

Life and work of Vojtěch Jarník

Bernhard Korte; Jaroslav Nešetřil

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VOJTĚCH JARNÍK'S WORK IN COMBINATORIAL OPTIMIZATION

BERNHARD KORTE and JAROSLAV NEŠETŘIL

Abstract. We discuss two papers of Vojtěch Jarník from 1930 and 1934 which are devoted to the Minimal Spanning Tree Problem and the Euclidean Steiner Tree Problem. These papers are historical milestones in combinatorial optimization.

INTRODUCTION

Jarník's status as one of the foremost mathematicians of his time is documented in this volume in many places. With respect to his lasting achievements in number theory and analysis the aim of this note may seem to be very modest: we want to discuss two lesser known papers [J], [JK] which belong to a different area from the major part of Jarník's oeuvre, namely to the area which much later became known as combinatorial or discrete optimization. These are the only papers by Jarník related to such problems and in fact the only papers which do not belong to the main line of his work (i.e. number theory, analysis and its foundations). Perhaps this would only be enough to justify a shorter note. But there is much more here than meets the eye. Papers [J], [JK] were overlooked for a long time, and, as we shall demonstrate, they are even now little known. But they are important and, as we wish to demonstrate, Jarník deserves much more credit for these truly pioneering works. In both of these papers Jarník was lucky to have dealt with problems which have since proved to be cornerstone pieces of Combinatorial Optimization developed in full in the fifties and sixties in the context of Linear Programming and Computer Science.

We thank Dr. R. von Randow for his help with the preparation of this paper.

1. ON A MINIMAL PROBLEM

Jarník's paper [J] is a very short one and we can include a translation of most of it (the original two pages are given in Figs. 1 and 2).

One should see the original and look at a translation of [J]. The problem is stated and treated with a rigour and clarity which is missing in many later additions to this area. So we consider this as a good opportunity to present parts of Jarník's paper in full (we include a translation of about two thirds of [J]). We found no mistakes or even misprints in [J]! The paper [J] has also an interesting form: it is written in the "first person"-form and the reason for this is explained by its subtitle. We have tried to preserve Jarník's style as closely as possible. In particular, all symbols and notations are preserved. While a longer discussion will follow, we have included a few comments within the translation (we use square brackets [] for these; the translation itself is in italics).

PRÁCE
MORAVSKÉ PŘÍRODOVĚDECKÉ SPOLEČNOSTI
 SVAZEK VI., SPIS 4. 1930 SIGNATURA: F 50
 BRNO, ČESKOSLOVENSKO.
 ACTA SOCIETATIS SCIENTIARUM NATURALIUM MORAVICAE
 TOMUS VI., FASCICULUS 4. SIGNATURA: F 50 BRNO, CZECHOSLOVACIA: 1930

VOJTECH JARNÍK:

O jistém problému minimálním.

(Z dopisu panu O. BORŮVKOVI.)

Zajímavou otázku, kterou jste řešil ve své práci »O jistém problému minimálním« (Práce moravské přírodovědecké společnosti, svazek III., spis 3), lze řešiti ještě jiným a — jak se mi zdá — jednodušším způsobem.

Dovolili si sdělití Vám v následujícím své řešení. Budíž dáno $n \geq 2$ prvků, jež označím čísly $1, 2, \dots, n$. Z těchto prvků sestojím $\downarrow n(n-1)$ dvojici $\{i, k\}$, kdež $1 \leq i, k; i, k = 1, 2, \dots, n$; dvojici $\{i, k\}$ považují za totožnou s $\{k, i\}$. Každé dvojici $\{i, k\}$ budíž přiřazeno číslo kladné $r_{i,k}$ ($r_{i,k} = r_{k,i}$). Tato čísla $r_{i,k}$ ($1 \leq i < k \leq n$) v počtu $\downarrow n(n-1)$ budíž navzájem různá.

Množství všech dvojic $\{i, k\}$ označme M. Jsou-li p, q dvě přirozená čísla $\leq n, p \neq q$, nazvu každou skupinu dvojic z M tvaru (1) $\{p, c_1\}, \{c_1, c_2\}, \{c_2, c_3\}, \dots, \{c_{p-1}, c_p\}, \{c_p, q\}$ řetězcem (p, q). Také jednou dvojici $\{p, q\}$ nazývám řetězcem (p, q).

Částečné množství H z množství M nazvu kompletní částí (značka kč), jestliže ke každé dvojici přirozených čísel p, q , jež jsou $\leq n$ a od sebe různá, existuje v H řetězec (p, q) (t. j. řetězec tvaru (1), jehož všechny dvojice patří k H). Existují kč; neboť M samo je kč.

Je-li (2) $\{i_1, k_1\}, \{i_2, k_2\}, \dots, \{i_r, k_r\}$ nějaké částečné množství K z množství M,¹⁾ označme

$$\sum_{j=1}^r r_{i_j, k_j} = R(K).$$

¹⁾ V (2) necht je každá dvojice z K napsána jen jednou.

Figure 1

60 VOJTECH JARNÍK:

Zavedeme nyní jisté částečné množství J z množství M takto:
 Definice množství J. Jest

$$J = \{a_1, a_2\}, \{a_2, a_3\}, \dots, \{a_{2k-2}, a_{2k-1}\},$$

kde a_1, a_2, \dots jsou definovány takto:
 1. krok. Za a_1 zvolíme kterýkoliv z prvků $1, 2, \dots, n$; a_2 budíž definováno vztahem

$$r_{a_1, a_2} = \min_{1 \neq a_1} r_{a_1, 1} \quad (1 \neq a_1, 2, \dots, n).$$

k-tý krok. Je-li již definováno (5) $a_1, a_2, a_3, \dots, a_{2k-2}, a_{2k-1}$ ($2 \leq k < n$), definujeme a_{2k-1}, a_{2k} vztahem

$$r_{a_{2k-1}, a_{2k}} = \min_{1 \neq a_{2k-1}} r_{a_{2k-1}, 1}$$

kde i probíhá všechna čísla $a_1, a_2, \dots, a_{2k-2}$; i všechna ostatní z čísel $1, 2, \dots, n$. Při tom budíž a_{2k-1} jedno z čísel (5), takže a_{2k} není obsaženo mezi čísly (5).

