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SOME RESULTS ON MATRICES OF CLASS  $\mathbf{K}$  AND THEIR  
APPLICATION TO THE CONVERGENCE RATE  
OF ITERATION PROCEDURES

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**Introduction.** The present paper represents a continuation of the authors' series of communications concerning matrices of type  $\mathbf{K}$  and their applications to spectral problems. The paper is divided into three sections, the first section being devoted to a recapitulation of some definitions and terminological conventions. The new results on matrices of class  $\mathbf{K}$  are collected in section two. Especially, we present improvements of two theorems of the first paper [2] of the series. Theorems (2,5) and (2,6) of the present paper constitute a quantitative sharpening of theorem (4,6) of [2]. Theorem (2,10) is a considerable improvement of theorem (6,7) of [2] in that it gives conditions under which the new matrix can be singular.

As an illustration, section 3 contains theorems which are closely connected with convergence theorems in relaxation methods. Theorem (3,3) recalls – under appropriate assumptions – the monotonous dependence of the convergence rate on the choice of the matrix  $B$  in the iteration formula  $x_{n+1} = B^{-1}(B - A)x_n + B^{-1}b$  for the solution of  $Ax = b$ . This theorem was proved in [1] for  $A$  symmetric. R. S. VARGA [4] generalized this result for the non-symmetric case. Theorem (3,4) shows that analogous estimates to those obtained by Varga [5] are valid for a more general class of Gauss-Seidel procedures.

**1. Definitions and notation.** In the whole paper,  $n$  will be a fixed natural number. The set of all natural numbers  $\leq n$  will be denoted by  $N$ . A matrix is a real function on  $N \times N$ , the value of a matrix  $A$  at the point  $(i, k)$  being denoted by  $a_{ik}$ . A matrix  $A$  is said to be nonnegative if  $a_{ik} \geq 0$  for each  $i$  and  $k$ . In this case, we write simply  $A \geq 0$ . The (unique) nonnegative proper value of a nonnegative matrix  $A$  which has the greatest modulus of all proper values of  $A$  will be called Perron root of  $A$  and denoted by  $p(A)$ .

A matrix  $A$  is said to be diagonal if  $a_{ik} = 0$  for  $i \neq k$ . Such a matrix will be denoted by  $\text{diag}(a_{11}, a_{22}, \dots, a_{nn})$ . A positive diagonal matrix is a diagonal matrix with  $a_{ii} > 0$  for all  $i$ .

The spectral radius of a matrix  $A$  is the maximum of the moduli of the proper values of  $A$  and will be denoted by  $|A|_\sigma$ . In accordance with common usage we shall, sometimes, drop the unit matrix in expressions like  $\lambda E - A$ .

We shall denote by  $\mathbf{Z}$  the class of all matrices  $A$  for which  $a_{ik} \leq 0$  for  $i \neq k$ . The subclass of  $\mathbf{Z}$  consisting of all matrices  $A \in \mathbf{Z}$  which have all principal minors positive will be called  $\mathbf{K}$ , the subclass of all matrices  $A \in \mathbf{Z}$  which have all principal minors nonnegative will be denoted by  $\mathbf{K}_0$ . The matrices which belong to  $\mathbf{K}$  are usually called  $M$ -matrices by various authors. The paper [2] presented by the authors is devoted to the study of both the important classes  $\mathbf{K}$  and  $\mathbf{K}_0$  and contains a whole series of equivalent characterizations of matrices in  $\mathbf{K}$  or  $\mathbf{K}_0$ . Since we shall repeatedly use different results on matrices of these types contained in [2], it will be convenient to simplify references to this paper in using the symbol 2 to denote results of [2]. Thus, theorem (2; 2,3) will be theorem (2,3) of [2] whereas (2,3) is theorem (2,3) of the present paper.

Finally, we recall the following notation from [2]. If  $A$  is a matrix in  $\mathbf{K}$  or  $\mathbf{K}_0$ , we denote by  $q(A)$  the (unique) nonnegative proper value of  $A$  which has the smallest modulus of all proper values of  $A$ .

