

František Neuman

Some results on geometrical approach to linear differential equations of the  $n$ -th order (Preliminary communication)

*Commentationes Mathematicae Universitatis Carolinae*, Vol. 12 (1971), No. 2, 307--315

Persistent URL: <http://dml.cz/dmlcz/105346>

## Terms of use:

© Charles University in Prague, Faculty of Mathematics and Physics, 1971

Institute of Mathematics of the Academy of Sciences of the Czech Republic provides access to digitized documents strictly for personal use. Each copy of any part of this document must contain these *Terms of use*.



This paper has been digitized, optimized for electronic delivery and stamped with digital signature within the project *DML-CZ: The Czech Digital Mathematics Library* <http://project.dml.cz>

SOME RESULTS ON GEOMETRICAL APPROACH TO LINEAR DIFFERENTIAL  
EQUATIONS OF THE n-TH ORDER

F. NEUMAN, Brno

(Preliminary communication)

Let  $\underline{y}(t) = (y_1(t), \dots, y_m(t)) \in E_m$  ( $m \geq 1$ ) for  
 $t \in I$ ,  $|\underline{y}(t)| = \sqrt{\sum_{i=1}^m y_i^2(t)}$ ; let  $S_{m-1} = \{\underline{c} \in E_m; |\underline{c}| = 1\}$   
be the unit sphere in  $E_m$ . Denote by  $\pi(\underline{y}(t)) =$   
 $= \underline{y}(t)/|\underline{y}(t)|$ . For  $\underline{y} \in C^k(I)$ ,  $k \geq 1$ ,  $j \leq k$ , put  
 $d^j \underline{y}(t)/dt^j = (d^j y_1(t)/dt^j, \dots, d^j y_m(t)/dt^j)$ .

Let  $x: I \rightarrow J$ ,  $x \in C^1(I)$ ,  $dx(t)/dt \neq 0$  for  
all  $t \in I$ . Then define  $T_x \underline{y} = \underline{z}$ , where  $x_i(x(t)) =$   
 $= y_i(t)$  for all  $t \in I$ ,  $i = 1, \dots, m$ . Denote by

$[\underline{u}_1, \dots, \underline{u}_m]$  the determinant whose  $i$ -th column is  $\underline{u}_i$ .

Let  $W_m(\underline{y}(t)) = [\underline{y}(t), d\underline{y}(t)/dt, \dots, d^{m-1}\underline{y}(t)/dt^{m-1}]$

for  $\underline{y} \in C^{m-1}(I)$ . If  $\underline{y} \in C^1(I)$ ,  $\underline{v} = \pi(\underline{y})$ ,

$|d\underline{v}(t)/dt| \neq 0$  for all  $t \in I$ ,  $t_0 \in I$ ,

$\rho = (t \mapsto \int_{t_0}^t |d\underline{v}(\sigma)/d\sigma| \cdot d\sigma)$ ,  $\rho: I \rightarrow J$ ,  $T_{\rho} \underline{v}(t) = \underline{u}(\rho)$ ,

then  $|d\underline{u}(\rho)/d\rho| = 1$ . Denote the  $T_{\rho}$  by  $\tau_{\rho, t_0}$ .

Obviously  $\underline{u}(\rho) = \tau_{\rho, t_0} \pi(\underline{y}(t)) \in S_{m-1}$  and

$d\underline{u}(\rho)/d\rho \in S_{m-1}$  for all  $\rho \in J$ ,  $0 \in J$  and

$\underline{u}(0) = \underline{y}(t_0) / |\underline{y}(t_0)|$ . Also  $\pi(\underline{y}(t)) =$   
 $= \pi(f(t) \cdot \underline{y}(t))$  for every  $f > 0$  and  
 $\tau_{s, t_0} \underline{y}(t) = \tau_{s, \sigma(t_0)} T_\sigma \underline{y}(t)$ .

If  $f \in C^{n-1}(I)$ ,  $\underline{y} \in C^{n-1}(I)$ , then  
 $W_n(f(t) \cdot \underline{y}(t)) = f^n(t) \cdot W_n(\underline{y}(t))$ , for  $f \neq 0$ ,  
 $W_n(\underline{y}(t)) \neq 0$  iff  $W_n(f(t) \cdot \underline{y}(t)) \neq 0$  on  $I$ .

