

Albert Nijenhuis

Vector form brackets in Lie algebroids

Archivum Mathematicum, Vol. 32 (1996), No. 4, 317--323

Persistent URL: <http://dml.cz/dmlcz/107584>

Terms of use:

© Masaryk University, 1996

Institute of Mathematics of the Academy of Sciences of the Czech Republic provides access to digitized documents strictly for personal use. Each copy of any part of this document must contain these *Terms of use*.



This paper has been digitized, optimized for electronic delivery and stamped with digital signature within the project *DML-CZ: The Czech Digital Mathematics Library* <http://project.dml.cz>

VECTOR FORM BRACKETS IN LIE ALGEBROIDS

ALBERT NIJENHUIS

To Ivan Kolář, on the occasion of his 60th birthday.

ABSTRACT. A brief exposition of Lie algebroids, followed by a discussion of vector forms and their brackets in this context - and a formula for these brackets in “deformed” Lie algebroids.

1. Introduction

The sections in the tangent bundle of a (smooth) manifold can be defined as the derivations on the ring of (smooth) functions on the manifold, and thus are seen to form a Lie algebra. A *Lie algebroid* [3] is a direct generalization: it consists of a triple, say $(A, [,]^A, a)$, where A is a vector bundle over a base manifold, say B , and $[,]^A$ is a Lie algebra product on $\Gamma(A)$, the (smooth) section in A . Further, $a : A \rightarrow TB$, the *anchor*, is a bundle map to the tangent bundle of B , which establishes a homomorphism between the Lie algebras $\Gamma(A)$ and $\Gamma(TB)$:

$$a([u, v]^A) = [au, av], \quad u, v \in \Gamma(A),$$

and satisfies the product rule

$$[u, fv]^A = f[u, v]^A + (a(u) \cdot f)v$$

where $f \in F$ (the ring of functions on B).

Given a Lie algebroid A and its dual bundle A^* , all tensor bundles can be constructed as a straightforward generalization of the structures based on TB and T^*B . This note shows some less obvious constructions.

Part of the material in this note was included in a talk at the Pacific Northwest Geometry Seminar, Corvallis, OR, U.S.A., on November 9, 1996.

2. A handy notation. [4] Denote by $S_{m,n}$ the set of (m, n) -shuffles, that is, the permutations $\sigma = (i_1, \dots, i_{m+n})$ of $m + n$ symbols such that $i_1 < \dots < i_m$ and $i_{m+1} < \dots < i_{m+n}$. (Any other selection from the cosets $S_{m+n}/S_m \times S_n$

1991 *Mathematics Subject Classification*: 17B66, 17B70.

Key words and phrases: vector valued form, Lie algebroid.

will serve equally well.) Let $\sigma = (\sigma_1, \sigma_2)$, where $\sigma_1 = (i_1, \dots, i_m)$ and $\sigma_2 = (i_{m+1}, \dots, i_{m+n})$. Let V be a vector space, and α, β multilinear maps of V to V , say $\alpha \in \text{Hom}(\bigwedge^a V, V)$ $\beta \in \text{Hom}(\bigwedge^b V, V)$, then define $\alpha \bar{\wedge} \beta \in \text{Hom}(\bigwedge^{a+b-1} V, V)$ by

$$(2.1) \quad (\alpha \bar{\wedge} \beta)(v_1, \dots, v_{a+b-1}) = \sum_{(\sigma_1, \sigma_2) \in S_{b, a-1}} \text{sgn}(\sigma_1, \sigma_2) \alpha(\beta(v_{\sigma_1}), v_{\sigma_2}).$$

It is well known that, for $\gamma \in \text{Hom}(\bigwedge^c V, V)$ we have

$$(2.2) \quad (\alpha \bar{\wedge} \beta) \bar{\wedge} \gamma - \alpha \bar{\wedge} (\beta \bar{\wedge} \gamma) = (-1)^{(b-1)(c-1)} ((\alpha \bar{\wedge} \gamma) \bar{\wedge} \beta - \alpha \bar{\wedge} (\gamma \bar{\wedge} \beta)),$$

while, if $\alpha \in \text{Hom}(V, V)$ then both sides of (2.2) vanish.