**2.** In this section, we shall prove some theorems on nonnegative matrices, and on matrices of classes  $\mathbf{K}$  and  $\mathbf{K}_0$ .

(2,1) *A matrix  $A$  belongs to  $\mathbf{K}$  if and only if it may be written in the form  $A = \lambda - P$  where  $P$  is nonnegative and  $\lambda > p(P)$ . Similarly,  $A$  belongs to  $\mathbf{K}_0$  if and only if it may be written in the form  $A = \lambda - P$  where  $P$  is nonnegative and  $\lambda \geq p(P)$ .*

*Proof.* Suppose that  $A \in \mathbf{K}$ . Clearly there exists a  $\lambda > 0$  such that  $P = \lambda - A \geq 0$ . The number  $\lambda - p(P)$  is a real proper value of  $A$  whence  $\lambda - p(P) > 0$  according to (2; 4,3). On the other hand, if a matrix  $\tau - P$  is given where  $P \geq 0$  and  $\tau > p(P)$ , we have  $\tau > |P|_\sigma$  so that  $(\tau - P)^{-1} = E + P + P^2 + \dots$  exists and is nonnegative. Hence  $\tau - P$  belongs to  $\mathbf{K}$  by (2;4,3). The statement about matrices of type  $\mathbf{K}_0$  may be obtained in an analogous manner or follows directly from (2;5,1).

(2,2) *Let  $M$  and  $S$  be two nonnegative matrices such that  $m_{ii} > 0$  and  $S$  is symmetric. Then  $p(MS) = 0$  implies  $S = 0$ .*

*Proof.* The matrix  $A = MS$  is nonnegative and  $p(A) = 0$ . It follows from the theory of nonnegative matrices that there exists a permutation matrix  $P$  such that  $B = PAP^{-1}$  is a matrix with  $b_{ik} = 0$  for  $i \leq k$ . If  $\tilde{M} = PMP^{-1}$  and  $\tilde{S} = PSP^{-1}$ , we have for  $i \leq k$

$$\tilde{m}_{ii}\tilde{s}_{ik} \leq \sum_r \tilde{m}_{ir}\tilde{s}_{rk} = b_{ik} = 0$$

so that  $\tilde{s}_{ik} = 0$ , the number  $\tilde{m}_{ii}$  being clearly positive. Since  $\tilde{S}$  is symmetric, this means that  $\tilde{S} = 0$  which implies  $S = 0$ .

(2,3) Let  $0 \leq A \leq B$  and suppose that  $p(A) = p(B)$ . If  $A$  is irreducible then  $A = B$ .

Proof. Suppose that  $A$  is irreducible. If  $n = 1$ , the result is obvious. If  $n \geq 2$ ,  $B$  is irreducible as well, we have  $p(A) > 0$  and there exist positive vectors  $x$  and  $y$  such that  $Ax = p(A)x$  and  $y'B = p(B)y'$ . We have thus

$$p(A)y'x = y'Ax \leq y'Bx = p(B)y'x = p(A)y'x$$

whence  $y'Ax = y'Bx$ . Both vectors  $y$  and  $x$  being positive, this implies  $A = B$ .

(2,4) Let  $P \leq Q$  and suppose that both  $P$  and  $Q$  belong to  $\mathbf{K}_0$ . If  $Q$  is singular then so is  $P$ . Moreover, if  $Q$  is irreducible then  $Q$  singular implies  $P = Q$ .

Proof. Suppose that  $P \in \mathbf{K}_0$ ,  $Q \in \mathbf{K}_0$  and  $P \leq Q$ . If  $P$  is nonsingular, we have  $P \in \mathbf{K}$  by (2;5,5) and it follows from (2;4,6) that  $Q \in \mathbf{K}$  as well. This proves the first assertion. Suppose now that  $Q$  is singular. There exists an  $\alpha > 0$  such that both matrices  $A = \alpha E - Q$  and  $B = \alpha E - P$  are nonnegative. It follows from (2;5,1) that  $\alpha = p(A) = p(B)$ .

We have thus  $A \leq B$  and  $p(A) = p(B)$ ; if  $Q$  is irreducible then  $A$  is irreducible as well so that, by (2,3), we have  $A = B$  whence  $P = Q$ .

