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## On the Non-existence of Certain Ovaloids

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We prove the non-existence of ovaloids satisfying

$$\Delta\{(K^{-1}dg(K))\} + 2g(K) = 0, \quad g : (0, \infty) \rightarrow < 0, \infty).$$

Несуществование некоторых оваллоидов. Доказано несуществование оваллоидов, для которых

$$\Delta\{(K^{-1}dg(K))\} + 2g(K) = 0, \quad g : (0, \infty) \rightarrow < 0, \infty).$$

Neexistence jistých ovaloidů. Je dokázána neexistence ovaloidu, pro kteréž

$$\Delta\{(K^{-1}dg(K))\} + 2g(K) = 0, \quad g : (0, \infty) \rightarrow < 0, \infty).$$

A more detailed analysis of the proof of the linearity of certain functions on the sphere, see [2], enables us to prove the following

**Theorem.** Let  $g : \mathbf{R}^+ \rightarrow \mathbf{R}^+ \cup \{0\}$ ,  $\mathbf{R}^+ = (0, \infty)$ ,  $g \not\equiv 0$ , be a function. Then there is no ovaloid  $M \subset E_3$  such that

$$(1) \quad \Delta \left\{ \int K^{-1} \frac{dg(K)}{dK} dK \right\} + 2g(K) = 0.$$

Here,  $K$  is the Gauss curvature of  $M$  and  $\Delta$  the Laplacian.

**Proof:** Let us consider just the Riemannian structure of a given ovaloid  $M$ . In a suitable domain  $\mathcal{D}$  of  $M$ , let us choose 1-forms  $\omega^1, \omega^2$  such that  $\omega^1 \wedge \omega^2 \neq 0$  and

$$(2) \quad ds^2 = (\omega^1)^2 + (\omega^2)^2;$$

$M$  may be covered by such domains. Then there is a 1-form  $\omega_1^2$  such that

$$(3) \quad d\omega^1 = -\omega^2 \wedge \omega_1^2, \quad d\omega^2 = \omega^1 \wedge \omega_1^2,$$

and we get

$$(4) \quad d\omega_1^2 = -K\omega^1 \wedge \omega^2,$$

$K$  being the Gauss curvature of  $M$ . Be given a real valued function  $f$  on  $M$ . Then, in  $\mathcal{D}$ , we get by the standard prolongation procedure the covariant

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derivatives  $f_i, f_{ij}, A, \dots, D, R, \dots, V$  of  $f$  with respect to  $\omega^1, \omega^2$  by means of the formulae

$$\begin{aligned}
(5) \quad & df = f_1\omega^1 + f_2\omega^2 ; \\
(6) \quad & (df^2 - f_2\omega_1^2) \wedge \omega^1 + (df_2 + f_1\omega_1^2) \wedge \omega^2 = 0 ; \\
(7) \quad & df_1 - f^2\omega_1^2 = f_{11}\omega^1 + f_{12}\omega^2 , \\
& df^2 + f_1\omega_1^2 = f_{12}\omega^1 + f_{22}\omega^2 ; \\
(8) \quad & (df_{11} - 2f_{12}\omega_1^2) \wedge \omega^1 + \{df_{12} + (f_{11} - f_{22})\omega_1^2\} \wedge \omega^2 = Kf_2\omega^1 \wedge \omega_2 , \\
& \{df_{12} + (f_{11} - f_{22})\omega_1^2\} \wedge \omega^1 + (df_{22} + 2f_{12}\omega_1^2) \wedge \omega^2 = -Kf_1\omega^1 \wedge \omega_2 ; \\
(9) \quad & df_{11} - 2f_{12}\omega_1^2 = A\omega^1 + (B - \frac{1}{2}Kf_2)\omega^2 , \\
& df_{12} + (f_{11} - f_{22})\omega_1^2 = (B + \frac{1}{2}Kf_2)\omega^1 + (C + \frac{1}{2}Kf_1)\omega^2 , \\
& df_{22} + 2f_{12}\omega_1^2 = (C - \frac{1}{2}Kf_1)\omega^1 + D\omega^2 ; \\
(10) \quad & \{dA - (3B + \frac{1}{2}Kf_2)\omega_1^2\} \wedge \omega^1 + \{dB + (A - 2C - \frac{1}{2}Kf_1)\omega_1^2\} \wedge \omega^2 = \\
& = \frac{1}{2}(5Kf_{12} + K_1f_2)\omega^1 \wedge \omega^2 , \\
& \{dB + (A - 2C - \frac{1}{2}Kf_1)\omega_1^2\} \wedge \omega^1 + \{dC + (2B - D + \frac{1}{2}Kf_2)\omega_1^2\} \wedge \omega^2 = \\
& = \frac{1}{2}(3Kf_{22} - 3Kf_{11} + K_2f_2 - K_1f_1)\omega^1 \wedge \omega^2 , \\
& \{dC + (2B - D + \frac{1}{2}Kf_2)\omega_1^2\} \wedge \omega^1 + \{dD + (3C + \frac{1}{2}Kf_1)\omega_1^2\} \wedge \omega^2 = \\
& = -\frac{1}{2}(5Kf_{12} + K_2f_1)\omega^1 \wedge \omega^2 ; \\
(11) \quad & dA - (3B + \frac{1}{2}Kf_2)\omega_1^2 = R\omega^1 + (S - \frac{5}{4}Kf_{12} - \frac{1}{4}K_1f_2)\omega^2 , \\
& dB + (A - 2C - \frac{1}{2}Kf_1)\omega_1^2 = (S + \frac{5}{4}Kf_{12} + \frac{1}{4}K_1f_2)\omega^1 + \\
& + (T + \frac{3}{2}Kf_{11} + \frac{1}{2}Kf_1f_1)\omega^2 , \\
& dC + (2B - D + \frac{1}{2}Kf_2)\omega_1^2 = (T + \frac{3}{2}Kf_{22} + \frac{1}{2}K_2f_2)\omega^1 + \\
& + (U + \frac{5}{4}Kf_{12} + \frac{1}{4}K_2f_1)\omega^2 , \\
& dD + (3C + \frac{1}{2}Kf_1)\omega_1^2 = (U - \frac{5}{4}Kf_{12} - \frac{1}{4}K_2f_1)\omega^1 + V\omega^2 . \\
(12) \quad & \varphi = \{ -f_{12}A + (f_{11} - f_{22})(B + \frac{1}{2}Kf_2) + f_{12}(C - \frac{1}{2}Kf_1) \} \omega^1 + \\
& + \{ -f_{12}(B - \frac{1}{2}Kf_2) + (f_{11} - f_{22})(C + \frac{1}{2}Kf_1) + f_{12}D \} \omega^2 .
\end{aligned}$$

