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ERROR ESTIMATE FOR QUADRATIC SPLINE INTERPOLATING
THE FIRST DERIVATIVES

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Abstract. For the quadratic spline interpolating the given values of the first derivative the estimates of interpolation error are studied.

Key words: splines, quadratic splines, error estimates

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1. Simple set of spline knots

Let us have the growing sequence of simple knots

$$(\Delta x) = \{x_i; i=0(1)n+1\}, \text{ with } h_i = x_{i+1} - x_i,$$

and the given values $\{m_i; i=0(1)n+1\}$. Denote $\mathcal{S}_2(\Delta x)$ the linear space of quadratic splines with knots (Δx) . It is wellknown that any quadratic spline $s(x) \in \mathcal{S}_2(\Delta x)$ can be piecewise written as (see [1])

$$(1) \quad s(x) = (1-t^2)s_i + t^2 s_{i+1} + h_i t(1-t)m_i$$

for $x \in [x_i, x_{i+1}]$, $i=0(1)n$, $t=(x-x_i)/h_i$, $s_j = s(x_j)$.

Such a spline can be uniquely determined by the conditions

of interpolation of the first derivatives

$$(2) \quad s'(x_i) = m_i, \quad i=0(1)n+1$$

and by one additional (initial) condition

$$(3) \quad s(x_k) = s_k \quad \text{with } k \in \{0, \dots, n+1\}.$$

The spline values $s_i = s(x_i)$ and the values of its derivatives $m_i = s'(x_i)$ are connected together by continuity conditions $s \in C^1[x_0, x_{n+1}]$, which can be expressed as

$$(4) \quad s_{i+1} - s_i = h_i (m_{i+1} + m_i) / 2, \quad i=0(1)n, \quad (\text{see [1], [2]}).$$

In case of $m_i = g'(x_i)$ with some known function g , we can ask for the interpolation error $e(x) = g(x) - s(x)$. For equidistant knot mesh (Δx) we can find the error estimate in [2].

Theorem 1

Let the spline knots (Δx) and values $m_i = g'(x_i) = g'_i$, $i=0(1)n+1$ with $g \in C^3[x_0, x_{n+1}]$ are given.

Denote $s(x) \in S_2(\Delta x)$ the quadratic spline determined by the conditions

$$(5) \quad s(x_0) = s_0 = g(x_0), \quad s'(x_i) = m_i, \quad i=0(1)n+1$$

and let $e(x) = g(x) - s(x)$, $e_j = e(x_j)$.

Then the following error estimates are valid for $x \in [x_i, x_{i+1}]$:

$$1. \quad |e_j| \leq \frac{1}{12} H_j^2 (x_j - x_0) \|g'''\|_{0j} \quad \text{with } H_j = \max\{h_i; i \leq j\};$$

$$2. \quad |e(x)| \leq \frac{1}{12} H_{j+1}^2 (x_{j+1} - x_0) \|g'''\|_{0,j+1} + \frac{2}{81} h_j^3 \|g'''\|_j;$$

$$3. \quad |e'(x)| \leq \frac{1}{8} h_j^2 \|g'''\|_j \leq \frac{1}{8} H_j^2 \|g'''\|_{0,j+1};$$

$$4. \quad |e''(x)| \leq \frac{1}{2} h_j [\|g'''\|_j + \omega_j(g''', h_j)] \leq \\ \leq \frac{1}{2} H_j [\|g'''\|_{0,j+1} + \omega_{0j}(g''', H_j)],$$

where $\|\cdot\|$ denotes the maximum norm, $\|\cdot\|_1$ and ω_1 the maximum norm and modulus of continuity with respect to the interval $[x_i, x_{i+1}]$, $\|\cdot\|_{0j}$ and ω_{0j} - with respect to the interval $[x_0, x_j]$.

Proof

1. Adding (4) with $i=0(1)j-1$, we obtain

$$s_j - s_0 = \frac{1}{2} \sum_{i=0}^{j-1} h_i (m_i + m_{i+1})$$

Using the trapezoidal rule of numerical integration with known error term we have

$$g_j - g_0 = \int_{x_0}^{x_j} g'(x) dx = \frac{1}{2} \sum_{i=0}^{j-1} h_i (m_i + m_{i+1}) - \frac{1}{12} \sum_{i=0}^{j-1} h_i^3 g'''(z_i),$$

with $z_i \in [x_i, x_{i+1}]$. As $s_0 = g_0$, we obtain by subtraction

$$g_j - s_j = - \frac{1}{12} \sum_{i=0}^{j-1} h_i^3 g'''(z_i)$$

and then

$$|e_j| \leq \frac{1}{12} H_j^2 \|g'''\|_{0j} \sum_{i=0}^{j-1} h_i = \frac{1}{12} (x_j - x_0) H_j^2 \|g'''\|_{0j}$$

follows.