(2,5) Let  $A \in \mathbf{K}$ . If  $B \geq A$  and  $B \in \mathbf{Z}$  then

1°  $B \in \mathbf{K}$ ,

2°  $0 \leq B^{-1} \leq A^{-1}$ ,

3°  $\det B \geq \det A > 0$ ,

4°  $A^{-1}B \geq E$  and  $BA^{-1} \geq E$ ,

5°  $E \geq B^{-1}A$  and  $E \geq AB^{-1}$  and both matrices  $B^{-1}A$  and  $AB^{-1}$  belong to  $\mathbf{K}$ ,

6°  $1 - p(E - B^{-1}A) = 1 - p(E - AB^{-1}) = \frac{1}{p(A^{-1}B)} = \frac{1}{p(BA^{-1})}$ ,

7°  $q(B) \geq q(A)$ .

Proof. If  $B \in \mathbf{Z}$  and  $B \geq A$ , the matrix  $\tau E - B$ , and hence also  $\tau E - A$ , will be nonnegative for a suitable positive  $\tau$ . Since  $A = \tau E - (\tau E - A)$ , the number  $\tau - p(\tau E - A)$  is a proper value of  $A$  so that  $\tau - p(\tau E - A)$  is positive by 7° of (2;4,3). We have  $0 \leq \tau E - B \leq \tau E - A$  whence  $p(\tau E - B) \leq p(\tau E - A) < \tau$ . It follows that both the series

$$E + \left(E - \frac{1}{\tau} B\right) + \left(E - \frac{1}{\tau} B\right)^2 + \dots,$$

$$E + \left(E - \frac{1}{\tau} A\right) + \left(E - \frac{1}{\tau} A\right)^2 + \dots$$

are convergent. The first series converges to  $(1/\tau) \cdot B^{-1}$ , the second series to  $(1/\tau) \cdot A^{-1}$ . It follows that  $0 \leq B^{-1} \leq A^{-1}$ . This proves 2°; further it follows from 11° of (2;4,3) that  $B \in \mathbf{K}$ . The inequalities in 4° and 5° may be obtained upon multiplying  $B - A \geq 0$  by the nonnegative matrices  $A^{-1}$  and  $B^{-1}$ . Since  $E \geq B^{-1}A$  and  $E \geq AB^{-1}$ , we have  $B^{-1}A \in \mathbf{Z}$  and  $AB^{-1} \in \mathbf{Z}$ . Further, these matrices have inverses  $A^{-1}B$  and  $BA^{-1}$  which are nonnegative by 4°. It follows that both  $B^{-1}A$  and  $AB^{-1}$  belong to  $\mathbf{K}$ . To prove 6°, let us note first that the matrices  $B^{-1}A$  and  $AB^{-1}$  are similar so that it suffices to prove  $1 - p(E - B^{-1}A) = 1/p(A^{-1}B)$ . If we write  $\lambda$  for  $p(E - B^{-1}A)$ , it follows that  $1 - \lambda$  is a proper value of  $B^{-1}A$ . Since  $B^{-1}A \in \mathbf{K}$ , the number  $1 - \lambda$  is positive according to 7° of (2;4,3). We intend to show now that  $1/(1 - \lambda)$  is the Perron root of  $A^{-1}B$ . Indeed,  $1/(1 - \lambda)$  is a proper value of  $A^{-1}B = (B^{-1}A)^{-1}$ . If  $\mu > 1/(1 - \lambda)$ , we may write  $\mu = 1/(1 - \sigma)$  for a suitable  $\sigma > \lambda$ . It follows that

$$\begin{aligned} \mu E - A^{-1}B &= \frac{1}{1 - \sigma} E - A^{-1}B = \frac{1}{1 - \sigma} A^{-1}B(B^{-1}A - (1 - \sigma)E) = \\ &= \frac{1}{1 - \sigma} A^{-1}B(\sigma E - (E - B^{-1}A)) \end{aligned}$$

and the last matrix is nonsingular since  $\sigma > \lambda = p(E - B^{-1}A)$ .