Je patrné, že při tomto postupu je mezi čísly (5) právě k čísel různých, takže pro $k < n$ lze k-tý krok provést.

- Řešení naší úlohy je nyní dáno tímto tvrzením:
 1. J jest mkč.
 2. Neexistuje žádná jiná mkč.
 3. J se skládá z $n-1$ dvojic.

Důkaz provedu indukcí. Tvrzení 3. je patrné správné.
 1. Podle první pomocné věty musí každá mkč obsahovati množství

$$J_0 = \{a_1, a_2\}.$$

Množství J_0 jest souvislé a má právě dva indexy.

2. Budíž pro jisté celé k ($2 \leq k < n$) již dokázáno, že množství

$$J_k = \{a_1, a_2\}, \{a_2, a_3\}, \dots, \{a_{2k-2}, a_{2k-1}\}$$

je souvislé část s k indexy, jež jest obsažena v každé mkč. Potom podle 2. pomocné věty je také množství

$$J_{k+1} = \{a_1, a_2\}, \{a_2, a_3\}, \dots, \{a_{2k-1}, a_{2k}\}$$

obsaženo v každé mkč a má patrně k+1 indexů (neboť a_{2k-1} patří k indexům množství J_k , a_{2k} nikoliv). Dále jest J_{k+1} souvislé část; neboť buďte p, q dva různé indexy množství J_{k+1} :

Figure 2

Vojtěch Jarník
On a certain minimal problem
 (From a letter to O. Borůvka)

In your article “On a certain minimal problem” (which appeared in “Práce moravské přírodovědecké společnosti,” vol. III, No. 3) you solved an interesting problem. It seems to me that there is a simpler solution of this problem. Allow me to state my solution here.

[Thus Jarník decided to use the same title for his paper as Borůvka [B1]. Borůvka was the first to solve the Minimal Spanning Tree problem, see [GH] and comments below.]

Let n elements be given, I denote them as numbers $1, 2, \dots, n$. From these elements I form $\frac{1}{2}n(n-1)$ pairs $[i, k]$ where $i \neq k$, $i, k = 1, 2, \dots, n$. I consider the pair $[k, i]$ identical with the pair $[i, k]$. To every pair $[i, k]$ let there be associated a positive number $r_{i,k}$ ($r_{i,k} = r_{k,i}$). Let these numbers $r_{i,k}$ ($1 \leq i < k \leq n$) be pairwise different.

[It is interesting to note that Jarník denotes the unordered pair by $[i, k]$, which is standard usage in graph theory today. This is also a departure from Borůvka's paper [B1] where the numbers $r_{i,k}$ are denoted by $[i, k]$. The fact that the numbers $r_{i,k}$ —i.e. in later terminology weights of edges—are supposed to be distinct is neither discussed nor justified. It seems that both Borůvka and Jarník were aware—as classical mathematicians—of “perturbation arguments.” Certainly applications that they clearly had in mind suggest this, see [B3], [B4] and the discussion of the concluding remarks of Jarník's paper below.]

We denote by M the set of all pairs $[i, k]$. For two distinct natural numbers $p, q \leq n$, I call a chain (p, q) any set of pairs from M of the following form:

$$(1) \quad [p, c_1], [c_1, c_2], \dots, [c_{s-1}, c_s], [c_s, q].$$

Also, a single pair $[p, q]$ I call a chain (p, q) .

[Even today the terminology is not unique—a set of the form (1) is called a path, trail, walk; Jarník considers (1) as a family—repetitions are allowed.]

*A subset H of M I call a complete subset (*kč* in short), if for any pair of distinct natural numbers $p, q \leq n$ there exists a chain (p, q) in H (i.e. a chain of form (1) all of whose pairs belong to H). There are *kč*; M itself is a *kč*.*

[Jarník's lucid Czech mathematical style became famous and standard; he may well be a bit playful here: *kč* is close to *Kč*—an abbreviation of Czech currency (“*koruna česká*”).]

If

$$(2) \quad [i_1, k_1], [i_2, k_2], \dots, [i_t, k_t]$$

is a subset K of M , we put

$$\sum_{j=1}^t r_{i_j, k_j} = R(K).$$

If for a complete set K the value $R(K)$ is smaller than or equal to the values for all other complete sets, then I call K a minimal complete set in M (symbolically $mk\check{c}$). As there exists at least one $k\check{c}$ and there are only finitely many $k\check{c}$, there exists at least one $mk\check{c}$. The problem, which you [i.e. O. Borůvka] solved in your paper, can be formulated as follows:

Problem. Prove that there exists a unique $mk\check{c}$ and give a formula [i.e. an algorithm] for its construction.

[Of course $mk\check{c}$ is the unique minimum spanning tree. There is no mention of trees in this paper.]

First Lemma. Let a_1 be a natural number $\leq n$ with

$$(3) \quad r_{a_1, a_2} = \min \{r_{a_1, k}; k = 1, 2, \dots, n, k \neq a_1\}.$$

Then every $mk\check{c}$ contains a pair $[a_1, a_2]$.

[Summary of proof: The First Lemma is proved by a textbook argument: if K is a $k\check{c}$ not containing $[a_1, a_2]$, then consider a chain $(a_1, a_2) = [a_1, c_1], [c_1, c_2], \dots, [c_t, a_2]$ and form a new set K' by removing $[a_1, c_1]$ from K while adding $[a, a_2]$. Then K' is again a $k\check{c}$ and $R(K') < R(K)$.]