Based on $\bar{\wedge}$ we define a commutator bracket;

$$(2.3) \quad [\alpha, \beta]^{\bar{\wedge}} = \alpha \bar{\wedge} \beta - (-1)^{(a-1)(b-1)} \beta \bar{\wedge} \alpha.$$

It is easy to show that $[\cdot, \cdot]^{\bar{\wedge}}$ defines a graded Lie algebra structure with reduced grading:

$$(2.4) \quad \sum_{cycl} (-1)^{(c-1)(a-1)} [[\alpha, [\beta, \gamma]^{\bar{\wedge}}]^{\bar{\wedge}}] = 0.$$

Our application is to the case when $V = \Gamma(A) \oplus F$; i.e., when the entries in α, β , etc. are sections in a Lie algebroid A or functions on the base space, or formal sums of the two. In the latter case, the linearity permits a decomposition of $\alpha(v_1, \dots, v_a)$ into pure terms, in which each entry is either a section in A or a function.

Each A -(differential) form or A -vector form ω is identified with an element of $\text{Hom}(\bigwedge V, V)$, also denoted ω , which takes the same values when evaluated on A -sections, and vanishes when any one entry is a function. As a result, all expressions of the form $L \bar{\wedge} \omega$ vanish when L is an A -form or a A -vector form and ω an A -form.

The structure of Lie algebroid is incorporated in an element $\mu \in \text{Hom}(\bigwedge^2 V, V)$, the multiplication map, as follows. (It is not a vector form!)

$$(2.5) \quad \begin{aligned} \mu(u, v) &= [u, v]^A \quad \text{for } u, v \in \Gamma(A); \\ \mu(u, f) &= -\mu(f, u) = a(u) \cdot f \quad \text{for } u \in \Gamma(A), f \in F; \end{aligned}$$

where a is the anchor. Finally, $\mu(f, g) = 0$ for $f, g \in F$.

Lemma 1. *If μ is the multiplication map of a Lie algebroid, then $[\mu, \mu]^{\bar{\wedge}} = 0$ and $\mu(u, fv) = f\mu(u, v) + \mu(u, f)v$. Conversely, if $[\cdot, \cdot]^A$ is any alternating product on $\Gamma(A)$, $a : A \rightarrow TB$ any bundle map, μ defined by (3.5) and $[\mu, \mu]^{\bar{\wedge}} = 0$, then $(A, [\cdot, \cdot]^A, a)$ is a Lie algebroid with multiplication μ .*

We may write (A, μ) instead of $(A, [\cdot, \cdot]^A, a)$.

Proof. There are three cases to be considered for the first formula, depending on how many of the variables in $[\mu, \mu]^{\bar{\wedge}}(\dots)$ are A -sections and how many are functions. Note that $[\mu, \mu]^{\bar{\wedge}} = 2\mu \bar{\wedge} \mu$.

$$(\mu \bar{\wedge} \mu)(u, v, w) = \sum_{cycl} \mu(\mu(u, v), w) = \sum_{cycl} [[u, v]^A, w]^A = 0,$$

$$\begin{aligned} (\mu \bar{\wedge} \mu)(u, v, f) &= \mu(\mu(u, v), f) + \mu(\mu(v, f), u) + \mu(\mu(f, u), v) \\ &= \mu([u, v]^A, f) + \mu(a(v) \cdot f, u) + \mu(-a(u) \cdot f, v) \\ &= a([u, v]^A) \cdot f - a(u) \cdot a(v) \cdot f + a(v) \cdot a(u) \cdot f \\ &= a([u, v]^A) \cdot f - [a(u), a(v)] \cdot f = 0, \end{aligned}$$

Finally, $\mu \bar{\wedge} \mu(\dots)$ is easily seen to vanish when two or more of the variables are functions.

The second formula is just a re-write of the product rule in a Lie algebroid. \square

Consider an A -form $\omega \in \Gamma(\bigwedge^p A^*)$, then for its A -exterior derivative we find

$$\begin{aligned} (d^A \omega)(u_0, \dots, u_p) &= \sum_{i=0}^p (-1)^i a(u_i) \cdot \omega(u_0, \dots, \hat{i}, \dots, u_p) \\ &\quad + \sum_{i < j} (-1)^{i+j} \omega([u_i, u_j]^A, u_0, \dots, \hat{i}, \dots, \hat{j}, \dots, u_p) \\ &= \sum_{i=0}^p (-1)^i \mu(u_i, \omega(u_0, \dots, \hat{i}, \dots, u_p)) \\ &\quad + \sum_{i < j} (-1)^{i+j} \omega(\mu(u_i, u_j), u_0, \dots, \hat{i}, \dots, \hat{j}, \dots, u_p) \\ &= (-1)^{p+1} (\mu \bar{\wedge} \omega)(u_0, \dots, u_p) - (\omega \bar{\wedge} \mu)(u_0, \dots, u_p) \\ &= -[\omega, \mu]^{\bar{\wedge}}(u_0, \dots, u_p). \end{aligned}$$

We have just shown

Lemma 2. $d^A \omega = -[\omega, \mu]^{\bar{\wedge}}$.