This form is invariant, see [1], and we have

$$(13) \quad d\varphi = -[\Phi + \{(f_{11} - f_{22})^2 + 4f_{12}^2\}K] \omega^1 \wedge \omega^2$$

with

$$(14) \quad \Phi = 2(B^2 + C^2 - AC - BD) - \frac{1}{2}(f_1^2 + f_2^2)K^2 - (f_1A + f_2D)K .$$

Now, let us study a general equation

$$(15) \quad \Delta f + 2g = 0$$

on  $M$ . In our notation, (15) turns out to be

$$(16) \quad f_{11} + f_{22} + 2g = 0 .$$

Because of (9), the differential consequences of (16) are

$$(17) \quad A + C - \frac{1}{2}Kf_1 + 2g_1 = 0 , \quad B + D - \frac{1}{2}Kf_2 + 2g_2 = 0 ,$$

and we get

$$(18) \quad \begin{aligned} \Phi &= 2B^2 + 2C^2 - \frac{1}{2}(f_1^2 + f_2^2)K^2 + \\ &+ (2C + f_1K)(C - \frac{1}{2}Kf_1 + 2g_1) + (2B + f_2K)(B - \frac{1}{2}Kf_2 + 2g_2) = \\ &= (2B + g_2)^2 + (2C + g_1)^2 - (g_2 - f_2K)^2 - (g_1 - f_1K)^2. \end{aligned}$$

Suppose

$$(19) \quad dg = Kdf;$$

of course, we get

$$(20) \quad dK \wedge df = 0$$

as an immediate consequence. The suppositions  $f = f(K)$  and (19) imply

$$(21) \quad \Phi \geq 0,$$

and we get

$$(22) \quad f_{11} - f_{22} = 0, \quad f_{12} = 0$$

from the integral formula  $\int_M d\varphi = 0$ . From (16) and (22),  $f_{11} = f_{22} = -g$ , i.e.,

$$(23) \quad df = f_1\omega^1 + f_2\omega^2, \quad df_1 - f_2\omega_1^2 = -g\omega^1, \quad df_2 + f_1\omega_1^2 = g\omega^2.$$

Now,

$$(24) \quad d * df = d(-f_2\omega^1 + f_1\omega^2) = -2g\omega^1 \wedge \omega^2;$$

the supposition  $g \geq 0$  and the integral formula  $\int_M d * df = 0$  imply

$$(25) \quad g = 0.$$

Because of  $K > 0$ , we get

$$(26) \quad f = \text{const.}$$

from (19). Thus there is only one couple of functions  $g(K)$ ,  $f(K) = \int K^{-1}g'(K)dK$  satisfying (15), this couple being given by (25) + (26). QED.

As an example of our Theorem, we get the following.

**Corollary.** *There are no ovaloids  $M \subset E^3$  satisfying*

$$(27) \quad \alpha \Delta K^{\alpha-1} + (\alpha - 1) K^\alpha = 0, \quad 1 \neq \alpha \in \mathbf{R}.$$

**Proof.** Take  $g(K) = K^\alpha$ . QED.

#### References

- [1] ŠVEC A.: Contributions to the global differential geometry of surfaces. Rozpravy ČSAV, Praha; 1977.
- [2] ŠVEC A.: A remark on the differential equations on the sphere. Czech. Mat. J.; to appear.