For  $x \in C^{n-1}(I)$ ,  $dx(t)/dt \neq 0$  on  $I$  we have

$$W_n(\underline{y}(t)) = \left( \frac{dx(t)}{dt} \right)^{\frac{n(n-1)}{2}} \cdot W_n(T_x \underline{y}(t))$$

and again  $W_n(\underline{y}(t)) \neq 0$  on  $I$  iff

$$W_n(T_x \underline{y}(t)) \neq 0 \text{ on } J.$$

Suppose  $\underline{y} \in C^n(I)$ ,  $W_n(\underline{y}(t)) \neq 0$  on  $I$ .  
 Then  $\underline{u}(s) = \tau_{s, t_0} \pi(\underline{y}(t))$ ,  $s \in J$ , satisfies

$(\cdot = d/ds, \underline{u} \equiv \underline{u}_1)$ :

$$\underline{u}'_1(s) = \underline{u}_2(s)$$

$$\underline{u}'_2(s) = -\underline{u}_1(s) + \alpha_2(s) \underline{u}_3(s)$$

$$(1) \quad \underline{u}'_3(s) = -\alpha_2(s) \underline{u}_2(s) + \alpha_3(s) \underline{u}_4(s)$$

...

$$\underline{u}'_{m-1}(s) = -\alpha_{m-2}(s) \underline{u}_{m-2}(s) + \alpha_{m-1}(s) \underline{u}_m(s)$$

$$\underline{u}'_m(s) = -\alpha_{m-1}(s) \underline{u}_{m-1}(s),$$

where  $|\underline{u}_i(s)| = 1$  for  $i = 1, \dots, m$ ,  $\underline{u}_i \cdot \underline{u}_j = 0$   
 for  $i \neq j$ ,  $0 < \alpha_i(s) \in C^{m-i}(J)$  (generalized  
 Frenet formula). Constant vectors  $\underline{u}_i(0)$ ,  $i = 1, \dots, m$ ,  
 can be determined from  $d^{i-1} \underline{y}(0) / dt^{i-1}$  or

$$\underline{u}^{(i-1)}(0) .$$

Conversely, there exists the unique solution  $\underline{u}_1, \dots$   
 $\dots, \underline{u}_m$  of (1) which satisfies the initial conditions de-  
 termined by  $\underline{u}$  and its  $(n-1)$  derivatives at 0 ,  
 and  $\underline{u}_1(s) = \underline{u}(s)$  for all  $s \in J$  . Moreover

$$\begin{aligned} W_m(\underline{y}(t)) &= |\underline{y}(t)|^m \cdot W_m(\pi(\underline{y}(t))) = \\ &= |\underline{y}(t)|^m \cdot \left| \frac{d \frac{\underline{y}(t)}{|\underline{y}(t)|}}{dt} \right|^{\frac{n(n-1)}{2}} \cdot W_m(\underline{u}(s)), \end{aligned}$$

$$W_m(\underline{u}(s)) = \alpha_2^{m-2}(s) \cdot \alpha_3^{m-3}(s) \cdot \dots \cdot \alpha_{m-1}(s) \cdot [\underline{u}_1, \dots, \underline{u}_m] .$$

Hence for arbitrary  $0 < \alpha_i \in C^{n-i}(J)$  ,  $i = 2, \dots, m-1$  ,  
 arbitrary conditions on  $\underline{u}_1, \dots, \underline{u}_m$  at 0 such that  
 $[\underline{u}_1, \dots, \underline{u}_m]_{s=0} \neq 0$  ,  $t: J \rightarrow I$  ,  $dt(s)/ds > 0$   
 on  $J$  ,  $t \in C^{n-1}(J)$  ,  $f \in C^{m-1}(I)$  ,  $f > 0$  on  $I$  ,  
 we have  $W_m(f(t) \cdot \underline{u}(s(t))) \neq 0$  on  $I$  .