The Jacobi identity (2.4) easily implies that $(d^A)^2 = 0$.

3. Derivations on differential forms. The classical theory of derivations on the graded ring of differential forms (i.e., the case of the standard tangent Lie algebroid), see [1], states that every derivation is uniquely a sum of one of type i_* and one of type d_* . A derivation is of type i_* if it vanishes on functions, and is of the form $\omega \mapsto i_L \omega = \omega \bar{\wedge} L$, where L is a vector form, $L \in \Gamma(TB \otimes \bigwedge T^*B)$, and it is of type d_* if it commutes with the exterior derivative d ; in this case it is of the form $\omega \mapsto d_L \omega = [i_L, d] = (i_L d + (-1)^q d i_L) \omega$, where $L \in \Gamma(TB \otimes \bigwedge^q T^*B)$.

In a general Lie algebroid A the A -forms also admit derivations of types i_*^A (the same as i_* above), and d_*^A (in obvious generalization of the above), but these need not span all derivations.

For example, consider the Lie algebroid A with bundle space TB but trivial bracket and anchor. Then the classical d is a derivation, but is not a sum of derivations of types i_*^A and d_*^A , because the first vanish on functions, and the second are trivial (zero).

The commutator relations for derivations of types i_* and d_* for the standard tangent Lie algebroid are (see [1])

$$(3.1) \quad [i_L, i_M] = i_{[M, L]} \bar{\wedge};$$

$$(3.2) \quad [i_L, d_M] = d_M \bar{\wedge} L + (-1)^m i_{[L, M]};$$

$$(3.3) \quad [d_L, d_M] = d_{[L, M]}.$$

We generalize these formulas to Lie algebroids, as follows. (3.1) is “the same” (see above); (3.2) is seen as a definition of $[L, M]$, and requires a proof that $[i_L, i_M] - d_M \bar{\wedge} L$ is indeed of type i_*^A . Then (3.3) easily follows from (3.2) as a consequence of the Jacobi identity for derivations.

In what follows, the A for Lie algebroids has been suppressed in the formulas. – Define $\mu(L, M)$ by

$$(3.4) \quad \mu(L, M)(u_1, \dots, u_{q+m}) = \sum_{(\sigma_1, \sigma_2) \in S_{q, m}} \text{sgn}(\sigma_1, \sigma_2) \mu(L(u_{\sigma_1}), M(u_{\sigma_2})).$$

Note that $\mu(L, M)$, though not an A -vector form, vanishes if any one entry is a function; in particular, $\mu(L, M) \bar{\wedge} \omega = 0$ for A -forms ω .

Lemma 3. *We have the following*

$$(3.5) \quad \mu(L, M) = (-1)^{q(m-1)} ((\mu \bar{\wedge} L) \bar{\wedge} M - \mu \bar{\wedge} (L \bar{\wedge} M));$$

$$(3.6) \quad d_L \omega = (-1)^{q+1} \omega \bar{\wedge} [L, \mu] \bar{\wedge} + (-1)^{p q + q} (\mu \bar{\wedge} L) \bar{\wedge} \omega;$$

$$(3.7) \quad [M \bar{\wedge} L, \mu] \bar{\wedge} = M \bar{\wedge} [L, \mu] \bar{\wedge} - (-1)^q [M, \mu] \bar{\wedge} \bar{\wedge} L + (-1)^{q+1} \mu(L, M);$$

$$(3.8) \quad [\omega \bar{\wedge} L, \mu] \bar{\wedge} = \omega \bar{\wedge} [L, \mu] \bar{\wedge} - (-1)^q [\omega, \mu] \bar{\wedge} \bar{\wedge} L + (-1)^{q p + 1} (\mu \bar{\wedge} L) \bar{\wedge} \omega.$$

Proof. For (3.5) see page 104 of [4]. (Note that the proof of (2.2) in [1] contains two canceling errors, and would give an incorrect sign in (3.5).) The other formulas require simple calculations using the definitions and (2.2). □