2. Using the Hermite interpolation and its error term for the function $g(x)$, we can write with $t=(x-x_i)/h_i \in [0,1]$

$$(6) \quad g(x) = (1-t^2)g_j + t^2 g_{j+1} + h_j t(1-t)m_j + \frac{1}{6} g'''(z_i)(x-x_i)^2(x-x_{i+1}),$$

$x, z_i \in [x_i, x_{i+1}].$

For the error $e(x)=g(x)-s(x)$ we obtain then

$$e(x) = (1-t^2)e_j + t^2 e_{j+1} + \frac{1}{6} g'''(z_i)(x-x_i)^2(x-x_{i+1}).$$

So, for $x \in [x_j, x_{j+1}]$ we have

$$|e(x)| \leq \max\{|e_j|, |e_{j+1}|\} + \frac{1}{6} h_j^3 |t^3 - t^2| \|g'''\|_j \leq$$

$$\leq \max\{|e_j|, |e_{j+1}|\} + \frac{2}{81} h_j^3 \|g'''\|_j$$

With the help of the proved first assertion of our theorem we get

$$|e(x)| \leq \frac{1}{12} |x_{j+1} - x_0| H_{j+1} \|g'''\|_{0,j+1} + \frac{2}{81} h_j^3 \|g'''\|_j$$

3. The derivatives $s'(x), g'(x)$ for $x \in [x_j, x_{j+1}]$ can be expressed as

$$(7) \quad s'(x) = (1-t)m_j + t m_{j+1},$$

$$g'(x) = (1-t)m_j + t m_{j+1} + \frac{1}{2} g'''(z_j)(x-x_j)(x-x_{j+1}).$$

Subtracting the equalities in (7),

$$|g'(x) - s'(x)| = |e'(x)| \leq \frac{1}{2} (x - x_j)(x_{j+1} - x) |g'''(z_j)| \leq \\ \leq \frac{1}{8} h_j^2 \|g'''\|_j \leq \frac{1}{8} H_j^2 \|g'''\|_{0,j+1}$$

follows.

4. The Taylor's expansion of g'_{j+1} gives

$$g'_{j+1} = m_{j+1} = m_j + h_j g'_j + \frac{1}{2} h_j^2 g''(y_j), \quad y_j \in [x_j, x_{j+1}];$$

we have then

$$(m_{j+1} - m_j) / h_j = g'_j + \frac{1}{2} h_j g''(y_j).$$

For the second derivatives $s''(x)$, $g''(x)$, $x \in [x_j, x_{j+1}]$,

$$s''(x) = (m_{j+1} - m_j) / h_j = g'_j + \frac{1}{2} h_j g''(y_j), \\ g''(x) = g'_j + h_j g'''(z_j)$$

hold.

The error $e(x)$ obeys then the relation

$$e''(x) = g''(x) - s''(x) = h_j [g'''(z_j) - \frac{1}{2} g''(y_j)] = \\ = \frac{1}{2} h_j [g'''(z_j) + g'''(z_j) - g''(y_j)].$$

Using local modulus of continuity $\omega_1(g''', h_j)$, we obtain the estimate

$$|e''(x)| \leq \frac{1}{2} h_j [\|g'''\|_j + \omega_1(g''', h_j)]$$

2. Separated mesh $(\Delta x \Delta t)$

2.1 Spline representation

Let us consider the mesh with separated spline knots x_i and points of interpolation t_i

$$(\Delta x \Delta t) = x_0 \leq t_0 < x_1 < t_1 < \dots < t_n \leq x_{n+1} \quad \text{with} \quad h_i = x_{i+1} - x_i, \quad d_i = (t_i - x_i) / h_i.$$

Quadratic spline $s(x)$ over the interval $[x_i, x_{i+1}]$ can be expressed as

$$(8) \quad s(x) = A(t) s_i + B(t) s_{i+1} + h_i C(t) m_i, \\ t = (x - x_i) / h_i, \quad s_i = s(x_i), \quad m_i = s'(t_i),$$

where

$$A(t) = (t^2 - 2td_1) / (2d_1 - 1) = -B(t) + 1,$$

$$B(t) = -t(t - 2d_1) / (2d_1 - 1),$$

$$C(t) = t(t - 1) / (2d_1 - 1)$$

in case of $d_1 \neq \frac{1}{2}$, $i=0(1)n$. It can be uniquely determined

a) by the conditions of interpolation of derivatives

$$m_i = s'(t_i), \quad i=0(1)n;$$

b) by two boundary conditions $s(x_0) = s_0$, $s(x_{n+1}) = s_{n+1}$.