Let  $C$  be a non-singular  $n \times n$  matrix,  $C \underline{y}(t)$   
 the centroaffine transform of  $\underline{y}(t)$  ,  $t \in I$  . Suppose  
 $\underline{y} \in C^n(I)$  and  $W_m(\underline{y}(t)) \neq 0$  on  $I$  . If  $\underline{u}(s) =$   
 $= \tau_{s, t_0} \pi(\underline{y}(t))$  , then  $\underline{y}(t) = |\underline{y}(t)| \cdot \underline{u}(s(t))$  and  
 $C \underline{y}(t) = |\underline{y}(t)| \cdot C \underline{u}(s(t))$  . Since  $C \underline{u}$  ,  $C \underline{u}_2, \dots, C \underline{u}_m$   
 (for arbitrary non-singular  $C$  ) is the general form of  
 solutions of (1), all centroaffine transforms of  $\underline{y}(t)$   
 are of the form  $|\underline{y}(t)| \cdot \underline{v}(s(t))$  , where  $\underline{v}$  is  
 the first vector of any solution  $\underline{v}_1, \dots, \underline{v}_m$  of (1)  
 such that  $[\underline{v}_1, \dots, \underline{v}_m] \neq 0$  .

Let  $\underline{y} \in C^n(I)$  ,  $W_m(\underline{y}(t)) \neq 0$  on  $I$  and (1)  
 be the corresponding system on  $J$  . If  $\underline{x} \in C^n(I')$  ,  
 and  $\underline{x}(x) \neq f(t) \cdot C \underline{y}(t)$  on  $I$  for any

non-singular matrix  $C$ ,  $f \in C^n(I)$ ,  $f > 0$  on  $I$ ,  
 $x: I \rightarrow I'$ ,  $x \in C^n(I)$ ,  $dx(t)/dt > 0$  on  $I$ ,  
then  $\tau_{\lambda, x_0} \pi(x(x))$  does not satisfy (1) on  $J$  for  
any  $x_0 \in I'$ .

Let  $n$  be fixed. By  $Y$  denote the set of all trip-  
les  $(\underline{y}, t_0, I)$ , where  $I \subset \mathbb{R}$ ,  $\underline{y} \in C^n(I)$ ,  $t_0 \in I$ ,  
 $W_n(\underline{y}(t)) \neq 0$  on  $I$ . For  $(\underline{y}, t_0, I) \in Y$  define  
the mapping  $M = ((\underline{y}, t_0, I) \mapsto (\alpha_2, \dots, \alpha_{n-1}; J))$ ,  
where  $\alpha_i$  are the corresponding functions in (1) defined  
on  $J$ . Let  $E(Y)$  be such a decomposition of  $Y$  that  
 $(\underline{x}, x_0, I')$  and  $(\underline{y}, t_0, I)$  belong to the same  
class of  $E(Y)$  iff  $\underline{x}(x(t)) = f(t)$ ,  $C\underline{y}(t)$  on  $I$   
for a non-singular  $C$ ,  $f \in C^n(I)$ ,  $f > 0$  on  $I$ ,  
 $x: I \rightarrow I'$ ,  $x \in C^n(I)$ ,  $dx(t)/dt > 0$  on  $I$   
and  $x(t_0) = x_0$ . Denote by  $\simeq$  the corresponding  
equivalence.

Theorem 1. If  $(\underline{y}, t_0, I) \not\approx (\underline{x}, x_0, I')$ , then  
 $M(\underline{y}, t_0, I) \neq M(\underline{x}, x_0, I')$ .

Now, consider a differential equation

$$(2) L_m(y) \equiv y^{(m)} + a_1(t)y^{(m-1)} + \dots + a_n(t)y = 0 \quad \text{on } I.$$

Let  $t_0 \in I$ ,  $\underline{y}(t) = (y_1(t), \dots, y_m(t))$  be  $n$  linearly  
independent solutions of (2) on  $I$ , ( $\underline{y} \in C^n(I)$ ,  $W_n(\underline{y}(t)) \neq 0$   
on  $I$ ). Since  $C\underline{y}$  ( $\det C \neq 0$ ) is the general form of  $n$   
linearly independent solutions of (2), we may assign a fi-  
xed class  $\Phi(L_m, t_0, I) \equiv C\underline{y}(t)$  of the decom-  
position  $E(Y)$  to  $L_m$  on  $I$ ,  $t_0 \in I$ .