Theorem 1. *The derivations of types i_* and d_* in a Lie algebroid satisfy (3.1-3). The bracket $[L, M]$ is given by*

$$(3.9) \quad [L, M] = \mu(L, M) + (-1)^{m(q-1)} L \bar{\wedge} [M, \mu]^{\bar{\wedge}} + (-1)^{q+1} M \bar{\wedge} [L, \mu]^{\bar{\wedge}}.$$

Proof. In the following calculations, the $\bar{\wedge}$ on $[\cdot, \cdot]^{\bar{\wedge}}$ will be suppressed. Use Lemma 3.

$$\begin{aligned} & (-1)^m [i_L, d_M] \omega - (-1)^m d_L \bar{\wedge} M \omega \\ &= (-1)^m (d_M \omega) \bar{\wedge} L - (-1)^{qm} d_M (\omega \bar{\wedge} L) - (-1)^m d_M \bar{\wedge} L \omega \\ &= (-1)^m ((-1)^{m+1} \omega \bar{\wedge} [M, \mu] + (-1)^{m(p-1)} (\mu \bar{\wedge} M) \bar{\wedge} \omega) \bar{\wedge} L \\ &\quad - (-1)^{qm} ((-1)^{m+1} (\omega \bar{\wedge} L) \bar{\wedge} [M, \mu] + (-1)^{(p+q)m} (\mu \bar{\wedge} M) \bar{\wedge} (\omega \bar{\wedge} L)) \\ &\quad - (-1)^m ((-1)^{q+m} \omega \bar{\wedge} [M \bar{\wedge} L, \mu] + (-1)^{(p-1)(q+m-1)} (\mu \bar{\wedge} (M \bar{\wedge} L)) \bar{\wedge} \omega). \end{aligned}$$

We first combine the first terms in each line.

$$\begin{aligned} & - (\omega \bar{\wedge} [M, \mu]) \bar{\wedge} L - (-1)^{qm+p+q} (\omega \bar{\wedge} L) \bar{\wedge} [M, \mu] - (-1)^q \omega \bar{\wedge} [M \bar{\wedge} L, \mu] \\ &= -(\omega \bar{\wedge} [M, \mu]) \bar{\wedge} L \\ &\quad + ((-1)^{(q-1)m} (\omega \bar{\wedge} (L \bar{\wedge} [M, \mu] + (\mu \bar{\wedge} [M, \mu]) \bar{\wedge} L - \omega \bar{\wedge} ([M, \mu] \bar{\wedge} L)) \\ &\quad - (-1)^q \omega \bar{\wedge} (M \bar{\wedge} [L, \mu] - (-1)^q [M, \mu] \bar{\wedge} L + (-1)^{q+1} \mu(L, M)) \\ &= \omega \bar{\wedge} ((-1)^{(q-1)m} L \bar{\wedge} [M, \mu] + (-1)^{q+1} M \bar{\wedge} [L, \mu] + \mu(L, M)). \end{aligned}$$

This proves (3.9), after we show the vanishing of the remaining terms:

$$\begin{aligned} & (-1)^{pm} (((\mu \bar{\wedge} M) \bar{\wedge} \omega) \bar{\wedge} L - (\mu \bar{\wedge} M) \bar{\wedge} (\omega \bar{\wedge} L) \\ &\quad + (-1)^{(p-1)(q-1)} (\mu \bar{\wedge} (M \bar{\wedge} L)) \bar{\wedge} \omega) \\ &= (-1)^{pm} (-(\mu \bar{\wedge} M) \bar{\wedge} (L \bar{\wedge} \omega) + (-1)^{(p-1)(q-1)} (((\mu \bar{\wedge} M) \bar{\wedge} L) \bar{\wedge} \omega \\ &\quad - (\mu \bar{\wedge} (M \bar{\wedge} L)) \bar{\wedge} \omega)) = 0 + (-1)^{pm+(p+m-1)(q-1)} \mu(M, L) \bar{\wedge} \omega = 0. \end{aligned}$$

□

4. The “deformed” Lie algebroid. [2] The operator i_L , so far defined as acting on $\Gamma(\wedge A^*)$, is extended to act on $\text{Hom}(\wedge V, V)$ (V as defined in section 2) in the case when L is an A -vector 1-form. In that case we prefer the notation h , k , etc. over L , etc., and set

$$(4.1) \quad i_h \alpha = \alpha \bar{\wedge} h - h \bar{\wedge} \alpha.$$

According to (2.2) and the line following, i_h satisfies a product rule with respect to $\bar{\wedge}$:

$$i_h (\alpha \bar{\wedge} \beta) = (i_h \alpha) \bar{\wedge} \beta + \alpha \bar{\wedge} i_h \beta.$$

If A is a Lie algebroid with multiplication μ , and h an A -vector 1-form, a new, *deformed* multiplication μ_h is given by

$$\mu_h(u, v) = \mu(hu, v) + \mu(u, hv) - h\mu(u, v),$$

i.e., by $\mu_h = i_h\mu$. (This implies (see (2.5)) that a *deformed* anchor map a_h is given by $a_h(u) = a(hu)$.) In general, μ_h does not define a Lie algebroid structure on the bundle space A .

