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Kačanov - Galerkin Method and its Application

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The Kačanov's method on the convergence of approximants of the minimum of nonquadratic functionals is explained in the book by MICHLIN [4, pp. 369—370] and it was firstly applied by L. M. KAČANOV [2]. The proof of the convergence of this method was given by ROZE [7], but in [4] on p. 369 (footnote 2) it is remarked that the proof contains a mistake. The convergence of this method for the solving of the magnetostatic field in nonlinear media has been proved in the paper by KAČUR, NEČAS, POLÁK and SOUČEK [3]. The proof in the abstract setting of the convergence has been given in the authors' paper [1].

This communication deals with the KAČANOV-GALERKIN method and with the application to the second and mixed problems for elastoplastic materials, where the deformation theory of plasticity is used (see for example NEČAS [6]).

Kačanov-Galerkin Method

Let \tilde{H} be a Hilbert space with the inner product (\cdot, \cdot) and let H be a closed subspace with the same inner product. Suppose that $f: \tilde{H} \rightarrow R_1$ is a functional defined on \tilde{H} with the Gâteaux derivative $f'(u)$ in each point $u \in \tilde{H}$ which is continuous on \tilde{H} and f' takes the bounded subset in \tilde{H} onto bounded subsets.

Let $\varphi \in \tilde{H}$ and $x^* \in \tilde{H}$. Let $c_1 > 0$ and suppose that for each $u \in \tilde{H}$ and $h \in H$ it is

$$(i) \quad (h, f'(u+h) - f'(u)) \geq c_1 \|h\|^2.$$

From the well-known theorem (see e.g. VAJNBERG [8, Thm. 9.2]) it follows that there exists a uniquely determined $x_0 \in H$ satisfying

$$f(x_0 + x^*) - (x_0 + x^*, \varphi) = \min_{v \in H} \{f(v + v^*) - (v + v^*, \varphi)\}. \quad (1)$$

The main goal of the Kačanov's method is the introducing the functional $\Phi: \tilde{H} \times \tilde{H} \times \tilde{H} \rightarrow R_1$ such that $\Phi(u, \cdot, \cdot): \tilde{H} \times \tilde{H} \rightarrow R_1$ is a bilinear and symmetric form for each fixed $u \in \tilde{H}$. Suppose that there exist $c_2, c_3 > 0$ such that for each $u, v, w \in \tilde{H}$ and $h \in H$ it is:

$$(ii) \quad \Phi(u, h, h) \geq c_2 \|h\|^2,$$

- (iii) $\Phi(u, u, h) = (h, f'(u)),$
 (iv) $\frac{1}{2} \Phi(u, v, v) - \frac{1}{2} \Phi(u, u, u) - f(v) + f(u) \geq 0,$
 (v) $\Phi(u, v, w) \leq c_3 \|v\| \cdot \|w\|.$

The reason for introducing the functional Φ which approximates in the sense (iii), (iv) our functional f is that $\Phi(u, v, v)$ is quadratic, so it is easy to find the minimum of the functional $\frac{1}{2}\Phi(u, v, v) - (v, \varphi)$.

For the Kačanov-Galerkin method suppose that $\varphi_n \rightarrow \varphi, x_n^* \rightarrow x^*, \sum_{n=1}^{\infty} \|x_{n+1}^* - x_n^*\|, \sum_{n=1}^{\infty} \|\varphi_{n+1} - \varphi_n\|$ are the convergent series and $\{H_n\}$ is a sequence of closed subspaces of H such that

(vi) $H_n \subset H_{n+1}, \quad \overline{\bigcup H_n} = H.$

Let $x_1 \in H_1$. Then (again by [8, Thm. 9.2]) there exists a uniquely determined sequence $\{x_n\} \subset H$ such that $x_n \in H_n$ and

$$\begin{aligned} & \frac{1}{2} \Phi(x_n + x_{n+1}^*, x_{n+1} + x_{n+1}^*, x_{n+1} + x_{n+1}^*) - (x_{n+1} + x_{n+1}^*, \varphi_{n+1}) = \\ & = \min_{v \in H_{n+1}} \left\{ \frac{1}{2} \Phi(x_n + x_{n+1}^*, v + x_{n+1}^*, v + x_{n+1}^*) - (v + x_{n+1}^*, \varphi_{n+1}) \right\}, \\ & \qquad \qquad \qquad n = 1, 2, \dots \end{aligned} \tag{2}$$

Theorem. $\lim_{n \rightarrow \infty} \|x_n - x_0\| = 0.$

(The proof has the following steps:

- (1) The sequence $\{\|x_n\|\}$ is bounded.
 (2) $\lim_{n \rightarrow \infty} \|x_{n+1} - x_n\| = 0.$

Application

Our Theorem can be applied to the variational problem:

$$\min_{\substack{u \in W \\ u - u^* \in V}} \left\{ \int_{\Omega} \left[\frac{k(x)}{2} \vartheta^2(u) + \frac{1}{2} \int_0^{\Gamma(u, u)} \mu(x, \sigma) d\sigma \right] dx - \int_{\Omega} u_i F_i dx - \int_{\Gamma_1} u_i g_i ds \right\},$$

where Ω is a bounded domain in R_3 with the boundary $\partial\Omega = \Gamma_1 \cup \Gamma_2 \cup R$, $\Gamma_1 \cap \Gamma_2 = \emptyset$, Γ_1, Γ_2 are open sets in $\partial\Omega$, $\Gamma_2 \neq \emptyset$, two dimensional measure of R is zero; $W = [W_{\frac{1}{2}}^1(\Omega)]^3$, $V = [\overset{\circ}{W}_{\frac{1}{2}}^1(\Omega)]^3$, ($W_{\frac{1}{2}}^1(\Omega)$ and $\overset{\circ}{W}_{\frac{1}{2}}^1(\Omega)$ are the Sobolev spaces — see e.g. NEČAS [5, Chapt. 1]); $F_i \in L_2(\Omega)$ are the components of the body force, $g_i \in L_2(\Gamma_1)$ are the components of the boundary force vector; $k(x) \in L_{\infty}(\Omega)$ is the bulk modulus of the material; $\mu(x, s)$ is the Lamé's coefficient, $\mu(x, s)$ is

measurable in $x \in \Omega$ for fixed $s \in \langle 0, \infty \rangle$ and continuously differentiable in the variable $s \in \langle 0, \infty \rangle$ for almost all $x \in \Omega$; u is the displacement vector; $e_{ij}(u) = \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$ is the infinitesimal strain tensor; $\vartheta(u) = e_{ii}(u)$ and

$$\Gamma(u, v) = 2e_{ij}(u) e_{ij}(v) - \frac{2}{3} \vartheta(u) \vartheta(v).$$

Under the assumptions:

$$0 < \mu_0 \leq \mu(x, s) \leq \frac{3}{2} k(x) \leq k_1 < +\infty,$$

$$\mu(x, s) + 2 \frac{\partial \mu(x, s)}{\partial s} \cdot s \geq \kappa > 0,$$

$$\frac{\partial \mu}{\partial s}(x, s) \leq 0,$$

we can set in abstract Theorem:

$$f(u) = \frac{1}{2} \int_{\Omega} [k(x) \vartheta^2(u) + \int_0^{\Gamma(u, u)} \mu(x, \sigma) d\sigma] dx,$$

$$\Phi(u, v, h) = \int_{\Omega} [k(x) \vartheta(v) \vartheta(h) + \mu(x, \Gamma(u, u)) \cdot \Gamma(v, h)] dx.$$

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