To prove 7°, it is sufficient to show that  $\lambda E - B$  is nonsingular if  $\lambda < q(A)$ . But in this case  $\alpha - \lambda \geq q(A) - \lambda > 0$  for each real proper value  $\alpha$  of  $A$  so that  $A - \lambda E \in \mathbf{K}$  by 7° of (2;4,3). Since  $B - \lambda E \geq A - \lambda E$  and  $B - \lambda E \in \mathbf{Z}$ ,  $B - \lambda E \in \mathbf{K}$  and thus nonsingular. The proof is complete.

(2,6) Let  $M \in \mathbf{K}$ . Suppose we are given two matrices  $B_1$  and  $B_2$  which satisfy

$$B_2 \geq B_1 \geq M.$$

If  $B_2 \in \mathbf{Z}$ , then both  $B_2$  and  $B_1$  belong to  $\mathbf{K}$ . Further, both  $B_2^{-1}M$  and  $B_1^{-1}M$  belong to  $\mathbf{K}$  and

$$0 \leq p(B_1^{-1}(B_1 - M)) \leq p(B_2^{-1}(B_2 - M)) < 1.$$

Proof. The inclusions  $B_2 \in \mathbf{K}$  and  $B_1 \in \mathbf{K}$ ,  $B_2^{-1}M \in \mathbf{K}$  and  $B_1^{-1}M \in \mathbf{K}$  follow immediately from the preceding theorem. Clearly it suffices to prove

$$0 < 1 - p(B_2^{-1}(B_2 - M)) \leq 1 - p(B_1^{-1}(B_1 - M)) \leq 1.$$

According to 6° of the preceding theorem, we have

$$1 - p(E - B_2^{-1}M) = \frac{1}{p(M^{-1}B_2)} \leq \frac{1}{p(M^{-1}B_1)} = 1 - p(E - B_1^{-1}M).$$

Together with the obvious facts  $1/p(M^{-1}B_2) > 0$  and  $p(E - B_1^{-1}M) \geq 0$  this yields the desired inequalities.

(2,7) Let  $A \in \mathbf{K}$ ,  $B \in \mathbf{K}$  and suppose that  $AB \in \mathbf{Z}$ . Then  $AB \in \mathbf{K}$ .

Proof. We use condition 11° of (2;4,3). Since  $A$  and  $B$  belong to  $\mathbf{K}$ , they are both nonsingular and  $A^{-1} \geq 0$ ,  $B^{-1} \geq 0$ . It follows that  $(AB)^{-1}$  exists and  $(AB)^{-1} = B^{-1}A^{-1} \geq 0$  whence  $AB \in \mathbf{K}$ , taking into account the inclusion  $AB \in \mathbf{Z}$ .

(2,8) Let  $A \in \mathbf{K}$ ,  $B \in \mathbf{Z}$ . If  $AB \in \mathbf{K}$ , then  $B \in \mathbf{K}$ . If  $AB \in \mathbf{K}_0$  and is irreducible, then  $B \in \mathbf{K}_0$ .

Proof. By 2° of (2;4,3) there exists a vector  $x > 0$  such that  $ABx = y > 0$ . Since  $A \in \mathbf{K}$ , it follows that  $A^{-1} \geq 0$  with all diagonal elements positive. Hence  $Bx = A^{-1}y > 0$  and it follows from 2° of (2;4,3) that  $B \in \mathbf{K}$ .

Let now  $AB \in \mathbf{K}_0$  and let  $AB$  be irreducible. It suffices to discuss only the case that  $AB$  is singular since otherwise  $AB \in \mathbf{K}$  and  $B \in \mathbf{K}$ . In this case, there exists, by (2;5,6), a vector  $x > 0$  such that  $ABx = 0$ . Thus we have  $Bx \geq 0$  and  $B \in \mathbf{K}_0$  by (2;5,4). The proof is complete.

(2,9) Let  $A \in \mathbf{K}_0$  be singular and suppose  $z$  is a vector for which  $Az \geq 0$ . If  $A$  is irreducible then  $Az = 0$ .