A differential equation  $L_m(y)$  on  $I (t_0 \in I)$  is said to be transformable into  $L_m^*(x)$  on  $I' (x_0 \in I')$  if there exist functions  $x$  and  $f$  such that  $x: I \rightarrow I'$ ,  $x(t_0) = x_0$ ,  $x \in C^n(I)$ ,  $dx(t)/dt > 0$  on  $I$ ,  $f \in C^n(I)$ ,  $f > 0$  on  $I$ , and for every solution  $y$  of  $L_m(y)$  on  $I$ , the function  $x = (x \mapsto f(t) \cdot y(t), x = x(t))$ , is a solution of  $L_m^*(x)$  on  $I'$ .

If  $W_m(y_j(t)) \neq 0$ , then  $W_m(f(t) \cdot y_j(t)) \neq 0$  and  $\underline{x}(x) = (x_1(x), \dots, x_m(x))$ ,  $x_i(x) = f(t) \cdot y_i(t)$ , are  $m$  linearly independent solutions of  $L_m^*(x)$  on  $I'$ . Hence  $\Phi(L_m, t_0, I) = \Phi(L_m^*, x_0, I')$ . Conversely, if the last relation is satisfied, then  $L_m(y)$  on  $I$  for  $t_0 \in I$  can be transformed into  $L_m^*(x)$  on  $I'$  for  $x_0 \in I'$ .

A solution  $y$  of (2) on  $I = (a, b)$ ,  $b \leq \infty$ , is oscillatory (for  $t \rightarrow b$ ), if it has infinitely many zeros on  $[t_1, b)$ ,  $t_1 \in I$ .

$L_m(y)$  is a non-oscillatory equation on  $I = (a, b)$  (for  $t \rightarrow b$ ), if no non-trivial solution of it is oscillatory (for  $t \rightarrow b$ ).

$L_m(y)$  is disconjugate on  $I$ , if no non-trivial solution has more than  $(m-1)$  zeros (including multiplicity).

Let  $d \in I$ ,  $\nu$  a positive integer,  $y$  be a solution of  $L_m(y)$  such that  $y(d_i) = 0$  for  $d = d_0 \leq d_1 \leq d_2 \leq \dots \leq d_{\nu+m-1}$ . Then  $\eta(d) = \inf_y \{d_{\nu+m-1}\}$  is called the  $\nu$ -th conjugate point of  $d$  (see [1]).

For  $\underline{c} \neq \underline{0}$ , let  $H(\underline{c}) \equiv \sum_{i=1}^n c_i \xi_i = 0$  be the hyperplane in  $E_n$ . Hyperplanes  $H(\underline{c}_j)$ ,  $j = 1, \dots, k$  ( $k \leq n$ ) will be called independent iff the rank of the matrix  $(\underline{c}_1, \dots, \underline{c}_k)$  is  $k$ .

**Theorem 2.** Let  $\underline{u}(\lambda) \in \Phi(L_m, t_0, I)$ ,  $\lambda \in J = (a', b')$ ,  $I = (a, b)$ . There exists a correspondence between the solutions of  $L_m(y)$  and all hyperplanes such that to linearly independent solutions  $y_1$  and  $y_2$  there correspond independent hyperplanes  $H_{y_1}$  and  $H_{y_2}$ . Moreover, there exists a 1-1 mapping  $\lambda: I \rightarrow J$  such that if  $t_1$  is a  $k$ -multiple zero of a solution  $y$  of  $L_m(y)$ , then  $\underline{u}$  and  $H_y$  have the contact of the  $(k-1)$ -th order at  $\underline{u}(\lambda(t_1))$ .