We introduce the following: Let $K \equiv [i_1, k_1], [i_2, k_2], \dots, [i_t, k_t]$ be a subset of M . An index of K I call any natural number from among $i_1, k_1, i_2, k_2, \dots, i_t, k_t$. A subset K of M I call a connected subset if for any two distinct indices p, q of K it is possible to find in K a chain (p, q) (i.e. a chain (p, q) consisting of pairs from K only).

2. Lemma. Let S be a connected subset; let h_1, h_2, \dots, h_s be all the indices of S ; let $s < n$.

Let l_1, l_2, \dots, l_t be numbers from $1, 2, \dots, n$ which fail to be indices of S , let

$$(4) \quad r_{a, b} = \min \{r_{h_i, l_j}; i = 1, 2, \dots, s, j = 1, 2, \dots, t\}.$$

Then I claim: every $mk\check{c}$ containing S contains $[a, b]$ as well.

[We do not translate the proof but just summarize it. The Second Lemma is proved again by a textbook argument: let K be a $k\check{c}$ containing S and not containing $[a, b]$. Let a be

an index of S . Then there exists in K a chain $(a, b) = [c_0, c_1], [c_1, c_2], \dots, [c_v, c_{v+1}]$ with $c_0 = a, c_{v+1} = b, v \geq 1$. Let c_w be the last of the numbers c_0, c_1, \dots, c_v which is an index of S . Then define subset K' by removing $[c_w, c_{w+1}]$ and adding $[a, b]$. K' is again $k\check{c}$. Here Jarník considers two cases: $c_w = a$ and $c_w \neq a$. But $R(K') < R(K)$ and thus K fails to be $mk\check{c}$.

Jarník does not mention that Lemma 1 is a special case of Lemma 2. Indeed, in his setting Lemma 1 is not a special case of Lemma 2 as a single vertex does not correspond to the index set of any $k\check{c}$.]

Let us now introduce a certain subset J of M [J for Jarník?] as follows:

Definition of set J . $J \equiv [a_1, a_2], [a_3, a_4], \dots, [a_{2n-3}, a_{2n-2}]$ where a_1, a_2, \dots are defined as follows:

First Step. Choose as a_1 any of the elements $1, 2, \dots, n$. Let a_2 be defined by the relation $r_{a_1, a_2} = \min r_{a_1, l}$ ($l = 1, 2, \dots, n; l \neq a_1$).

k -th Step. Having defined

$$(5) \quad a_1, a_2, a_3, \dots, a_{2k-3}, a_{2k-2} \quad (2 \leq k < n)$$

we define a_{2k-1}, a_{2k} by $r_{a_{2k-1}, a_{2k}} = \min r_{i, j}$ where i ranges over all the numbers $a_1, a_2, \dots, a_{2k-2}$ and j ranges over all the remaining numbers from $1, 2, \dots, n$. Moreover, let a_{2k-1} be one of the numbers in (5) such that a_{2k} is not among the numbers in (5). It is evident that in this procedure exactly k of the numbers in (5) are different, so that for $k < n$ the k -th step can be performed.

The solution to our problem is then provided by the following

Proposition.

1. J is $mk\check{c}$.
2. There is no other $mk\check{c}$.
3. J consists of exactly $n - 1$ pairs.

[Summary of Proof: Proof is by induction on n . Jarník defines $J_2 \equiv [a_1, a_2]$ by the First Lemma. Given a connected set J_k with k indices Jarník uses the Second Lemma to define J_{k+1} . He proves carefully that J_{k+1} is connected. He then puts $J = J_n$.]

Remark. *The following is a visual interpretation of the solved problem: We are given n balls numbered $1, 2, \dots, n$ which are joined pairwise by $\frac{1}{2}n(n - 1)$ sticks. Let $r_{a, b}$ be the mass of the stick joining balls a and b . Let the sticks be bent if necessary so that they do not touch. From this system we want to remove some of the sticks so that the n balls hold together and the mass of the remaining sticks is as small as possible.*

In Prague, Feb. 12, 1929.

[It is interesting to note how tempting it was for both Borůvka and Jarník to formulate an application of the problem. Borůvka was led to the problem by his friends from the Electric Power Company of Western Moravia in Brno, cf. [B3], and indeed published a note in an electrotechnical journal [B2]. Jarník added a geometric interpretation—in \mathbb{R}_3 .]

2. JARNÍK'S PAPER IN A HISTORICAL PERSPECTIVE

A noncombinatorialist may wonder why we have discussed Jarník's paper [J] in such detail, and why it is worth translating. The reason is very simple as the following problem is perhaps the central problem of combinatorial optimization and a cradle of many key notions:

Minimal spanning tree (MST). *Given a set V and a weight function $w: \binom{V}{2} \rightarrow \mathbb{R}$, find a tree (V, E) such that $\sum_{e \in E} w(e)$ is minimal.*

MST was first solved by Borůvka [B1]. Jarník quickly realized the novelty of this problem and immediately contributed his elegant solution [J]. Borůvka never returned to this problem although he lectured about his solution in Paris [B3]. Also other early contributions were illustrious: by G. Choquet [CH], by K. Florek, J. Lukaszewicz, J. Perkal, H. Steinhaus, S. Zubrzycki [FLPSZ]. And after 1955 progress has been very fast and a number of general procedures and special algorithms were formulated. A rich spectrum of these results and a history of the problem is described in great detail and accuracy by R. L. Graham and P. Hell [GH]. Let us just note that O. Borůvka is quoted by both the standard early references: J. Kruskal [K] and R. C. Prim [P]. Vojtěch Jarník's article only began to be quoted later, see e.g. K. Čulík, V. Doležal, M. Fiedler [CDF], despite the fact that his treatment was very precise (like all his mathematical work) and modern. That should be clear from the above translation. His algorithm is identical with the Prim algorithm [P] and his argument is a standard proving argument even now after 65 years. Perhaps it is time to do justice to this elegant procedure and call it the Jarník-Prim algorithm. Jarník returned to this topic only once more in his second paper [JK], which we will discuss below. We believe that the geometrical interpretation given in the final lines of [J] provided his definitely non-planar motivation for [JK].