Proof. According to (2;5,6) there exists a vector  $y > 0$  such that  $y'A = 0$ . If  $u = Az$ , we have  $y > 0$ ,  $u \geq 0$  and  $y'u = y'Az = 0$  so that  $u$  must be the zero vector.

We shall need further a sharpening of theorem (2;6,7). For the sake of completeness we intend to give the entire proof although a part of the present result is already contained in (2;6,7). We introduce first a notation.

(2,10) Let  $A$  and  $B$  be two matrices of type  $(n, n)$  and let  $0 < \alpha < 1$  be given. We shall denote by  $g(A, B)$  the matrix  $G$  where

$$g_{ii} = |a_{ii}|^\alpha |b_{ii}|^{1-\alpha}, \quad g_{ik} = -|a_{ik}|^\alpha |b_{ik}|^{1-\alpha} \quad \text{for } i \neq k.$$

(2,11) Let  $0 < \alpha < 1$  be given. Then the following implications hold:

- 1° If  $A \in \mathbf{K}$ ,  $B \in \mathbf{K}$  then  $g(A, B) \in \mathbf{K}$ .
- 2° If  $A \in \mathbf{K}_0$ ,  $B \in \mathbf{K}_0$  then  $g(A, B) \in \mathbf{K}_0$ .
- 3° Let  $A$  and  $B$  belong to  $\mathbf{K}_0$  and let  $g(A, B)$  be singular. Suppose further that  $g(A, B)$  is irreducible. Then
- 31° both  $A$  and  $B$  are singular and there exist vectors  $x_0 > 0$  and  $y_0 > 0$  with  $Ax_0 = 0$  and  $By_0 = 0$ ;
- 32° if  $x > 0$ ,  $y > 0$  and  $Ax = 0$ ,  $By = 0$  then the vector  $z$  with coordinates  $z_i = x_i^\alpha y_i^{1-\alpha}$  satisfies  $g(A, B)z = 0$ ;
- 33° there exist positive diagonal matrices  $P$  and  $Q$  such that  $PA = BQ$ ;

34° if  $x > 0$ ,  $y > 0$  satisfy  $Ax = 0$ ,  $By = 0$  and if  $X = \text{diag}(x_1, \dots, x_n)$ ,  $Y = \text{diag}(y_1, \dots, y_n)$  then there exists a positive diagonal matrix  $D$  such that  $AX = DBY$ .

4° Conversely, let  $A$  and  $B$  be matrices of type  $(n, n)$  and let  $A \in \mathbf{Z}$ . Let  $X, Y, D$  be positive diagonal matrices. Let  $e$  be the vector with  $e_i = 1$  for every  $i$  and suppose that  $AXe = 0$ . Let  $B$  satisfy the relation  $AX = DBY$ . Then both  $A$  and  $B$  belong to  $\mathbf{K}_0$ ,  $BYe = 0$  and  $g(A, B)$  is singular.

Proof. We shall use the Hölder inequality in the following form: if  $a_i$  and  $b_i$  are nonnegative numbers then

$$\sum a_i^\alpha b_i^{1-\alpha} \leq (\sum a_i)^\alpha (\sum b_i)^{1-\alpha}$$

and equality holds if and only if the vectors  $a$  and  $b$  are linearly dependent. Consider first the case  $A, B \in \mathbf{K}$ . According to 2° of (2;4,3), there exist positive vectors  $x$  and  $y$  such that  $Ax > 0$  and  $By > 0$ . We are going to show that  $g(A, B)z > 0$  where  $z$  is the vector with coordinates  $z_i = x_i^\alpha y_i^{1-\alpha}$ . Indeed, we have

$$\begin{aligned} \sum_{k \neq i} |a_{ik}|^\alpha |b_{ik}|^{1-\alpha} z_k &= \sum_{k \neq i} (|a_{ik}| x_k)^\alpha (|b_{ik}| y_k)^{1-\alpha} \leq \\ &(\sum_{k \neq i} |a_{ik}| x_k)^\alpha (\sum_{k \neq i} |b_{ik}| y_k)^{1-\alpha} < (a_{ii} x_i)^\alpha (b_{ii} y_i)^{1-\alpha} = a_{ii}^\alpha b_{ii}^{1-\alpha} z_i. \end{aligned}$$