In case $d_1 = \frac{1}{2}$, $i=0(1)n$, with $s'_i = s'(x_i)$ we can write

$$(9) \quad s(x) = s_1 + s'_1(x - x_1) + (s'_{i+1} - s'_1)(x - x_1)^2 / (2h_1)$$

Such a spline is uniquely determined

a) by the conditions of interpolation of derivatives

$$m_i = s'(t_i), \quad i=0(1)n,$$

b) by initial values $s(x_0) = s_0$, $s'(x_0) = s'_0$ (see [1], [2]).

2.2 Error estimate in case $d_1 = \frac{1}{2}$, $i=0(1)n$

Let the values $m_i = s'(t_i)$, $i=0(1)n$, s_0 , s'_0 be given.

Denote $s_i = s(x_i)$, $s'_i = s'(x_i)$, $g_i = g(x_i)$, $g'_i = g'(x_i)$; $H_j = \max\{h_i; i < j\}$.

Suppose that $g \in C^3[x_0, x_{n+1}]$, $g'(t_i) = m_i$, $g(x_0) = s_0$, $g'(x_0) = s'_0$.

There are simple relations between quantities m_j, s_j, s'_j :

$$(10) \quad m_i = \frac{1}{2}(s'_i + s'_{i+1}), \quad s_{i+1} - s_i = h_i m_i, \quad i=0(1)n.$$

1° Summing the last equalities we obtain

$$(11) \quad s_j - s_0 = \sum_{i=0}^{j-1} h_i m_i = \sum_{i=0}^{j-1} h_i s'(t_i).$$

On the other hand - by midpoint rule of numerical integration with known remainder term - we have

$$(12) \quad \int_{x_0}^{x_j} g'(x) dx = g_j - g_0 = \sum_{i=0}^{j-1} h_i m_i + \frac{1}{24} \sum_{i=0}^{j-1} h_i^3 g'''(z_i)$$

with some $z_i \in [x_i, x_{i+1}]$. Subtracting (11) from (12) we obtain

for the error $e(x)=g(x)-s(x)$ the relation

$$e_j = \frac{1}{24} \sum_{i=0}^{j-1} h_i^3 g'''(z_i) ,$$

and finally the estimate

$$(13) \quad |e_j| \leq \frac{1}{24} H_j^2(x_j-x_0) \|g'''\|_{0j} .$$

2° From Taylor's expansion of g' at $x=t_1$ we have

$$g'_{i+1} + g'_i = 2g'(t_1) + \frac{1}{4} h_1^2 g''(z_1) .$$

Following (10), there is also $s'_{i+1} + s'_i = 2m_1$.

Subtracting these relations, the recurrence relation

$$e'_{i+1} + e'_i = \frac{1}{4} h_1^2 g''(z_1)$$

and the inequality

$$|e'_{i+1}| < |e'_i| + \frac{1}{4} h_1^2 |g''(z_1)|$$

follow .

By induction, using $e'_0=0$, we obtain the estimates

$$(14) \quad |e'_j| \leq \frac{1}{4} \sum_{i=0}^{j-1} h_i^2 |g''(z_i)| \leq \frac{1}{4} H_j(x_j-x_0) \|g''\|_{0j} .$$

3° We have further (with $\tau_1, \eta_1 \in [x_1, x_{i+1}]$)

$$g'_i = g'(t_1) - \frac{1}{2} h_1 g''(t_1) + \frac{1}{8} h_1^2 g'''(\tau_1) , \quad s''(t_1) = s'_i ,$$

$$g''(t_1) = g'_i + \frac{1}{2} h_1 g'''(\eta_1) , \quad s'_i = m_1 - \frac{1}{2} h_1 s''(t_1) .$$

