0, \infty]$ . By (ii),  $G(\cdot, t)$  is a condensing map for  $t \in [0, \infty]$  and (iv) implies that  $G(x, \cdot)$  is continuous in  $t$ , uniformly in  $x \in \overline{U(r_0)}$ . Hence, by Corollary 2 in [6], p. 745, and (iii), for each  $t_0$ ,  $0 \leq t_0 < \infty$ ,

$$\begin{aligned} \deg(I - G(\cdot, t_0), U(r_0), 0) &= \deg(I - G(\cdot, 0), U(r_0), 0) = \\ &= \deg(g(\cdot, 0) - y, U(r_0), 0) \neq 0. \end{aligned}$$

As to the set  $S = \{x \in U(r_0) : g(x, t_0) - y = 0\}$ , either it is not compact or in case it is compact we can use Proposition 5 from [6], p. 744, and hence, in both cases it is nonempty.

Corollary 2 as well as Proposition 5 from [6] can be applied to the case  $t_0 = \infty$ , too, since then  $t = tg \frac{\pi}{2} s$  maps  $[0, 1]$  continuously on  $[0, \infty]$  and instead of the function  $G(x, t)$  we consider  $G_1(x, s) = G(x, tg \frac{\pi}{2} s)$ ,  $x \in \overline{U(r_0)}$ ,  $s \in [0, 1]$ .

*Remark.* Clearly the assumption (iii) is satisfied if  $g(x, 0) = x$  for each  $x \in E$ .

On the basis of the Schauder theorem on domain invariance ([2], p. 72) the following result can be proved ([10]).

**Theorem 2.** Let  $T : E \rightarrow E$  be such that

$$(a) \quad \lim_{|x| \rightarrow \infty} |T(x)| = \infty;$$

$$(b) \quad I - T \text{ is compact};$$

(c)  $T$  is locally one-to-one, i.e. for each point  $x_0 \in E$  there is a neighbourhood  $N$  of this point such that  $T|_N$  is one-to-one. Then  $T(E) = E$ .

Proof. The assumptions (b), (c) imply that  $T$  is an open mapping, i.e. it maps open sets onto open sets. Hence  $T(E)$  is an open subset of  $E$ . Let  $\{y_n\} \subset T(E)$  be a convergent sequence and  $y_0 = \lim_{n \rightarrow \infty} y_n$ . Then we can find a sequence  $\{x_n\}$  such that  $T(x_n) = y_n$ . Assumption (a) is equivalent to the statement that the inverse image of a bounded set at the mapping  $T$  is a bounded set. Hence the sequence  $\{x_n\}$  is bounded together with the sequence  $\{y_n\}$ . By (d), there is a subsequence  $\{x_m\}$  of  $\{x_n\}$  and a point  $x_0 \in E$  such that  $x_m - y_m = x_m - T(x_m) \rightarrow x_0$  as  $m \rightarrow \infty$ . Then  $\lim_{m \rightarrow \infty} x_m = y_0 + x_0$ , and by continuity of  $T$ ,  $T(x_0 + y_0) = y_0$ . Thus  $y_0 \in T(E)$  and  $T(E)$  is closed. As  $E$  is connected,  $T(E) = E$ .

Corollary 1. Let  $T : E \rightarrow E$  be such that

- (a)  $\lim_{|x| \rightarrow \infty} |T(x)| = \infty$ ;
- (b)  $I - T$  is compact;
- (c)  $T$  is one-to-one.

Then  $T$  is a homeomorphism of  $E$  onto  $E$  and there is a compact mapping  $T_1 : E \rightarrow E$  such that  $T^{-1} = I - T_1$  where  $T^{-1}$  is the inverse mapping to  $T$ .

Proof. By Theorem 2 and its proof we have that  $T(E) = E$  and the mapping  $T^{-1}$  is continuous. Hence  $T$  is a homeomorphism. For  $T^{-1}$  we have the identity  $I - T^{-1} = (T - I) \circ T^{-1}$ . By (a),  $T^{-1}$  is a bounded mapping and thus, by (b),  $I - T^{-1} = T_1$  is compact.