**Note.** The mapping  $\lambda$  and the correspondence between solutions of  $L_m$  and hyperplanes in  $E_n$  can be constructed in the following way: Let  $\underline{y}$  be formed by  $n$  linearly independent solutions of  $L_m$ . Since  $\underline{u}(\lambda) \in \Phi(L_m, t_0, I)$ ,  $\lambda \in J$ , we have

$$(3) \quad A \underline{y}(t) = |A \underline{y}(t)| \cdot \underline{u}(\lambda(t)), \quad t \in I,$$

for a (fixed) non-singular matrix  $A$ . Then the mapping  $\lambda$  is given in (3), and to every solution  $\underline{c} \underline{y}(t) = \underline{c}^* A \underline{y}(t)$  ( $\underline{c} = (c_1, \dots, c_n) \neq \underline{0}$  and hence  $\underline{c}^* \neq \underline{0}$ ) we assign the hyperplane  $H(\underline{c}^*)$ , and conversely.

**Corollary 1.**  $L_m(y)$  is non-oscillatory iff no hyperplane intersects  $\underline{u}(\lambda)$  infinitely many times for  $\lambda \in [0, b')$ .

**Corollary 2.**  $L_m(y)$  has  $k$  linearly indepen-

dent oscillatory solutions and every other linearly independent on them is non-oscillatory iff there exist just  $k$  independent hyperplanes, every of which intersects  $\underline{u}(\rho)$  infinitely many times for  $\rho \in [0, \rho']$ .

Corollary 3.  $L_m(\gamma)$  is disconjugate on  $I$  iff no hyperplane intersects  $\underline{u}$  at more than  $m - 1$  points on  $J$ , including multiplicity.

Corollary 4.  $L_m(\gamma)$  has a non-vanishing solution on  $I$  iff there exists a hyperplane which does not intersect  $\underline{u}(\rho)$  on  $J$ .

The oscillatory properties of solutions of  $L_m(\gamma)$  are simply recognizable from the behaviour of curves  $\underline{u}$  on  $S_{m-1}$  and some known results are easy to derive, e.g.,

(Sansone 1948,[3]): There exists an equation  $L_3(\gamma)$  on  $[a, \infty)$ , every solution of which is oscillatory. For construction of such  $L_3(\gamma)$  only a curve  $\underline{u}$ ,  $[\underline{u}, \underline{u}', \underline{u}''] \neq 0$ , on  $S_2$  is sufficient to be considered, which is intersected infinitely many times by every plane  $c_1 \xi_1 + c_2 \xi_2 + c_3 \xi_3 = 0$ .

Also a construction of  $L_3(\gamma)$  having a non-trivial oscillatory solution and every linearly independent on it being non-oscillatory is rather easy.

A constructive characterization of all conjugate points for general  $L_3(\gamma)$ , as required in [1], p.450, is given by the behaviour of curves on  $S_2$ . Hence Theorems 2.9, 2.10, Lemmas 2.15, 2.16 in [1], Theorems 4.1, 4.2, 4.7, 4.8 in [5] and others are obvious.



The known examples suggest the affirmative answer ([2],[4]) to the unsolved problem ([1],p.450): If  $L_3(y)$  is oscillatory on  $[\alpha, \infty)$ , then, is its adjoint equation also oscillatory? However, using the above considerations it can be shown that

Theorem 3. There exists an oscillatory equation  $L_3(y)$  such that its adjoint equation is non-oscillatory.

The described geometrical approach makes it possible to see the whole situation and not only to consider the separate examples as motivation for possible form of theorems. And oscillatory properties of solutions can be studied for all equivalent differential equations without respect to any change of dependent or independent variables.

#### R e f e r e n c e s

- [1] BARRETT J.H.: Oscillation theory of ordinary linear differential equations, *Advances in Mathematics*, 3(1969),415-509.
- [2] HANAN M.: Oscillation criteria for third-order linear differential equations, *Pacific J.Math.*11(1961), 919-944.
- [3] SANSONE G.: Studi sulle equazioni differenziali lineari omogenee di terzo ordine nel campo reale, *Revista Mat.Fis.Teor.Tucuman* 6(1948),195-253.
- [4] ŠVEC M.: Několik poznámek o lineárním diferenciálním rovnicím třetího řádu, *Czech.Math. J.* 15(1965),42-49.
- [5] SWANSON C.A.: Comparison and oscillation theory of

Linear differential equations, Acad.Press,  
vol.48, New York & London 1968.

Přírodovědecká fakulta UJEP

Janáčkovo nám. 2a

Brno

Československo

(Oblatum 18.12.1970)