Then

$$\begin{aligned} g'_i - s'_i &= \frac{1}{2} h_1 (s'_i - g'_i) - \frac{1}{4} h_1^2 g'''(\eta_1) + \frac{1}{8} h_1^2 g'''(\tau_1) = \\ &= \frac{1}{2} h_1 (s'_i - g'_i) - \frac{1}{8} h_1^2 [2g'''(\eta_1) - g'''(\tau_1)] , \end{aligned}$$

and

$$s'_i - g'_i = \frac{2}{h_1} (g'_i - s'_i) + \frac{1}{4} h_1 [g'''(\eta_1) + g'''(\eta_1) - g'''(\tau_1)] .$$

With the local modulus of continuity $\omega_1(g''', h_1)$ we can write the recurrent estimate

$$|e'_i| \leq \frac{2}{h_1} |e'_i| + \frac{1}{4} h_1 [\|g'''\|_i + \omega_1(g''', h_1)] .$$

Substitute the estimate (14), we obtain

$$|e'_i| \leq \frac{1}{2} (H_j/h_1)(x_i-x_0) \|g'''\|_{0i} + \frac{1}{4} h_1 [\|g'''\|_i + \omega_1(g''', h_1)] .$$

4° For the function values $s(x)$, $g(x)$ with $x \in [x_1, x_{i+1}]$ we have the expansions ($\delta_1 \in [x_1, x_{i+1}]$)

$$s(x) = s_1 + s'_1(x-x_1) + (s'_{i+1} - s'_1)(x-x_1)^2 / (2h_1) ,$$

$$g(x) = g_1 + g'_1(x-x_1) + \frac{1}{2} g''_1(x-x_1)^2 + \frac{1}{6} g'''_1(\delta_1)(x-x_1)^3 .$$

For the error $e(x) = g(x) - s(x)$ then the relations

$$e(x) = e_1 + (x-x_1)e'_1 + \frac{1}{2}(x-x_1)^2 [g''_1 - (s'_{i+1} - s'_1)/h_1] + \frac{1}{6} g'''_1(\delta_1)(x-x_1)^3 ,$$

$$|e(x)| \leq |e_1| + h_1 |e'_1| + \frac{1}{2} h_1^2 |e''_1| + \frac{1}{6} h_1^3 \|g''''_1\|_1$$

follow .

Substituting for $|e_1|$, $|e'_1|$, $|e''_1|$ from (13)-(15), we finally obtain the estimate

$$\begin{aligned} (16) \quad |e(x)| &\leq \frac{1}{24} H_1^2(x_1-x_0) \|g''''_1\|_{01} + \frac{1}{2} h_1 H_1(x_1-x_0) \|g''''_1\|_{01} + \\ &\quad + \frac{1}{2} h_1^2 \frac{1}{4} h_1 \{ \|g''''_1\|_1 + \omega_1(g''''_1, h_1) \} + \frac{1}{6} h_1^3 \|g''''_1\|_1 = \\ &= \frac{1}{2} H_1(x_1-x_0) \|g''''_1\|_{01} \left\{ \frac{1}{12} H_1 + h_1 \right\} + \frac{1}{8} h_1^3 \left[\frac{7}{3} \|g''''_1\|_1 + \omega_1(g''''_1, h_1) \right] . \end{aligned}$$

We summarize our discussion from 2.2 in the following theorem.

Theorem 2

Let the function $g(x) \in C^3[x_0, x_{n+1}]$ and $s(x)$ be the quadratic spline interpolating the derivatives $m_i = g'(t_i)$ on the mesh $(\Delta x \Delta t)$ with $d_i = \frac{1}{2}$, $i=0(1)n$ described by (9).

Then the following estimates for $e(x) = g(x) - s(x)$ hold:

1. $|e_j| \leq \frac{1}{24} H_j^2(x_j-x_0) \|g''''_j\|_{0j} ;$
2. $|e'_j| \leq \frac{1}{4} H_j(x_j-x_0) \|g''''_j\|_{0j} ;$
3. $|e''_j| \leq \frac{1}{2} (H_j/h_j)(x_j-x_0) \|g''''_j\|_{0j} + \frac{1}{4} h_j \{ \|g''''_j\|_j + \omega_j(g''''_j, h_j) \};$
4. $|e(x)| \leq \frac{1}{2} H_j(x_j-x_0) \|g''''_j\|_{0j} \left(\frac{1}{12} H_j + h_j \right) + \frac{7}{24} h_j^3 \|g''''_j\|_j + \frac{1}{8} h_j^3 \omega_j(g''''_j, h_j) .$

(with notation used in Theorem 1).

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