If  $E = \mathbb{R}^n$ , then Theorem 1 is true without assuming assumptions (ii), (iv) and in Theorem 2 instead of the assumption (b) it suffices to assume the continuity of  $T$ . Choosing properly the mapping  $g : \mathbb{R}^n \rightarrow B$  ( $B$  now means the Banach space of all continuous functions  $x : [0, 1] \rightarrow \mathbb{R}^n$  with the supnorm,  $|\cdot|$  is the euclidean norm in  $\mathbb{R}^n$  and  $(\cdot, \cdot)$  the scalar product in this space) we get the following

Corollary 2. Let  $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$  be a continuous mapping such that

- (i)  $\lim_{|x| \rightarrow \infty} |T(x)| = \infty$ ;
- (ii) either there is an  $x_0 \in \mathbb{R}^n$  such that  $T(x) - x_0 = k(x - x_0)$  implies  $k \geq 0$  for each  $x \in \mathbb{R}^n$ ,  $x \neq x_0$ , or  
there is an  $r_1 > 0$  such that  $(x, T(x)) \geq 0$  for all  $x \in \mathbb{R}^n$ ,  $|x| \geq r_1$

or

$T$  is locally one-to-one.

Then

$$T(\mathbb{R}^n) = \mathbb{R}^n.$$

Proof. a. Consider the first case that there is an  $x_0 \in \mathbb{R}^n$  such that

( $\alpha$ )  $T(x) - x_0 = k(x - x_0)$  implies  $k \geq 0$  for each  $x \in \mathbb{R}^n$ ,  $x \neq x_0$ .

Without loss of generality we may assume that  $x_0 = 0$ . Let the mapping  $g : \mathbb{R}^n \rightarrow B$  be defined by

$$\begin{aligned} g(x,t) &= tT(0) \quad \text{for } x = 0, 0 \leq t \leq 1, \\ g(x,t) &= [(1-t)|x| + t|T(x)|] \cdot [| (1-t)x + tT(x) |]^{-1} \cdot \\ &\quad [ (1-t)x + tT(x) ] \quad \text{for } x \neq 0, 0 \leq t < 1, \\ g(x,t) &= T(x) \quad \text{for } x \neq 0, t = 1. \end{aligned}$$

By ( $\alpha$ ) the mapping  $g$  is well defined. Further  $g(x, \cdot)$  is continuous in  $[0, 1]$  for each  $x \in \mathbb{R}^n$  and thus,  $g$  maps  $\mathbb{R}^n$  into  $B$ . Clearly

( $\beta$ )  $g(x, 0) = x$ ,  $g(x, 1) = T(x)$  for each  $x \in \mathbb{R}^n$ .

Now we prove that  $g$  is continuous. Let  $x \neq 0$  be an arbitrary but fixed point from  $\mathbb{R}^n$  and  $y$  be a point sufficiently close to  $x$ . Then

$$\begin{aligned} |g(x,t) - g(y,t)| &\leq \left| \frac{(1-t)x + tT(x)}{|(1-t)x + tT(x)|} - \frac{(1-t)y + tT(y)}{|(1-t)y + tT(y)|} \right| \cdot \\ &\quad \cdot [ (1-t)|x| + t|T(x)| ] + \\ &\quad + |(1-t)(|x| - |y|) + t(|T(x)| - |T(y)|)|, \quad 0 \leq t \leq 1. \end{aligned}$$

Clearly the second term on the right-hand side is less or equal to

( $\gamma$ )  $(1-t)|x - y| + t|T(x) - T(y)|$ ,  $0 \leq t \leq 1$ .

As to the first term, there is a constant  $k > 0$  such that this term is less or equal to

$$\begin{aligned} k &| (1-t)y + tT(y) |^{-1} \cdot [ (1-t)x + tT(x) ] \cdot | (1-t)y + tT(y) | - \\ &\quad - [ (1-t)y + tT(y) ] \cdot | (1-t)x + tT(x) | | \leq \\ &\leq k | (1-t)y + tT(y) |^{-1} \cdot [ (1-t)(x - y) + t(T(x) - T(y)) ] \cdot \\ &\quad \cdot | (1-t)y + tT(y) | + [ (1-t)y + tT(y) ] \cdot [ | (1-t)y + tT(y) | - \\ &\quad - | (1-t)x + tT(x) | ] |. \end{aligned}$$

Hence the first term is less or equal to

( $\delta$ )  $2k[ (1-t)|x - y| + t|T(x) - T(y)| ]$ ,  $0 \leq t \leq 1$ .