3. ON MINIMAL GRAPHS CONTAINING n GIVEN POINTS

We proceed as in section 1: First we provide a translation of the key parts of the Jarník-Kössler paper [JK]. We have decided (mainly because of space limitations), to translate only the first two sections of the Jarník-Kössler paper. They are devoted to general properties of "Steiner trees." It appears that virtually all general properties of Steiner trees have already been explicitly stated in [JK]. Even today they are attributed to others and even today one can find in [JK] arguments superior to those in common use (such as the local planarity of k -dimensional Steiner trees; cf. Theorem 3(c) of [JK] and p. 77 of [HRW]). We hope to return to this paper in the near future and give a critical version of the whole paper [JK]. We give a brief discussion below of the context and later development. Let us note that what follows may be the first translation of the essential parts of [JK]. However, such a translation is badly needed. Even the recent papers and books (such as [HRW]) are not aware of what a rich source of ideas is provided by [JK]. Some of the main misquotations will be discussed below.

[JK] is a paper with 13 pages, numbered 223–235. We include a translation of p. 223–229. The first and third pages are reproduced in Figs. 3, 4.

ČASOPIS PRO PĚSTOVÁNÍ MATEMATIKY A FYSIKY

ČÁST MATEMATICKÁ

O minimálních grafech, obsahujících n daných bodů.

Vojtěch Jarník a Miloš Kössler.
(Doloženo 10. února 1934.)

V tomto článku zabýváme se touto úlohou: je dáno n bodů C_1, C_2, \dots, C_n ; hledáme souvislé množství, složené z konečného počtu úseček a obsahující body C_1, C_2, \dots, C_n tak, aby „celková délka“ tohoto množství byla co nejmenší (pro $n = 2$ jest ovšem touto „nejkratší spojnicí“ úsečka, spojující body C_1, C_2). V § 2 dokazujeme existenci takového „minimálního grafu“, v § 3 zabýváme se případem, kdy body C_1, C_2, \dots, C_n tvoří vrcholy pravidelného n -úhelníka.

Charakter tohoto článku je zcela elementární; mimo to některé body důkazu jsou zcela běžné úvahy a proto je provádíme stručně.

§ 1.

Budíž R_k ($k \geq 1$) k -rozměrný euklidovský prostor. Neprázdné bodové množství $G \subset R_k$ nazveme grafem v R_k , má-li tyto vlastnosti: 1. G je souvislé; 2. buď se G skládá z jediného bodu nebo je G soustem konečného počtu uzavřených úseček.¹⁾ Je-li $P \in G$ a existuje-li právě n (nikoliv však $n + 1$) úseček, ležících v grafu G , majících P za bod koncový, z nichž žádná dvě nemají kromě bodu P společných bodů, budeme říkati, že P je bodem n -tého řádu grafu G .²⁾

¹⁾ Označení: $A \subset B$ značí: A je část množství B ; $A \in B$ značí: A je prvkem množství B ; A, B je prvkem množství A, B . Znakem \overline{MN} značíme uzavřenou úsečku (t. j. včetně koncových bodů) o koncových bodech M, N ; \overline{MN} značí polopřímku s koncovým bodem M , její obsahující bod N (včetně bodu M). Znak $\langle \overline{MN} \rangle$, $\langle \overline{MN} \rangle_0$, $\langle \overline{MN} \rangle_1$ značí množství všech bodů úsečky \overline{MN} s výjimkou bodu M , resp. bodu N , resp. obou bodů M, N a pod. Úhel α dvou úseček $\overline{PM}, \overline{PN}$, majících jediný společný bod P , berte me vždy v intervalu $0 < \alpha \leq \pi$. Znak \overline{MN} bude někdy značiti též orientovanou úsečku (začáteční bod M , koncový N); někdy bude \overline{MN} značiti též délku této úsečky; nedorozumění není třeba se obávat.

²⁾ V grafu G existuje bod nulového řádu tehdy a jen tehdy, je-li G jednobodový graf.

Časopis pro pěstování matematiky a fyziky, Ročník 34. 16

Figure 3

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V této posloupnosti lze konečně — jestli posloupnosti $X_1^i, X_2^i, X_3^i, \dots$ ($i = 1, 2, \dots, z$) jsou ohraničené — nalézt částečně posloupnost G^i, G^2, \dots tak, že existují limity $\lim_{p \rightarrow \infty} X_i^p = X_i$ ($i = 1, 2, \dots, z$).

Označme znakem G_i součet oněch úseček $\overline{X_i X_j}$ ($1 \leq i < j \leq z$), pro něž $a_i = 1$.) Zřejmé jest $G_i \in \mathbb{R}^k$ a platí

$$l(G_i) = \sum_{1 \leq i < j \leq z} a_i \overline{X_i X_j} \overline{X_i X_j},$$

$$l(G_i) \leq \sum_{1 \leq i < j \leq z} a_i \overline{X_i X_j} = \lim_{p \rightarrow \infty} l(G_i^p) = d_i,$$

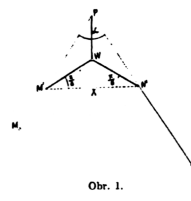
jak bylo dokázáno.

Důkaz tvrzení 4. Budíž $G \in \mathbb{R}^k$ graf takový, že neplatí $G \subset K$. Potom existuje nadrovina S ($[k-1]$ -rozměrná) taková, že všechny body základní leží po jedné straně nadroviny S a po druhé straně této nadroviny leží jistě neprázdná část G' grafu G . Sestrojíme graf G_1 tím, že v grafu G nahradíme část G' pravouhlou projekcí množství G' na nadrovinu S ; zřejmě je $G_1 \in \mathbb{R}^k$ a $l(G_1) < l(G)$, jak bylo dokázáno.

Nyní snadno dokážeme následující větu 3, která podrobněji popisuje strukturu minimálních grafů.