This completes the proof of 1°. Suppose now that  $A$  and  $B$  belong to  $\mathbf{K}_0$ . We are going to show that  $g(A, B) + \varepsilon E$  belongs to  $\mathbf{K}$  for each positive  $\varepsilon$ . Clearly there exist positive numbers  $s_i$  and  $t_i$  such that

$$g_{ii} + \varepsilon = (a_{ii} + s_i)^\alpha (b_{ii} + t_i)^{1-\alpha}.$$

If  $S$  and  $T$  are diagonal matrices with  $s_i$  and  $t_i$  as diagonal elements, we have  $A + S \in \mathbf{K}$  and  $B + T \in \mathbf{K}$  by (2;5,11) and 3° of (2;5,1). Hence  $g(A, B) + \varepsilon E = g(A + S, B + T) \in \mathbf{K}$  by the first assertion of the present theorem. It follows from (2;5,1) that  $g(A, B) \in \mathbf{K}_0$ .

To prove 3°, assume  $A, B \in \mathbf{K}_0$  and suppose that  $g(A, B)$  is singular and irreducible. According to 2°, we have  $g(A, B) \in \mathbf{K}_0$ . Since  $g(A, B)$  is irreducible, both  $A$  and  $B$  are irreducible as well. Since both  $A, B \in \mathbf{K}_0$  it follows from (2;5,8) that there exist vectors  $x_0 > 0$  and  $y_0 > 0$  for which  $Ax_0 \geq 0$  and  $By_0 \geq 0$ . If  $z$  is the vector with coordinates  $z_i = x_{0i}^\alpha y_{0i}^{1-\alpha}$ , we obtain in the same manner as above  $z > 0$  and  $g(A, B)z \geq 0$ . Now it follows from (2,9) that  $g(A, B)z = 0$ ; hence equality is attained in the inequalities

$$\begin{aligned} \sum_{k \neq i} |a_{ik}|^\alpha |b_{ik}|^{1-\alpha} z_k &= \sum_{k \neq i} (|a_{ik}| x_{0k})^\alpha (|b_{ik}| y_{0k})^{1-\alpha} \leq \\ &\leq (\sum_{k \neq i} |a_{ik}| x_{0k})^\alpha (\sum_{k \neq i} |b_{ik}| y_{0k})^{1-\alpha} \leq (a_{ii} x_{0i})^\alpha (b_{ii} y_{0i})^{1-\alpha} = a_{ii}^\alpha b_{ii}^{1-\alpha} z_i \end{aligned}$$

so that  $Ax_0 = 0$  and  $By_0 = 0$ . This proves 31°.

To prove 32°, 34° and 33°, let  $x > 0, y > 0$  be vectors for which  $Ax = 0, By = 0$ . Then, an analogous chain of inequalities as for  $x_0, y_0$  is satisfied for  $x, y$  and for the vector  $z, z_i = x_i^\alpha y_i^{1-\alpha}$ . By (2,9), we have  $g(A, B)z = 0$  which proves 32°. In these inequalities equality is attained. Hence, for each  $i$ , the vectors

$$u^{(i)} = (|a_{i1}| x_1, \dots, |a_{i,i-1}| x_{i-1}, |a_{i,i+1}| x_{i+1}, \dots, |a_{in}| x_n),$$

$$v^{(i)} = (|b_{i1}| y_1, \dots, |b_{i,i-1}| y_{i-1}, |b_{i,i+1}| y_{i+1}, \dots, |b_{in}| y_n)$$

are linearly dependent. Since  $x > 0, y > 0$  and both  $A$  and  $B$  are irreducible, none of these is the zero vector so that there exists a  $d_i > 0$  with  $u^{(i)} = d_i v^{(i)}$ . Since  $a_{ii} x_i = \sum_{k \neq i} |a_{ik}| x_k = d_i \sum_{k \neq i} |b_{ik}| y_k = d_i b_{ii} y_i$  as well, we have proved the equation  $AX = DBY$  where  $D = \text{diag}(d_1, \dots, d_n)$ . This proves 34°. Since there exist vectors  $x$  and  $y$  according to 31°, 33° is satisfied for  $P = D^{-1}, Q = YX^{-1}$ .