Lemma 4. *If $[h, h] = 0$ then μ_h defines a Lie algebroid structure (A, μ_h) , and h is a homomorphism to (A, μ) .*

Proof. The product rule $\mu_h(u, fv) = \dots$ follows by a simple calculation, using just the F -linearity of h and the fact that h acts trivially on functions.

Again, we suppress the $\bar{\wedge}$ on $[\cdot, \cdot]^{\bar{\wedge}}$ below. The formula (3.9) with $L = M = h$, and the observation that $\mu(h, h)(u, v) = 2\mu(hu, hv)$, yields

$$\mu(hu, hv) = -h \bar{\wedge} [h, \mu](u, v) = h\mu_h(u, v),$$

so h gives the homomorphism of μ_h to μ .

Formulas (3.7) and (3.9), with $L = M = h$, using $[h, \mu] = -i_h\mu = -\mu_h$ give rise to

$$[h^2, \mu] = -h \bar{\wedge} \mu_h - \mu_h \bar{\wedge} h + \mu(h, h), \quad 0 = \mu(h, h) - 2h \bar{\wedge} \mu_h.$$

Elimination of $\mu(h, h)$ by subtraction yields $[h^2, \mu] = -[h, \mu_h]$. Bracketing with μ , combined with the product rule for i_h yields

$$[\mu, [h^2, \mu]] = -[\mu, i_h\mu_h] = -i_h[\mu, \mu_h] + [i_h\mu, \mu_h] = i_h[\mu, [h, \mu]] + [\mu_h, \mu_h].$$

Now, $[\mu, [\mu, k]] = -\frac{1}{2}[k, [\mu, \mu]] = 0$ for any vector 1-form k (Jacobi identity), so we find $[\mu_h, \mu_h] = 0$. Hence, μ_h satisfies the Jacobi identity. \square

Given a Lie algebroid (A, μ) and a deformed Lie algebroid (A, μ_h) , we define $[L, M]_h$, the A -vector form bracket with respect to μ_h by replacing in (3.9) all μ by μ_h . (Formulas (3.1-3) will then be valid, after the same substitution, see Lemma 2.)

Theorem 2. *Let $[L, M]_h$ denote the vector form bracket in a deformed Lie algebroid (A, μ_h) , then*

$$(4.2) \quad [L, M]_h = i_h[L, M] - [i_hL, M] - [L, i_hM].$$

Proof. Let $P(X, Y, \dots)$ be a polynomial, linear in each of X, Y, \dots , with $X, Y, \dots \in \text{Hom}(\bigwedge V, V)$, and with the (non-commutative, non-associative) product $\bar{\wedge}$, with respect to which i_h is a derivation, then

$$i_hP(X, Y, \dots) = P(i_hX, Y, \dots) + P(X, i_hY, \dots) + \dots$$

Apply this to $P(L, M, \mu) = [L, M]$ (see (3.9)), and observe that

$$[L, M]_h = P(L, M, i_h\mu).$$

The result follows immediately. \square

REFERENCES

The following articles contain suitable introductions to the relevant topics, as well as references to further information.

- [1] Frölicher, A., Nijenhuis, A., *Theory of vector-valued differential forms, Part I.*, Kon. Nederl. Akad. Wetensch. Proc. **A 59** (= Indag. Math. **18**), 338-359 (1956).
- [2] Kosmann-Schwarzbach, Y., Magri, F., *Poisson-Nijenhuis structures*, I Ann. Inst. Henri Poincaré **53**, 35-81 (1990).
- [3] Mackenzie, K., Ping Xu, *Lie bialgebroids and Poisson groupoids*, Duke Math. J. **73**, 415-452 (1994).
- [4] Nijenhuis, A., Richardson, R.W., *Deformations of Lie algebra structures*, J. Math. Mech. **17**, 89-105 (1967).

DEPARTMENT OF MATHEMATICS
UNIVERSITY OF WASHINGTON
SEATTLE WA 98195, U.S.A.
E-mail: nijenhuis@math.washington.edu