Věta 3. Budíž G minimální graf v R_k ($k \geq 1$) vzhledem k bodům C_1, C_2, \dots, C_n ($n \geq 2$). Potom má G tyto vlastnosti:

- G je řádů nejmenšího konvexního množství, obsahujícího body C_1, C_2, \dots, C_n .
- G je strom, nemající ani volných konců ani volných rohů.
- Mají-li dvě strany grafu G společný bod, jsou úhel těchto stran nejmenší rovno $\frac{\pi}{3}$.
- Každý rozvětvení bod grafu G je třetího řádu. Tyto strany vlastnosti b) můžeme předpokládati (následkem vlastnosti a), že $k \geq 3$ (kdyby bylo $k < 3$, vnořili bychom R_k do prostoru R_3); potom však vlastnost b) plyne z tvrzení 1 a 2. Vlastnost c) dokážeme takto: budíž $G \in \mathbb{R}^k$ a buďte $\overline{PM}, \overline{PN}$ dvě strany



Obr. 1.

Figure 4

¹⁾ Některé z těchto „úseček“ ovšem mohou degenerovat v body.

On minimal graphs containing n given points

Vojtěch Jarník and Miloš Kössler

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In this paper we consider the following problem: given n points C_1, C_2, \dots, C_n , we want to find a connected set consisting of finitely many segments, which contains the points C_1, C_2, \dots, C_n , so that “the total length” of this set is the least possible (of course for $n = 2$ such a “shortest connection” is a line segment joining points C_1 and C_2). In §2 we prove the existence of such a “minimal graph,” and in §3 we consider the case when the points C_1, C_2, \dots, C_n form the vertices of a regular n -gon.

The nature of this article is completely elementary. Also some of the steps in the proof are routinely known and thus we are brief there.

[The reader should bear in mind that this paper was published before e.g. König’s book [Ko] and no references are given.]

§1.

Let \mathbb{R}_k ($k \geq 1$) be the k -dimensional Euclidean space.

[So already this first line violates the common belief that, while Jarník-Kössler pioneered the Euclidean Steiner problem for the plane, the k -dimensional case was considered only by Gilbert and Pollack in [GP]. In fact the whole paper [JK] is written for k dimensions.]

A nonempty point set $G \subseteq \mathbb{R}_k$ is called a graph in \mathbb{R}_k if it has the following properties:

1. *G is connected,*
2. *either G contains one point only or G is a sum of finitely many closed segments.*

[From now on we use the word union instead of sum. Now a footnote follows where Jarník in his characteristic style clearly defines all used symbols starting with $A \in B$ and ending with ${}_0(\overline{MN})$, $(\overline{MN})_0$, ${}_0(\overline{MN})_0$ for half-open and open line segments; \overline{MN} denotes a line segment, an oriented line segment or the length of this segment; “one need not be afraid of a misunderstanding.”]

If $P \in G$ and there exist exactly n (and not $n + 1$) segments of G for which P is an end-vertex and which do not have common points except for P , then we say that P is a point of n -th order [or degree] of G . The points of order one are called endpoints, points of higher order are called branching points (in every graph there are finitely many of both types of points). If P is a point of n -th order in G , then we put $V(P) = n - 2$, and we further put $V(G) = \sum V(P)$. $V(P)$ is called the weight of point P .

A cycle is a graph which is a closed, simple, continuous curve. A graph, no part of which is a cycle, is called a tree. Now the following well-known theorem holds:

Theorem 1. *If G is a tree, then $V(G) = -2$.*

[A note is added, stating that any tree with at least 2 points has at least 2 end-vertices. A typical proof by induction on the number of vertices is given. The authors take care in defining vertices of G .]

§2.

Let n ($n \geq 2$) points C_1, C_2, \dots, C_n in the space \mathbb{R}_k ($k \geq 1$) be given. These points are called basic points. Let G be a graph in \mathbb{R}_k containing points C_1, C_2, \dots, C_n .

[Recall that a graph is defined as a topological realization of a "graph" and that it is always connected.]

By a "vertex of graph G " we shall understand:

1. basic points
2. all points of G of order > 2
3. all points of G of order 2 in which two noncollinear line segments meet.

A segment $\overline{MN} \subset G$ is called a "side of graph G " [i.e. an edge] if ${}_0\overline{MN}_0$ does not contain a vertex and both M and N are vertices. The graph G is then the union of its sides. Obviously there are only finitely many vertices and sides in a graph; if two sides have a common point, then this point is the endpoint of both sides. The sum of all side-lengths is called the length of G and denoted $l(G)$.

Let \mathcal{M} denote the set of all graphs in \mathbb{R}_k containing C_1, \dots, C_n . In what follows let us fix a lower bound d for all graph lengths in \mathcal{M} . If $l(G) = d$, then G is called a "minimal graph in \mathbb{R}_k with respect to the points C_1, \dots, C_n ". First we prove

Theorem 2. *Let C_1, C_2, \dots, C_n be points of \mathbb{R}_k ($k \geq 1, n \geq 2$). Then there exists at least one minimal graph in \mathbb{R}_k with respect to the points C_1, C_2, \dots, C_n .*

We first introduce some notation. Let $G \in \mathcal{M}$. A free end of G is an endpoint of G which is not a basic point. A free corner of G is a vertex of order 2 which is not a basic point. Let \mathcal{N} be the set of all $G \in \mathcal{M}$ which are trees and which have no free ends. Let \mathcal{P} be the set of all $G \in \mathcal{N}$ which have no free corners. First we prove the following statements:

Proposition 1. Let $G \in \mathcal{M} - \mathcal{N}$. Then there exists $G_1 \in \mathcal{N}$ such that $l(G_1) < l(G)$.

Proposition 2. Let $k \geq 3$ and $G \in \mathcal{N} - \mathcal{P}$. Then there exists $G_1 \in \mathcal{P}$ such that $l(G_1) < l(G)$.