To prove 4°, let us write  $x = Xe, y = Ye$  so that  $x > 0$  and  $y > 0$ . We have  $A \in \mathbf{Z}, x > 0$  and  $Ax = AXe = 0$ . It follows from (2;5,4) that  $A \in \mathbf{K}_0$ . Since  $B = D^{-1}AXY^{-1}$ , we have  $B \in \mathbf{Z}$  and

$$By = BYe = D^{-1}AXe = 0.$$

Since  $y > 0$ , it follows from (2;5,4) that  $B \in \mathbf{K}_0$ . To see that  $g(A, B)$  is singular, it suffices to take the vector  $z$  with coordinates  $z_i = x_i^\alpha y_i^{1-\alpha}$  and show that  $g(A, B)z = 0$ . This follows from a direct computation.

The last theorem concerns matrices with all principal minors positive or non-negative.

(2,12) *Let  $A$  be a real matrix such that  $A + A^*$  is positive definite. Then, all principal minors of  $A$  are positive. If  $A + A^*$  is nonnegative definite then all principal minors of  $A$  are nonnegative.*

*Proof.* The first part follows from (2;3,3) if we put  $D_x = E$  for each  $x$ . To prove the second part, it suffices to consider the set of matrices  $A + \varepsilon E$  for  $\varepsilon > 0$  and apply the preceding result.

**3. Some applications.** As an illustration of the preceding results we shall prove here a theorem which generalizes some earlier results of R. S. Varga. In its formulation we shall need some notions concerning relations and their decompositions.

A relation on a set  $M$  is an arbitrary subset of  $M \times M$ . If  $R$  is a relation on  $M$  we shall write  $xRy$  for  $(x, y) \in R$ . A cycle in the relation  $R$  is a sequence  $g_1, \dots, g_m \in M$  such that

$$g_1 R g_2 R g_3 \dots g_{m-1} R g_m R g_1.$$

A relation is said to be symmetric if  $aRb$  implies  $bRa$ . If  $R$  is a symmetric relation on  $M$ , we shall denote by  $R^e$  the relation defined as follows:



$aR^e c$  if and only if one of the following conditions is satisfied:

1°  $a = c$ ,

2°  $aRc$ ,

3° there exist elements  $b_1, \dots, b_k \in M$  such that  $aRb_1Rb_2 \dots b_kRc$ .

Clearly  $R^e$  is the minimal equivalence containing  $R$ . We shall say that  $R$  is connected if  $xR^e y$  for each  $x$  and  $y$  in  $M$ . (This is clearly in conformity with the terminology of the theory of graphs.)

Let us introduce now the following definition:

(3,1) Let  $R$  be a symmetric relation on  $M$ . We shall say that the three subsets  $S, P, P^*$  of  $R$  form a conservative decomposition of  $R$  if the following conditions are satisfied:

1° the sets  $S, P, P^*$  are pairwise disjoint;

2°  $iPk$  if and only if  $kP^*i$ ;

3° for each cycle  $g_1, \dots, g_m$  in  $R$

$$p(g_1, g_2) + p(g_2, g_3) + \dots + p(g_{m-1}, g_m) + p(g_m, g_1) = 0$$

where

$$(1) \quad \begin{aligned} p(i, k) &= 0 && \text{for } iSk, \\ p(i, k) &= -1 && \text{for } iPk, \\ p(i, k) &= 1 && \text{for } iP^*k. \end{aligned}$$

(3,2) Let  $S \cup P \cup P^*$  be a decomposition of a symmetric relation  $R$  satisfying 1° and 2° of (3,1). This decomposition is conservative if and only if there exists an integer-valued function  $V$  on  $M$  such that  $i_0Ri_1R \dots Ri_s$  implies

$$(2) \quad V(i_s) - V(i_0) = \sum_{k=1}^s p(i_{k-1}, i_k),$$

$p(i, k)$  being defined in (1).

Moreover, this function  $V$  is unique up to an additive constant if  $R$  is connected.