The inequalities ( $\gamma$ ) and ( $\delta$ ) give

$$|g(x,t) - g(y,t)| \leq (2k + 1)[(1 - t)|x - y| + t|T(x) - T(y)|], \\ 0 \leq t \leq 1,$$

which proves the continuity of  $g$  at  $x \neq 0$ . In a similar way it can be shown that  $g$  is continuous at 0.

Now we derive properties (i), (iii) of  $g$  from Theorem 1 and this will complete the proof of this part of Corollary 2. As  $|g(x,t)| = (1 - t)|x| + t|T(x)| \geq \min(|x|, |T(x)|)$ , clearly (i) is satisfied. (iii) follows from ( $\beta$ ).

b. Suppose that there is an  $r_1 > 0$  such that

$$(*) \quad (x, T(x)) \geq 0 \quad \text{for all } x \in \mathbb{R}^n, |x| \geq r_1.$$

Consider the mapping  $g$  which is defined for each  $x \in \mathbb{R}^n$ ,  $0 \leq t \leq 1$ , by

$$g(x,t) = (1 - t)x + tT(x).$$

Clearly  $g : \mathbb{R}^n \rightarrow B$  and  $g$  is continuous. Further  $g$  satisfies ( $\beta$ ). By (\*),  $|g(x,t)|^2 \geq (1 - t)^2|x|^2 + t^2|T(x)|^2 \geq \frac{1}{2} [(1 - t)|x| + t|T(x)|]^2$ . Hence  $g$  satisfies assumption (i) as well as (iii) of Theorem 1. By this theorem the result follows.

c. The statement of Corollary 2 in case that  $T$  is locally one-to-one follows directly from Theorem 2.

## 2. Functional Differential Equations With Deviating Argument

First we formulate the initial-value problem for these equations which includes the problem from [12], [4] and is related to one in [1], [3]. For details and proofs, see [9]. We shall employ the notations:

$(E, \|\cdot\|)$  is a real Banach space.

The state space  $C$  is the Banach space of all continuous and bounded mappings  $x : (-\infty, 0] \rightarrow E$  with the sup-norm  $\|\cdot\|$ .

$\psi : [0, \infty) \rightarrow (0, \infty)$  is a nondecreasing continuous function.

The deviation  $\omega : [0, \infty) \rightarrow \mathbb{R}$  is a continuous mapping such that  $\omega(0) = 0$ .

$f : [0, \infty) \times C \rightarrow E$  is a continuous mapping.

$a^+ = \max(a, 0)$  for each  $a \in \mathbb{R}$ ,  $\text{sgn } 0 = 0$ ,  $\text{sgn } a = 1$  for each  $a > 0$ .

Finally, if  $x : (-\infty, \infty) \rightarrow E$  is a continuous mapping which is bounded in  $(-\infty, 0]$  and  $u \in \mathbb{R}$ , then  $x_u$  is the function defined by

$$x_u(s) = x(u + s) \quad \text{for all } s, -\infty < s \leq 0.$$

Clearly  $x_u \in C$ .

The initial-value problem in the case that  $h \in C$  is uniformly continuous in  $(-\infty, 0]$

$$(1) \quad x'(t) = f[t, x_{\omega(t)}]$$

$$(2) \quad x_0 = h$$

means the problem to find a function  $x$  which is continuous in  $(-\infty, \infty)$ ,  $x(t) = h(t)$  for all  $t \in (-\infty, 0]$ ,  $x$  is differentiable in  $[0, \infty)$  and it satisfies (1) at each point from  $[0, \infty)$ . Since  $\omega$ ,  $f$  are continuous and  $h$  is uniformly continuous, the problem (1),(2) is equivalent to the problem: To find a continuous solution of the integral equation

$$(3) \quad x(t) = h(0) + \int_0^t f[s, x_\omega(s)] ds \quad (0 \leq t < \infty)$$

which satisfies (2).

Consider the following assumptions:

- (A1) The function  $\int_0^t |f(s, 0)| ds$  is  $\psi$ -bounded in  $[0, \infty)$ , i.e.  $|\int_0^t |f(s, 0)| ds| / \psi(t)$  ( $0 \leq t < \infty$ ) is bounded.
- (A2) There exists a nonnegative, locally integrable in  $[0, \infty)$  real function  $n$  such that
- $$|f(t, z_1) - f(t, z_2)| \leq n(t) \|z_1 - z_2\|$$
- for every  $z_1, z_2 \in C$  and  $t \in [0, \infty)$ .
- (A3) The function  $\int_0^t n(s) ds$  is  $\psi$ -bounded in  $[0, \infty)$ .
- (A4) There exists a  $q$ ,  $0 \leq q < 1$ , such that
- $$\int_0^t n(s) \operatorname{sgn} \omega^+(s) \psi[\omega^+(s)] ds \leq q \psi(t) \quad (0 \leq t < \infty).$$
- (A5) There is a  $K > 0$  such that  $\int_0^t |f(s, 0)| ds \leq K$  for all  $t$ ,  $0 \leq t < \infty$ .
- (A6) There is a  $q$ ,  $0 \leq q < 1$ , such that  $\int_0^t n(s) ds \leq q$ ,  $0 \leq t < \infty$ .

The existence of a unique  $\psi$ -bounded solution to (1),(2) is guaranteed by

Lemma 1. If the assumptions (A1)-(A4) are satisfied, then there exists a unique  $\psi$ -bounded in  $[0, \infty)$  solution  $x(t)$  of (1),(2), i.e.  $|x(t)| / \psi(t)$  is bounded in  $[0, \infty)$ .

Proof. Let  $D$  be the vector space of all continuous mappings  $x : (-\infty, \infty) \rightarrow E$  which are bounded in  $(-\infty, 0]$  and  $\psi$ -bounded in  $[0, \infty)$ ,  $D_h = \{x \in D : x(t) = h(t), -\infty < t \leq 0\}$ . Let  $F$  be the Banach space of all continuous and  $\psi$ -bounded mappings  $x : [0, \infty) \rightarrow E$  with the norm  $\|x\|_1 = \sup_{0 \leq t < \infty} |x(t)| / \psi(t)$ . Then in view of the assumptions of the lemma the mapping  $T$  defined by

$$T(x)(t) = h(t), \quad -\infty < t \leq 0,$$

$$T(x)(t) = h(0) + \int_0^t f[s, x_\omega(s)] ds, \quad 0 \leq t < \infty,$$

maps  $D_h$  into  $D_h$  or considering only the restriction of functions from  $D_h$  to  $[0, \infty)$ ,  $T : G \rightarrow G$  where  $G = \{x \in F : x(0) = h(0)\}$  is a closed

subset of  $F$ . By (A2) and (A4)  $|T(x)(t) - T(y)(t)|/\psi(t) \leq \int_0^t n(s) \|x_{\omega(s)} - y_{\omega(s)}\| ds / \psi(t) \leq \|x - y\| \int_0^t n(s) \operatorname{sgn} \omega^+(s) \psi[\omega^+(s)] ds / \psi(t) \leq q \|x - y\|_1$ . The Banach fixed point theorem gives the result.

By considering the bounded solutions of the problem (1), (2) we can prove

**Lemma 2.** If the assumptions (A1)-(A4) are satisfied and  $\psi$  is bounded, then for the unique bounded solution  $x(t)$  of (1),(2) there exists  $\lim_{t \rightarrow \infty} x(t) = c$  ( $\in E$ ).

*Proof.* By (3) and (A2), for  $0 \leq t_1 < t_2 < \infty$  we have  $|x(t_2) - x(t_1)| \leq \int_{t_1}^{t_2} |f(s,0)| ds + \int_{t_1}^{t_2} n(s) \|x_{\omega(s)}\| ds$ . In view of (A1), (A3) and the boundedness of  $\psi$ , by the Cauchy-Bolzano criterion the result follows.

Denote this unique bounded solution of (1),(2) as  $x(t,h)$ . Then the continuity of the bounded solution of (1),(2) in  $h$  is proved in

**Lemma 3.** Suppose that (A2),(A5) and (A6) are satisfied. Then for any  $h_1, h_2 \in C$ ,  $h_1, h_2$  are uniformly continuous in  $(-\infty, 0]$  and  $h_1(0) = h_2(0) = 0$

$$\|x_t(\cdot, h_2) - x_t(\cdot, h_1)\| \leq \|h_2 - h_1\| v(t), \quad 0 \leq t < \infty,$$

where  $v(t)$  is the unique real bounded continuous solution of

$$(4) \quad v(t) = 1 + \int_0^t n(s) v[\omega^+(s)] ds, \quad 0 \leq t < \infty.$$

*Proof.* Denote  $u(t) = \|x_t(\cdot, h_2) - x_t(\cdot, h_1)\|$ ,  $0 \leq t < \infty$ . By (3) and (A2) it follows that

$$|x(t, h_2) - x(t, h_1)| \leq |h_2(0) - h_1(0)| + \int_0^t n(s) u[\omega^+(s)] ds, \quad 0 \leq t < \infty,$$

and hence  $u(t) \leq \|h_2 - h_1\| + \int_0^t n(s) u[\omega^+(s)] ds$ ,  $0 \leq t < \infty$ . Since  $u$  is bounded and continuous, by the generalized Gronwall lemma the result follows.