Proposition 3. Let d_1 be a lower bound for all lengths of graphs $G \in \mathcal{P}$. Then there exists at least one graph $G_\circ \in \mathcal{M}$ with $l(G_\circ) \leq d_1$.

Proposition 4. If G is a minimal graph in \mathbb{R}_k with respect to the points C_1, C_2, \dots, C_n , and if K is the smallest convex set in \mathbb{R}_k containing C_1, C_2, \dots, C_n , then $G \subset K$ [i.e. the convex hull contains all the Steiner points].

Theorem 2 follows from Propositions 1–4 as follows:

- A) If $k \geq 3$, then Propositions 1 and 2 yield $d_1 = d$ and Theorem 2 follows from Proposition 3.
- B) If $k \leq 2$, then we embed \mathbb{R}_k in \mathbb{R}_3 . From A) we get a minimal graph G in \mathbb{R}_3 with respect to the points C_1, C_2, \dots, C_n . But Proposition 4 implies $G \subset \mathbb{R}_k$.

Thus it suffices to prove Propositions 1–4.

[Note again that for Jarník the k -dimensional case is essential.]

Proof of Proposition 1 is by deleting endpoints together with the corresponding sides. The proofs of the remaining Propositions are elegant and more interesting, and we outline the Jarník-Kössler arguments in a greater detail:

Proof of Proposition 2. Let $k \geq 3$ and $G \in \mathcal{N} - \mathcal{P}$, i.e. $G \in \mathcal{M}$ is a tree without free ends containing at least one free corner M_1 in which two non-collinear sides $\overline{M_1M_2}$ and $\overline{M_1M_3}$ meet. M_1 is not a basic point. We prove: there exists a graph $G' \in \mathcal{N}$ with less free corners satisfying $l(G') < l(G)$.

[It now follows that by repeating this argument one obtains Proposition 2.]

We shall distinguish two cases:

CASE 1. Both M_2 and M_3 are basic points. Then the set $G - [{}_0(\overline{M_2M_1}) + (\overline{M_1M_3})_0]$ is the union of two disjoint trees G_2, G_3 , $M_2 \in G_2$, $M_3 \in G_3$. The segment $\overline{M_2M_3}$ contains at least one point of G_2 (e.g. M_2) and at least one point of G_3 (e.g. M_3). Thus let P_2, P_3 be points of the segment $\overline{M_2M_3}$ such that $P_2 \in G_2$, $P_3 \in G_3$ and no point of the segment ${}_0(\overline{P_2P_3})_0$ belongs to either G_2 or G_3 . Then the graph $G' = \{G - [{}_0(\overline{M_2M_1}) + (\overline{M_1M_3})_0] + \overline{P_2P_3}$ is in \mathcal{N} and has less free corners than G .

[This is justified in detail.]

Obviously $l(G') < l(G)$.

CASE 2. One of the points M_2, M_3 —say M_2 —is not a basic point. Let S be a $[(k - 1)$ -dimensional] hyperplane containing M_2 but not M_3 . If M'_2 is any point of S , then we denote by $G(M'_2)$ the graph obtained from G by replacing all sides $\overline{M_i M_2}$ of G by segments $\overline{M_i M'_2}$. Put $\overline{M_2 M_1} + \overline{M_1 M_3} - \overline{M_2 M_3} = a > 0$. It is clear that there exists $\delta > 0$ such that every graph $G(M'_2)$ for which $\overline{M_2 M'_2} < \delta$ satisfies:

1. $l(G(M'_2)) < l(G) + \frac{1}{2}a, \overline{M'_2 M_1} + \overline{M_1 M_3} - \overline{M'_2 M_3} > \frac{1}{2}a,$
2. the graph $G(M'_2)$ has the same vertices (of the same order) and the same sides as G with the exception that instead of the vertex M_2 and sides $\overline{M_2 M_i}$ we have M'_2 and $\overline{M'_2 M_i}$.

[This may be seen as follows:]

Let us consider all lines through M_3 and some other point of G . These lines intersect S in a set Σ which consists of finitely many points, segments and half-lines. As $k \geq 3$ [and thus S is at least 2-dimensional] there exists at least one $M'_2 \in S - \Sigma$ such that $\overline{M_2 M'_2} < \delta$. This graph then has properties 1 and 2. Moreover, the graph $G(M'_2)$ has the following property: no point of $G(M'_2)$ belongs to the segment ${}_0\overline{M'_2 M_3}{}_0$.

[This is justified in a detailed footnote.]

Now define graph $G' = \{G(M'_2) - [\overline{M'_2 M_1} + \overline{M_1 M_3}]\} + \overline{M'_2 M_3}$. Clearly $G' \in \mathcal{N}$, G' has less free corners than G , and finally from Condition 1 it follows that $l(G') < l(G)$.

PROOF OF PROPOSITION 3. This is a routine limit argument. Let G_1, G_2, \dots be a sequence of graphs from \mathcal{P} and let $\lim_{r \rightarrow \infty} l(G_r) = d_1$.

[We preserve as before all the notation of the paper [JK].]

As $C_1 \in G_r$, all graphs G_r lie in a closed ball with centre C_1 and diameter equal to the upper bound of the numbers $l(G_r)$ ($r = 1, 2, \dots$). All vertices of the graph G_r are basic or branching points. By Theorem 1 it follows that $V(G_r) = -2$. As all the endpoints (with weight -1) are basic points, we have at most n of them. Thus the number of branching points (with weight at least 1) is at most $n - 2$ and the graph G_r has at most $2n - 2$ points. Hence there exists a subsequence G'_1, G'_2, \dots of G_1, G_2, \dots such that all G'_r have the same number of vertices. We denote the vertices of G'_r by $X_1^r, X_2^r, \dots, X_z^r$ such that $X_i^r = C_i$ for $1 \leq i \leq n$. For

graph G'_r define the matrix

$$\begin{pmatrix} 0 & a_{12}^r & a_{13}^r & \dots & a_{1z}^r \\ a_{21}^r & 0 & a_{23}^r & \dots & a_{2z}^r \\ a_{31}^r & a_{32}^r & 0 & \dots & a_{3z}^r \\ \dots & \dots & \dots & \dots & \dots \\ a_{z1}^r & a_{z2}^r & a_{z3}^r & \dots & 0 \end{pmatrix}$$

where $a_{il}^r = 1$ or 0 according to whether or not $\overline{X_i^r X_l^r}$ is a side of the graph G'_r .

