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PŘEDBĚŽNÁ SDĚLENÍ

GENERAL STRESS-STRAIN RELATIONSHIPS OF ANISOTROPIC BODIES
AND THE CONCEPT OF THE TRANSFORMED STRAIN

[ADVANCED NOTE]

ZDENĚK SOBOTKA

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The author presents the general stress-strain relationships and the law of the deformation theory of plasticity of anisotropic bodies.

The general relation between the stress and strain components may be expressed in the following form

$$(1) \quad \sigma_{ij} = f_{ij}(B_{klmn}\epsilon_{mn}),$$

where B_{klmn} are the components of the fourth-rank tensor of anisotropy.

Introducing the transformed strain tensor of the rank two

$$(2) \quad \beta_{kl} = B_{klmn}\epsilon_{mn},$$

we may consider the general function

$$(3) \quad \sigma_{ij} = f_{ij}(\beta_{kl})$$

of two coaxial tensors σ_{ij} and β_{kl} .

The preceding function may be, under certain conditions, developed into absolutely convergent power series as follows

$$(4) \quad \sigma_{ij} = A_0\delta_{ij} + A_1\beta_{ij} + A_2\beta_{ia}\beta_{aj} + A_3\beta_{ia}\beta_{a\beta}\beta_{\beta j} + \dots$$

where $A_0, A_1, A_2, A_3, \dots$ are scalar coefficients and δ_{ij} is the Kronecker delta.

The left-hand side of (4) being a symmetrical tensor of the second rank, it follows from the tensorial dimensionality that the absolutely convergent series of the terms on the right-hand side is also represented by symmetrical tensors of rank two, which may be expressed according to the Cayley-Hamilton theorem in terms of three principal tensors

$$\delta_{ij}, \beta_{ij} = B_{ijkl}\epsilon_{kl}, \quad \beta_{ia}\beta_{aj} = B_{iakl}B_{ajmn}\epsilon_{kl}\epsilon_{mn}$$

and by functions of the three principal transformed strain invariants

$$(5) \quad I_\beta = \beta_{ij}\delta_{ij} = B_{ijkl}\delta_{ij}\epsilon_{kl},$$

$$(6) \quad II_\beta = \beta_{ij}\beta_{ij} = B_{ijkl}B_{ijmn}\epsilon_{kl}\epsilon_{mn},$$

$$(7) \quad III_\beta = \beta_{ij}\beta_{i\alpha}\beta_{\alpha j} = B_{ijkl}B_{iamn}B_{ajpq}\epsilon_{kl}\epsilon_{mn}\epsilon_{pq}.$$

Then we have the following constitutive stress-strain relation

$$(8) \quad \sigma_{ij} = \Phi_0\delta_{ij} + \Phi_1 B_{ijkl}\epsilon_{kl} + \Phi_2 B_{iakl}B_{ajmn}\epsilon_{kl}\epsilon_{mn}.$$

The scalar functions of the invariants Φ_0 , Φ_1 , Φ_2 follow from three equations which are analogous to those for isotropic materials

$$(9) \quad \sigma_{ij}\delta_{ij} = 3\Phi_0 + \Phi_1 B_{ijkl}\delta_{ij}\epsilon_{kl} + \Phi_2 B_{ijkl}B_{ijmn}\epsilon_{kl}\epsilon_{mn},$$

$$(10) \quad \begin{aligned} \sigma_{ij}\sigma_{ij} = & 3\Phi_0^2 + \Phi_1^2 B_{ijkl}B_{ijmn}\epsilon_{kl}\epsilon_{mn} + \\ & + \Phi_2^2 B_{iakl}B_{ajmn}B_{i\beta pq}B_{\beta jrs}\epsilon_{kl}\epsilon_{mn}\epsilon_{pq}\epsilon_{rs} + \\ & + 2\Phi_0\Phi_1 B_{ijkl}\delta_{ij}\epsilon_{kl} + 2\Phi_0\Phi_2 B_{ijkl}B_{ijmn}\epsilon_{kl}\epsilon_{mn} + \\ & + 2\Phi_1\Phi_2 B_{ijkl}B_{iamn}B_{ajpq}\epsilon_{kl}\epsilon_{mn}\epsilon_{pq}, \end{aligned}$$

