

Hans Havlicek

On the matrices of central linear mappings

Mathematica Bohemica, Vol. 121 (1996), No. 2, 151–156

Persistent URL: <http://dml.cz/dmlcz/126103>

Terms of use:

© Institute of Mathematics AS CR, 1996

Institute of Mathematics of the Czech Academy of Sciences provides access to digitized documents strictly for personal use. Each copy of any part of this document must contain these *Terms of use*.



This document has been digitized, optimized for electronic delivery and stamped with digital signature within the project *DML-CZ: The Czech Digital Mathematics Library* <http://dml.cz>

ON THE MATRICES OF CENTRAL LINEAR MAPPINGS

HANS HAVLICEK, Wien

(Received January 27, 1995)

Summary. We show that a central linear mapping of a projectively embedded Euclidean n -space onto a projectively embedded Euclidean m -space is decomposable into a central projection followed by a similarity if, and only if, the least singular value of a certain matrix has multiplicity $\geq 2m - n + 1$. This matrix is arising, by a simple manipulation, from a matrix describing the given mapping in terms of homogeneous Cartesian coordinates.

Keywords: linear mapping, axonometry, singular values

AMS classification: 51N15, 51N05, 15A18, 68U05

1. INTRODUCTION

A linear mapping between projectively embedded Euclidean spaces is called *central*, if its exceptional subspace is not at infinity. Such a linear mapping is in general not decomposable into a central projection followed by a similarity. Necessary and sufficient conditions for the existence of such a decomposition have been given in [4] for arbitrary finite dimensions; cf. also [1], [2], [3]. However, those results do not seem to be immediately applicable on a *central axonometry*, i.e., a central linear mapping given via an axonometric figure. On the other hand, in a series of recent papers [5], [6], [7] this problem of decomposition has been discussed for central axonometries of the Euclidean 3-space onto the Euclidean plane from an elementary point of view¹.

Loosely speaking, the concept of central axonometry is a geometric equivalent to the algebraic concept of a *coordinate matrix* for a linear mapping of the underlying vector spaces. However, from the results in [2] and [4] it is also not immediate whether or not a given matrix describes (in terms of homogeneous Cartesian coordinates) a mapping that permits the above-mentioned factorization. The aim of this communication is to give a criterion for this.

¹ A lot of further references can be found in the quoted papers.

Let \mathbf{I}, \mathbf{J} be finite-dimensional Euclidean vector spaces. Given a linear mapping $f: \mathbf{I} \rightarrow \mathbf{J}$ denote by $f^{\text{ad}}: \mathbf{J} \rightarrow \mathbf{I}$ its adjoint mapping. Then $f^{\text{ad}} \circ f$ is self-adjoint with eigenvalues

$$v_1 \geq \dots \geq v_r > v_{r+1} = \dots = v_n = 0.$$

Here r equals the rank of f and $n = \dim \mathbf{I}$. Moreover, each eigenvalue is written down repeatedly according to its multiplicity². The positive real numbers $\sqrt{v_1}, \dots, \sqrt{v_r}$ are frequently called the *singular values* of f . The multiplicity of a singular value of f is defined via the multiplicity of the corresponding eigenvalue of $f^{\text{ad}} \circ f$. It is immediate from the singular value decomposition that f and f^{ad} share the same singular values (counted with their multiplicities). See, e.g., [8].

These results hold true, *mutatis mutandis*, when replacing f by any real matrix, say A , and f^{ad} by the transpose matrix A^T .