**Lemma 4.** Assume that (A2),(A5) and (A6) are satisfied. Let  $h \in C$ ,  $h(0) = 0$  and let  $h$  be uniformly continuous in  $(-\infty, 0]$ . Let  $\{z_k\}$ ,  $z_k \in E$ ,  $k = 1, 2, \dots$ , be a sequence with  $\lim_{k \rightarrow \infty} |z_k| = \infty$ . Denote  $m_k = \inf\{|x(t, h + z_k)| : 0 \leq t < \infty\}$ . Then



$$\lim_{k \rightarrow \infty} m_k = \infty.$$

Proof. It is similar to that of Lemma 3 in [8], p. 240.

By using Theorem 1 where  $g(x_0, t) = x(t, h + x_0)$  the following boundary value problem for (1) can be solved. An arbitrary point  $x_1 \in E$  and an initial function  $h \in C$ ,  $h$  is uniformly continuous in  $(-\infty, 0]$ ,  $h(0) = 0$ , are given. To find a point  $x_0 \in E$  such that

$$(5) \quad \lim_{t \rightarrow \infty} x(t, h + x_0) = x_1.$$

Theorem 3. Assume that (A2'), (A5), (A6) as well as the assumption: (A7) There exists a  $q_1$ ,  $0 \leq q_1 < 1$ , such that for the bounded continuous solution  $v(t)$  of the equation (4) the inequality  $v(t) \leq 1 + q_1$ ,  $0 \leq t < \infty$ , is true,

are satisfied. Let  $x_1 \in E$  and let  $h \in C$ ,  $h$  be uniformly continuous in  $(-\infty, 0]$ ,  $h(0) = 0$ . Then there exists exactly one  $x_0 \in E$  such that (5) is true.

Proof. Define a mapping  $g : E \rightarrow B$  in this way. Given an  $x_0 \in E$ , let  $g(x_0, t) = x(t, h + x_0)$  for  $0 \leq t < \infty$  and let  $g(x_0, \infty) = \lim_{t \rightarrow \infty} x(t, h + x_0)$ . Lemma 1 and 2 guarantee that  $g$  is well defined. By Lemma 3  $g$  is continuous and Lemma 4 implies that the condition (i) in Theorem 1 is satisfied. Clearly (iii) in that theorem holds. Let  $r > 0$ ,  $t_1 < t$ ,  $|x_2| \leq r$ . Then  $|g(x_2, t) - g(x_2, t_1)| \leq \int_{t_1}^t |f(s, 0)| ds + \int_{t_1}^t n(s) \|x_{\omega^+}(s)(\cdot, h + x_2)\| ds \leq \int_{t_1}^t |f(s, 0)| ds + \int_{t_1}^t n(s) [M_1 + (\|h\| + r)K_1] ds$ , where  $M_1 = \sup_{0 \leq s < \infty} \|x_{\omega^+}(s)(\cdot, 0)\|$ ,  $K_1 = \sup_{0 \leq s < \infty} v(\omega^+(s))$ . If  $t < t_1$ , we get a similar inequality. This implies that (iv) is satisfied.

Consider the mapping  $U = I - g(\cdot, t)$  for a fixed  $t \in [0, \infty]$ . Then by Lemma 3 and (A7)  $|U(x_0) - U(y_0)| \leq \int_0^t n(s) \|x_{\omega^+}(s) - y_{\omega^+}(s)\| ds \leq |x_0 - y_0| (v(t) - 1) \leq q_1 |x_0 - y_0|$ . Hence  $U$  is a strict contraction and thus a condensing mapping. By Theorem 1,  $g(E, t) = E$  for each  $t \in [0, \infty]$ . Since  $U$  is a strict contraction,  $|g(x_0, t) - g(y_0, t)| \geq (1 - q_1) |x_0 - y_0|$  which implies that  $g(\cdot, t)$  is a homeomorphic mapping of  $E$  onto itself.