[So this is the adjacency matrix of G'_r .]

As there are only finitely many such matrices, there is a subsequence $G'_{s_1}, G'_{s_2}, \dots$ such that the same matrix

$$\begin{pmatrix} 0 & a_{12} & a_{13} & \dots & a_{1z} \\ a_{21} & 0 & a_{23} & \dots & a_{2z} \\ \dots & \dots & \dots & \dots & \dots \\ a_{z1} & a_{z2} & a_{z3} & \dots & 0 \end{pmatrix}$$

corresponds to every graph of the subsequence. Finally, as the sequences $X_i^1, X_i^2, X_i^3, \dots$ ($i = 1, 2, \dots, z$) are bounded, we can find a subsequence $G'_{t_1}, G'_{t_2}, \dots$ such that all the limits $\lim_{p \rightarrow \infty} X_i^{t_p} = X_i$ ($i = 1, 2, \dots, z$) exist. Let G_0 denote the union of segments $\overline{X_i X_l}$ ($1 \leq i < l \leq 2$) for which $a_{il} = 1$.

[Footnote: Of course some of these segments may degenerate to points.]

Obviously $G_0 \in \mathcal{M}$ and the following holds:

$$l(G'_{t_p}) = \sum_{1 \leq i < l \leq z} a_{il} \overline{X_i^{t_p} X_l^{t_p}},$$

$$l(G_0) \leq \sum_{1 \leq i < l \leq z} a_{il} \overline{X_i X_l} = \lim_{p \rightarrow \infty} l(G'_{t_p}) = d_1.$$

This completes the proof.

[This is a word for word, symbol-preserving translation. And even today the most elegant argument!]

Proof of Proposition 4. Let $G \in \mathcal{M}$ be a graph which violates $G \subset K$. Then there exists a hyperplane S [$(k - 1)$ -dimensional] such that all basic points lie on one side of S and a nonempty subset G' of G lies on the other side of S . Define a graph G_1 by replacing the subset G' by an orthogonal projection of G' onto the hyperplane S . Obviously $G_1 \in \mathcal{M}$ and $l(G_1) < l(G)$, which completes the proof.

[k dimensions are essential again.]

Now we can easily prove Theorem 3 which describes the structure of minimal graphs in a greater detail.

Theorem 3. Let G be a minimal graph in \mathbb{R}_k ($k \geq 1$) with respect to points C_1, C_2, \dots, C_n ($n \geq 2$). Then G has the following properties:

- a) G is a subset of the smallest convex set containing C_1, C_2, \dots, C_n .
- b) G is a tree without free ends and free corners.
- c) If two sides of G have a common point, then their angle is at least $\frac{2}{3}\pi$.
- d) Every branching point of G has degree 3. The three sides of the graph incident to a branching point lie in a (2-dimensional) plane and any two have angle $\frac{2}{3}\pi$.

[Here as elsewhere k dimensions are essential. We have not found d) in later literature. This yields a better and stronger argument than e.g. in [HRW] p. 77.]

Proof of Theorem 3. Property a) follows from Proposition 4. To prove b) we can assume (by a)) that $k \geq 3$ (if $k < 3$ then we can embed \mathbb{R}_k into \mathbb{R}_3). Then b) follows from Propositions 1 and 2. The property c) we prove as follows: let $G \in \mathcal{M}$ and let $\overline{PM}, \overline{PN}$ be two sides of G with angle $\alpha < \frac{2}{3}\pi$. We construct a point M' in the interior of side \overline{PM} and a point N' in the interior of side \overline{PN} such that $\overline{PM'} = \overline{PN'} = h$. Then we have (see Fig. 1)

$$\begin{aligned} \overline{M'W} = \overline{N'W} &= \overline{M'W} \frac{2}{\sqrt{3}} = \frac{2}{\sqrt{3}} h \sin \frac{1}{2}\alpha, \\ \overline{PW} = \overline{PX} - \overline{WX} &= h \cos \frac{1}{2}\alpha - \frac{1}{\sqrt{3}} h \sin \frac{1}{2}\alpha \end{aligned}$$

and thus

$$\overline{M'W} + \overline{N'W} + \overline{PW} = h \left(\sqrt{3} \sin \frac{1}{2}\alpha + \cos \frac{1}{2}\alpha \right) < 2h = \overline{PM'} + \overline{PN'}.$$

[This step is justified in a detailed and characteristic footnote: We have $\frac{d}{dx}(\sqrt{3} \sin x + \cos x) = \sqrt{3} \cos x - \sin x = \cos x(\sqrt{3} - \tan x) > 0$ for $0 < x < \frac{1}{3}\pi$ and thus $\sqrt{3} \sin x + \cos x$ is an increasing function for $0 \leq x \leq \frac{1}{3}\pi$, hence we have for $0 < x < \frac{1}{3}\pi$:

$$\sqrt{3} \sin x + \cos x < \sqrt{3} \sin \frac{1}{3}\pi + \cos \frac{1}{3}\pi = 2.]$$

Define graph $G_1 = [G - (\overline{M'P} + \overline{N'P})] + \overline{M'W} + \overline{N'W} + \overline{PW}$. Obviously $G_1 \in \mathcal{M}$, $l(G_1) < l(G)$ and thus G is not a minimal graph.

The property d) follows immediately from c): three line segments incident in a point and which do not lie in a plane form angles whose sum is less than 2π .

R e m a r k. From Theorem 3 we obtain the following for the minimal graph G : if P is a branching point, then $V(P) = 1$, whereas $V(P) = -1$ for every endpoint P . From $V(P) = -2$ it follows that the number of branching points equals the number of endpoints -2 .