2. DECOMPOSITIONS

When discussing central linear mappings it will be convenient to consider Euclidean spaces embedded in projective spaces. Thus let \mathbf{V} be an $(n+1)$ -dimensional real vector space ($3 \leq n < \infty$) and \mathbf{I} one of its hyperplanes. Assume, furthermore, that \mathbf{I} is equipped with a positive definite inner product (\cdot) so that \mathbf{I} is a Euclidean vector space. In the projective space on \mathbf{V} , denoted by $\mathcal{P}(\mathbf{V})$, we consider the projective hyperplane $\mathcal{P}(\mathbf{I})$ as the hyperplane at infinity. The absolute polarity in $\mathcal{P}(\mathbf{I})$ is determined by the inner product on \mathbf{I} . Hence $\mathcal{P}(\mathbf{V}) \setminus \mathcal{P}(\mathbf{I})$ is a projectively embedded Euclidean space³. Similarly, let $\mathcal{P}(\mathbf{W}) \setminus \mathcal{P}(\mathbf{J})$ be an m -dimensional projectively embedded Euclidean space ($2 \leq m < n < \infty$). Given a linear mapping

$$(1) \quad f: \mathbf{V} \rightarrow \mathbf{W}$$

of vector spaces then the associate (projective) linear mapping

$$(2) \quad \varphi: \mathcal{P}(\mathbf{V}) \setminus \mathcal{P}(\ker f) \rightarrow \mathcal{P}(\mathbf{W}), \mathbb{R}\mathbf{x} \mapsto \mathbb{R}(f(\mathbf{x}))$$

has $\mathcal{P}(\ker f)$ as its exceptional subspace. In the sequel we shall assume that

$$(3) \quad \ker f \not\subset \mathbf{I} \quad \text{and} \quad f(\mathbf{V}) = \mathbf{W},$$

² For a self-adjoint mapping the algebraic and geometric multiplicities of an eigenvalue are identical. Hence we may unambiguously use the term 'multiplicity'.

³ We do not endow this space with a unit segment.

or, in other words, that φ is central and surjective⁴. Obviously, (3) is equivalent to

$$(4) \quad f(\mathbf{I}) = \mathbf{W}.$$

We recall some results [2], [4]: If \mathbf{T} is any complementary subspace of $\ker f$ in \mathbf{V} , then denote by

$$(5) \quad \psi_{\mathbf{T}}: \mathcal{P}(\mathbf{V}) \setminus \mathcal{P}(\ker f) \rightarrow \mathcal{P}(\mathbf{T})$$

the projection with the exceptional subspace $\mathcal{P}(\ker f)$ onto $\mathcal{P}(\mathbf{T})$. The restricted mapping

$$(6) \quad \varphi_{\mathbf{T}} := \varphi|_{\mathcal{P}(\mathbf{T})}: \mathcal{P}(\mathbf{T}) \rightarrow \mathcal{P}(\mathbf{W})$$

is a collineation and

$$(7) \quad \varphi = \varphi_{\mathbf{T}} \circ \psi_{\mathbf{T}};$$

every decomposition of φ into a projection and a collineation is of this form. In the Euclidean vector space \mathbf{I} we have the distinguished subspace

$$(8) \quad \mathbf{E} := f^{-1}(\mathbf{J}) \cap \mathbf{I}.$$

Write

$$(9) \quad f_{\mathbf{E}}: \mathbf{E} \rightarrow \mathbf{J}, \mathbf{x} \mapsto f(\mathbf{x});$$

this $f_{\mathbf{E}}$ is well-defined and surjective, since $\mathbf{E} \subset f^{-1}(\mathbf{J})$ and $\ker f \not\subset \mathbf{E}$. The subspace \mathbf{T} can be chosen with $\varphi_{\mathbf{T}}$ being a similarity if, and only if, the least singular value of $f_{\mathbf{E}}$ has multiplicity⁵ $\geq 2m - n + 1$.

Next, we assume that $\mathcal{P}(\mathbf{T}) \not\subset \mathcal{P}(\mathbf{I})$ is orthogonal to $\mathcal{P}(\ker f)$. This means that $(\mathbf{T} \cap \mathbf{I})^{\perp} \subset \ker f \cap \mathbf{I}$ or $(\mathbf{T} \cap \mathbf{I})^{\perp} \supset \ker f \cap \mathbf{I}$. Hence $\psi_{\mathbf{T}}$ is an *orthogonal central projection*⁶. It is easily seen from [2] that φ permits a decomposition into an orthogonal central projection followed by a similarity if, and only if, all singular values of $f_{\mathbf{E}}$ are equal.