Remarks. 1. In case  $E = R^n$ , Theorem 3 is valid without assuming (A7). Of course uniqueness of  $x_0$  need not be true.

2. Theorem 3 extends the main result from [8], p. 239,

and in the case  $\omega(t) = t$ ,  $0 \leq t < \infty$ , is stronger than Theorem I in [11], p.3.

### 3. Generalized Boundary Value Problem for Differential Systems

The generalized boundary value problem for a differential system

$$(6) \quad x' = f(t, x), \quad t \in i, \quad x \in R^n,$$

and a given continuous mapping  $T$  (not necessarily linear) of the space  $C(i, R^n)$  of all continuous  $n$ -dimensional vector functions defined in  $i$  into  $R^n$  can be defined as a problem of finding a solution  $x(t)$  of the system (6) on the interval  $i$  for which  $T(x)$  is a given vector  $r$  in  $R^n$ , i.e.

$$(7) \quad T(x) = r.$$

The topology in  $C(i, R^n)$  is given in two different cases. If  $i = [a, b]$  is a compact interval, then we consider the topology of uniform convergence, while in case  $i$  is a noncompact interval, e.g.  $i = (a, \infty)$ , then we use the topology of locally uniform convergence.

**Theorem 4.** Let  $f = f(t, x)$  be a continuous function on  $i \times R^n$  and let the equation (6) have the following properties:

(a) There is a point  $t_0 \in i$  such that for each vector  $x_0 \in R^n$  there exists a unique solution  $x(t)$  on  $i$  to the initial-value problem (6),

$$(8) \quad x(t_0) = x_0$$

and either:

(b) For each solution  $x$  of (6), (8) the following implication is true:

$$\text{If } T(x) = kx(t_0), \quad x(t_0) \neq 0, \quad \text{then } k \geq 0,$$

or:

(c) The problem (6), (7) has at most one solution for each  $r \in R^n$ . Then in the case (a), (b) a sufficient condition and in the case (a), (c) a necessary and sufficient condition that there exist at least one solution of the problem (6), (7) for each  $r \in R^n$  is that the following *compactness condition* be satisfied:

(d) If  $\{x_k\}$  is a sequence of solutions of (6) on the interval  $i$  such that  $\{T(x_k)\}$  is bounded, then there is a subsequence  $\{x_{k(1)}\}$  such that  $\{x_{k(1)}\}$  is converging in  $C(i, R^n)$ .

The proof is based on Corollary 2 and the Kamke convergence lemma.

### References

- [1] ANGELOV, V.G., BAJNOV, D.D., *On the Existence and Uniqueness of a Bounded Solution to Functional Differential Equations of Neutral Type in a Banach Space* (In Russian). Arch. Math. 2, Scripta Fac. Sci. Nat. UJEP Brunensis XVII: 65-72 (1981).

- [ 2] DEIMLING, K., *Nichtlineare Gleichungen und Abbildungsgrade*, Springer-Verlag, Berlin 1974.
- [ 3] HALE, J. K., *Theory of Functional Differential Equations*, Appl. Math. Sci., Vol. 3, Springer-Verlag, New York 1977.
- [ 4] HALE, J. K., *Retarded Equations With Infinite Delays*, Lecture Notes in Mathematics, Vol. 730, Springer-Verlag, Berlin, 157-193 (1979).
- [ 5] HARTMAN, Ph., *Ordinary Differential Equations*, John Wiley, New York 1964.
- [ 6] NUSSBAUM, R. D., *Degree Theory for Local Condensing Maps*, J. Math. Anal. Appl. 37, 741-766 (1972).
- [ 7] OPIAL, Z., *Linear Problems for Systems of Nonlinear Differential Equations*, J. Differential Equations 3, 580-594 (1967).
- [ 8] SMÍTALOVÁ, K., *On a Problem Concerning a Functional Differential Equation*, Math. Slovaca 30, 239-242 (1980).
- [ 9] ŠEDA, V., *Functional Differential Equations With Deviating Argument* (Preprint).
- [ 10] ŠEDA, V., *On Surjectivity of an Operator* (Preprint).
- [ 11] ŠVEC, M., *Some Properties of Functional Differential Equations*, Bolletino U.M.I. (4) 11, Suppl. Fasc. 3, 467-477 (1975).
- [ 12] WEBB, G. F., *Accretive Operators and Existence for Nonlinear Functional Differential Equations*, J. Differential Equations 14, 57-69 (1973).