This is the end of the first two sections of the Jarník-Kössler paper. This is a remarkable text both in its clarity and contents. This part deals with general properties of Steiner trees, and these properties are generally attributed to later contributors although they are explicitly stated in the Jarník-Kössler paper. Here is a sample of such instances, mostly taken from a recent monograph [HRW] devoted to the “Steiner Tree Problem.”

The fact that for a Steiner tree all branching points are of degree 3, as well as the angle condition, the number of branching points, the convex hull result (i.e. Theorem 1.1, Theorem 1.2 of [HRW]) are attributed to Courant and Robbins [CR], Corollary 1.1, Corollary 1.5 of [HRW] are attributed to Gilbert and Pollak [GP]. These results are all explicitly contained in [JK] as various parts of Propositions 1–4 and Theorems 2–3.

Moreover, the generalization to k dimensions treated in [HRW], section 6.1 is not only mentioned but instrumental to [JK]. In fact the whole paper is written in k dimensions. And the complicated argument on [HRW], p. 77 is replaced by the pleasant Jarník-Kössler argument that three sides incident with a branching point are coplanar.

After all these years the Jarník-Kössler paper precisely in its general part (i.e. sections 1 and 2) is an example of clear style and elegance, and it is worth studying even today. The clarity of the introduction to the problem is not shared by many later texts.

No wonder, the “Steiner problem” is due to Jarník and Kössler and was elaborated by them to a degree surpassed only 30 years later. Comparing [J] and [JK] we see that what we have here is Jarník’s problem.

The Jarník-Kössler paper [JK] continues with the treatment of regular n -gons. They solve the cases $n = 3, 4, 5$ explicitly and carefully with all details (without referring to any earlier work for $n = 3$) and remark that for $n = 6$ they prove that the situation is entirely different: the solution is given by 5 sides of a regular hexagon. They prove this by an elegant argument for all $n \geq 13$. They leave it open for $7 \leq n \leq 12$ and remark that this is a finite problem *which could be directly solved with a certain amount of effort*. Indeed, their method of solution for $n = 3, 4, 5$ suggests that they were aware of the finiteness of the problem (proved much later by Melzak [M]).

4. JARNÍK-KÖSSLER'S PAPER IN A HISTORICAL PERSPECTIVE

The problem of finding a shortest connection between n given points in the plane has a long history. Indeed, it is one of the oldest optimization problems and it was, and is, frequently used as an example of maximality (and minimality) arguments. However, for most of the time in the long history of the problem, only the case $n = 3$ was considered. This goes back to a question posed by Fermat, was considered by Mersenne and solved by Torricelli and Cavalieri. The elegant solution of this problem of elementary geometry of course attracted many researchers such as Simpson and Steiner who also considered a generalization of the 3-point problem in a different direction: given n points in the plane, find a *single* vertex with the smallest sum of distances.

The history is involved and there are several sources available, such as [Ku] and [Z], and also early industrial applications such as the book [W] and the thorough mathematical treatment in [St].

However, prior to 1934 the problem of the shortest connection of n points was not considered (Ron Graham [G] informed us that Gauss formulated the n -point problem in one of his letters). It was first considered by Jarník and Kössler [JK], with a clarity and rigour which we hope is clear from the translation of the first two sections of [JK].

It is difficult to speculate why the authors considered this problem. In Jarník's oeuvre the papers [J] and [JK] present the only singularity. As a possible solution to this puzzle one could perhaps stress the fact that Jarník instantly recognized the novelty of Borůvka's problem and saw it as an n -point minimization problem. His interpretation of the minimal spanning tree problem given at the end of [J] (section 1 of this paper contains a translation of this) may suggest how naturally he may have arrived at the problem considered in [JK]. That could also suggest why Jarník considered *essentially* the k -dimensional problem. He didn't arrive at it from the geometry of the plane but from spatial geometry (see again the Remark at the end of [J], translated in section 1).

Like Borůvka, Jarník never returned to this problem again.

The 3-point problem was a classical optimization problem and it found its way into the Courant-Robbins book [CR] where the problem for $n = 3$ (i.e. the Fermat-Torricelli-Cavalieri-Simpson-Steiner problem) is called the Steiner problem and the problem of the nearest point to a given set of points (i.e. the problem considered by Steiner) is called a "mathematically sterile generalization." The problem of the shortest interconnection between n points is called the generalized Steiner problem [CR]. This is clearly Jarník's problem or the Jarník-Kössler problem.

These attributions (and some stylistic expressions) suggest that Courant and Robbins were motivated by [St] and [Z].

In the thirties Jarník was an internationally famous mathematician (a speaker at both the Zürich 1932 and the Oslo 1936 Congress of the International Mathematical Union) and thus the main reason for the omission probably was that Courant and Robbins did not know about his work outside number theory and analysis. The “Steiner” problem was then dormant for another 20 years until it was revived by Melzak [M], Gilbert and Pollack [GP] and others with the vigour and confidence of newly developing fields of combinatorial (discrete) optimization and the theory of algorithms. The problem is hard both theoretically [GGJ] and practically, and for its direct applications in VLSI [KPS] and other fields (see e.g. [HRW]) it is still intensively studied. And it is far from being solved.

Summarizing, let us just say that with these combinatorial papers [J], [JK] Jarník was very lucky. Single handedly (with the help of Borůvka and Kössler) he started important branches of fields which were in his time not yet born. The style and rigour of his contributions have lasting value. Jarník’s contribution is widely unrecognized (e.g. neither the recent Handbook of Combinatorics nor the Handbook of Computational Geometry mention him).

It is not a marginal contribution by a passerby. It is rather an important contribution by a major mathematician. Combinatorics was gaining strength while slowly emerging from the “slums of topology,” through the expertise and brilliance of mathematicians from other fields. From number theory these were Erdős and Turán and Jarník.

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