⁴ This assumption of surjectivity is made 'without loss of generality' in most papers on this subject. It will, however, be essential several times in this paper.

⁵ In [2, Satz 10] this multiplicity is printed incorrectly as $2m - n - 1$.

⁶ The central projections used in elementary descriptive geometry are trivial examples of orthogonal central projections.

Finally, we are going to show that the crucial properties of $f_{\mathbf{E}}$ can be read off from another mapping: Denote by

$$(10) \quad p: \mathbf{I} \rightarrow \mathbf{E}$$

the orthogonal projection with the kernel $\mathbf{E}^\perp \subset \mathbf{I}$. Then

$$(11) \quad (f_{\mathbf{E}} \circ p) \circ (f_{\mathbf{E}} \circ p)^{\text{nd}} = f_{\mathbf{E}} \circ p \circ p^{\text{nd}} \circ (f_{\mathbf{E}})^{\text{nd}} = f_{\mathbf{E}} \circ (f_{\mathbf{E}})^{\text{nd}},$$

since p^{nd} is the natural embedding $\mathbf{E} \rightarrow \mathbf{I}$. Thus, by (11) and the results stated in Section 1, $f_{\mathbf{E}}$ and $(f_{\mathbf{E}} \circ p)^{\text{nd}}$ have the same singular values (counted with their multiplicities). Hence, by the surjectivity of $f_{\mathbf{E}}$ and (11), all singular values of $f_{\mathbf{E}}$ are equal if, and only if, there exists a real number $v > 0$ such that

$$(12) \quad (f_{\mathbf{E}} \circ p) \circ (f_{\mathbf{E}} \circ p)^{\text{nd}} = v \text{id}_{\mathbf{J}}.$$

We shall use this in the next section.

3. A MATRIX CHARACTERIZATION

Introducing homogeneous Cartesian coordinates in $\mathcal{P}(\mathbf{V})$ is equivalent to choosing a basis $\{\mathbf{b}_0, \dots, \mathbf{b}_n\}$ of \mathbf{V} such that $\{\mathbf{b}_1, \dots, \mathbf{b}_n\} \subset \mathbf{I}$ is an orthonormal system. The origin is given by $\mathbb{R}\mathbf{b}_0$ and the unit points are $\mathbb{R}(\mathbf{b}_0 + \mathbf{b}_1), \dots, \mathbb{R}(\mathbf{b}_0 + \mathbf{b}_n)$. In the same manner we are introducing homogeneous Cartesian coordinates in $\mathcal{P}(\mathbf{W})$ via a basis $\{\mathbf{c}_0, \dots, \mathbf{c}_m\}$.

Theorem 1. *Suppose that $f: \mathbf{V} \rightarrow \mathbf{W}$ is inducing a surjective central linear mapping φ according to formula (2). Let*

$$(13) \quad A = \begin{pmatrix} a_{00} & \cdots & a_{0n} \\ \vdots & & \vdots \\ a_{m0} & \cdots & a_{mn} \end{pmatrix}$$

be the coordinate matrix of f with respect to bases of \mathbf{V} and \mathbf{W} that are yielding homogeneous Cartesian coordinates. Write

$$(14) \quad \mathbf{a}_i := (a_{i1}, \dots, a_{in}) \in \mathbb{R}^n \text{ for all } i = 0, \dots, m$$

and

$$(15) \quad \tilde{A} := \begin{pmatrix} \mathbf{a}_1 - \frac{\mathbf{a}_0 \cdot \mathbf{a}_1}{\mathbf{a}_0 \cdot \mathbf{a}_0} \mathbf{a}_0 \\ \vdots \\ \mathbf{a}_m - \frac{\mathbf{a}_0 \cdot \mathbf{a}_m}{\mathbf{a}_0 \cdot \mathbf{a}_0} \mathbf{a}_0 \end{pmatrix}.$$

Then the following assertions hold true:

1. φ is decomposable into a central projection followed by a similarity if, and only if, the least singular value of the matrix \tilde{A} has multiplicity $\geq 2m - n + 1$.
2. φ is decomposable into an orthogonal central projection followed by a similarity if, and only if, there exists a real number $v > 0$ such that

$$(16) \quad \tilde{A}\tilde{A}^T = \text{diag}(v, \dots, v).$$

Proof. We read off from the top row of A that

$$a_{00}x_0 + \dots + a_{0n}x_n = 0$$

is an equation of $f^{-1}(\mathbf{J}) \neq \mathbf{I}$ so that $\mathbf{a}_0 \cdot \mathbf{a}_0 \neq 0$. Write $\tilde{f}: \mathbf{I} \rightarrow \mathbf{J}$ for the linear mapping whose coordinate matrix with respect to $\{\mathbf{b}_1, \dots, \mathbf{b}_n\}$ and $\{\mathbf{c}_1, \dots, \mathbf{c}_m\}$ equals \tilde{A} . A straightforward calculation shows that

$$\tilde{f}(\mathbf{x}) = f(\mathbf{x}) \text{ for all } \mathbf{x} \in \mathbf{E}$$

and

$$\tilde{f}(a_{01}\mathbf{b}_1 + \dots + a_{0n}\mathbf{b}_n) = 0,$$

i.e., $\mathbf{E}^\perp \subset \ker \tilde{f}$. Thus \tilde{f} equals the mapping $f_{\mathbf{E} \circ p}$ discussed above. Now the proof is completed by translating formulae (11) and (12) into the language of matrices. \square

We remark that (3) and the linear independence of $\mathbf{a}_1, \dots, \mathbf{a}_m$ are equivalent conditions.

In contrast to the results in [5], [6], [7], the φ -image of the origin $\mathbf{R}\mathbf{b}_0$ does not appear in our characterization. On the other hand, we have

$$f(\mathbf{E}^\perp) = \mathbf{R}((\mathbf{a}_0 \cdot \mathbf{a}_0)\mathbf{c}_0 + \dots + (\mathbf{a}_0 \cdot \mathbf{a}_m)\mathbf{c}_m).$$

In projective terms this 1-dimensional subspace of \mathbf{W} gives the *principal point* of the mapping φ . Exactly if the principal point of φ equals the origin $\mathbf{R}\mathbf{c}_0$, then \tilde{A} arises from A merely by deleting the top row and the leading column.

References

- [1] *Brauner H.*: Zur Theorie linearer Abbildungen. *Abh. Math. Sem. Univ. Hamburg* 53 (1983), 154–169.
- [2] *Brauner H.*: Lineare Abbildungen aus euklidischen Räumen. *Beitr. Algebra u. Geometrie* 21 (1986), 5–26.
- [3] *Brauner H.*: Zum Satz von Pohlke in n -dimensionalen euklidischen Räumen. *Sitzungsber. österreich. Akad. Wiss., Math.-Natur. Kl.* 195 (1986), 585–591.
- [4] *Havel V.*: On decomposition of singular mappings (In Czech). *Časopis Pěst. Mat.* 85 (1960), 439–446.
- [5] *Paukowitz P.*: Fundamental ideas for computer-supported descriptive geometry. *Comput. & Graphics* 12 (1988), 3–14.
- [6] *Szabó J.*: Eine analytische Bedingung dafür, daß eine Zentralaxonometrie Zentralprojektion ist. *Publ. Math. Debrecen* 44 (1994), 381–390.
- [7] *Szabó J., Stachel H., Vogel H.*: Ein Satz über die Zentralaxonometrie. *Sitzungsber. österreich. Akad. Wiss., Math.-Natur. Kl.* 203 (1994), 1–11.
- [8] *Strang G.*: *Linear Algebra and Its Applications*, 3rd ed. Harcourt Brace Jovanovich, San Diego, 1988.

Author's address: Hans Havlicek, Abteilung für Lineare Algebra und Geometrie, Technische Universität, Wiedner Hauptstraße 8–10, A–1040 Wien, Austria, e-mail: havlicek@geometrie.tuwien.ac.at.