$$(11) \quad \begin{aligned} \sigma_{ij}\sigma_{i\alpha}\sigma_{\alpha j} = & 3\Phi_0^3 + \Phi_1^3 B_{ijkl}B_{iamn}B_{ajpq}\epsilon_{kl}\epsilon_{mn}\epsilon_{pq} + \\ & + \Phi_2^3 B_{ijkl}B_{iamn}B_{\alpha\beta pq}B_{\beta\gamma rs}B_{\gamma\delta tu}B_{\delta j\alpha b}\epsilon_{kl}\epsilon_{mn}\epsilon_{pq}\epsilon_{rs}\epsilon_{tu}\epsilon_{ab} + \\ & + 3\Phi_0^2\Phi_1 B_{ijkl}\delta_{ij}\epsilon_{kl} + 3\Phi_0\Phi_1^2 B_{ijkl}B_{ijmn}\epsilon_{kl}\epsilon_{mn} + \\ & + 3\Phi_0^2\Phi_2 B_{ijkl}B_{ijmn}\epsilon_{kl}\epsilon_{mn} + 3\Phi_0\Phi_2^2 B_{ijkl}B_{iamn}B_{\alpha\beta pq}B_{\beta jrs}\epsilon_{kl}\epsilon_{mn}\epsilon_{pq}\epsilon_{rs} + \\ & + 3\Phi_1^2\Phi_2 B_{ijkl}B_{iamn}B_{\alpha\beta pq}B_{\beta jrs}\epsilon_{kl}\epsilon_{mn}\epsilon_{pq}\epsilon_{rs} + \\ & + 3\Phi_1\Phi_2^2 B_{ijkl}B_{iamn}B_{\alpha\beta pq}B_{\beta\gamma rs}B_{\gamma jtu}\epsilon_{kl}\epsilon_{mn}\epsilon_{pq}\epsilon_{rs}\epsilon_{tu} + \\ & + 6\Phi_0\Phi_1\Phi_2 B_{ijkl}B_{iamn}B_{ajpq}\epsilon_{kl}\epsilon_{mn}\epsilon_{pq}. \end{aligned}$$

The third term in (8) represents the second-order effects. In the case of infinitesimal deformation, (8) becomes

$$(12) \quad \sigma_{ij} = \Phi_0\delta_{ij} + \Phi_1 B_{ijkl}\epsilon_{kl}.$$

The invariant functions may be expressed from

$$(13) \quad \sigma_{ij}\delta_{ij} = 3\Phi_0 + \Phi_1 B_{ijkl}\delta_{ij}\epsilon_{kl},$$

$$(14) \quad \sigma_{ij}\sigma_{ij} = 3\Phi_0^2 + 2\Phi_0\Phi_1 B_{ijkl}\delta_{ij}\epsilon_{kl} + \Phi_1^2 B_{iakl}B_{ajmn}\epsilon_{kl}\epsilon_{mn}$$

after introducing the relations (5) and (6) as follows

$$(15) \quad \Phi_0 = \frac{1}{3} \left(I_\sigma - I_\beta \sqrt{\frac{3II_\sigma - I_\sigma^2}{3II_\beta - I_\beta^2}} \right),$$

$$(16) \quad \Phi_1 = \sqrt{\frac{3II_\sigma - I_\sigma^2}{3II_\beta - I_\beta^2}},$$

where $I_\sigma = \sigma_{ij}\delta_{ij}$, $II_\sigma = \sigma_{ij}\sigma_{ij}$ are the invariants of the stress tensor.

After some rearrangements, the author has obtained the stress-strain relations of the deformation theory of plasticity for anisotropic bodies,

$$(17) \quad \sigma_{ij} - \sigma \delta_{ij} = \frac{2\sigma_i}{3\beta_i} (\beta_{ij} - \beta \delta_{ij}),$$

where $\sigma = \frac{1}{3}(\sigma_{11} + \sigma_{22} + \sigma_{33})$ is the mean stress

$$\sigma_i = \frac{1}{\sqrt{2}} \sqrt{[(\sigma_{11} - \sigma_{22})^2 + (\sigma_{22} - \sigma_{33})^2 + (\sigma_{33} - \sigma_{11})^2 + 6(\sigma_{12}^2 + \sigma_{23}^2 + \sigma_{31}^2)]}$$

the effective stress, $\beta_{ij} = B_{ijkl}e_{kl}$ the transformed strain components,

$$\beta_i = \frac{\sqrt{2}}{3} \sqrt{[(\beta_{11} - \beta_{22})^2 + (\beta_{22} - \beta_{33})^2 + (\beta_{33} - \beta_{11})^2 + 6(\beta_{12}^2 + \beta_{23}^2 + \beta_{31}^2)]}$$

the transformed effective strain and $\beta = \frac{1}{3}(\beta_{11} + \beta_{22} + \beta_{33})$ the transformed mean strain.

Then, the concept of the transformed strain makes it possible to express the stress-strain relationships for anisotropic bodies in a manner analogous to that of the isotropic case.

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