**Proof.** It is immediately seen that the condition (2) implies 3° of (3,1). Now, let the decomposition  $S \cup P \cup P^*$  be conservative and let  $M_1, \dots, M_m$  be classes of equivalent elements in the equivalence  $R^e$ . Choose arbitrary elements  $g_i \in M_i$ ,  $i = 1, \dots, m$  and put  $V(g_i) = 0$ . Let  $h \in M$ . If  $h \in M_k$ , we have one of the following three possibilities: either  $g_k = h$  or  $g_kRh$  or there exists a sequence  $a_1, \dots, a_t$  such that

$$g_kRa_1Ra_2R \dots Ra_tRh.$$

Let us form the sum

$$V(h) = p(g_k, a_1) + p(a_1, a_2) + \dots + p(a_t, h).$$

To include all the three possibilities in the definition of  $g_k R^e h$ , let us agree that we take this sum to be empty if  $g_k = h$  or has just one term if  $g_k R h$ .

Let us show that  $V(h)$  is independent on the sequence from  $g_k$  to  $h$ . Indeed, let  $g_k R b_1 R \dots R b_n R h$  (in the same generalized sense) as well. Then,

$$g_k R a_1 R a_2 \dots R a_t R h R b_n R \dots R b_1 R g_k$$

is a cycle in  $R$  and from 3° it follows that

$$V(h) + p(h, b_n) + \dots + p(b_1, g_k) = 0.$$

The independence follows immediately from the skew symmetry of  $p$ . We have thus obtained an integer-valued function on  $M$ . To prove the formula (2), let  $a_0 R a_1 R \dots R a_s$  and let all these elements  $a_i$  belong to  $M_k$ . Hence there exist sequences  $b_1, \dots, b_v$  and  $c_1, \dots, c_w$  such that  $g_k R b_1 R \dots R b_v R a_0, a_s R c_1 R \dots R c_w R g_k$ , which complete the given sequence to a cycle. It follows in a similar manner as above that

$$V(a_0) + p(a_0, a_1) + \dots + p(a_{s-1}, a_s) - V(a_s) = 0.$$

The formula is thus verified.

Let now  $R$  be connected (thus  $m = 1$ ). If  $W$  is another function on  $M$  satisfying condition (2) then this formula yields

$$V(a) - V(b) = W(a) - W(b)$$

for all  $a, b \in M$ . It follows that

$$V(a) = W(a) + C$$

where  $C$  is independent on  $a \in M$ . The proof is complete.

In the sequel, we shall apply these notions to the case that the set  $M$  is the set of all natural numbers  $\leq n$  and that  $R = R(A)$  is the relation on  $M$  corresponding to a square  $n$ -rowed matrix  $A$ , i.e.  $(i, k) \in R(A)$  if and only if  $a_{ik} \neq 0$ .

Let now  $A$  be a given matrix. Choose a nonsingular matrix  $B$  and consider the iteration procedure

$$(3) \quad Bx_{n+1} = (B - A)x_n + b;$$

if the sequence  $x_n$  converges, its limit  $x$  will be a solution of  $Ax = b$ . The preceding Gauss-Seidel procedure is clearly equivalent to the ordinary Ritz procedure

$$(4) \quad x_{n+1} = B^{-1}(B - A)x_n + B^{-1}b.$$

It is therefore convenient to introduce the following abbreviation: given  $A$ , we shall denote by  $\lambda(B)$  the spectral radius of  $B^{-1}(B - A)$ . The number  $\lambda(B)$  may be considered as a measure of the convergence-rate of the procedure (3). The question of estimating  $\lambda(B)$  as a function of  $B$  is of considerable practical importance.

Suppose now that  $A \in \mathbf{K}$  and that we choose a matrix  $B \in \mathbf{Z}$  and  $B \geq A$ . According to (2,5) the matrix  $B$  belongs to  $\mathbf{K}$  as well so that, in particular,  $B$  will be nonsingular. Further,  $\lambda(B) = p(E - B^{-1}A)$  and we see from 6° of (2,5) that  $\lambda(B) < 1$  so that the procedure (3) is convergent.

The following theorem on the monotonic dependence was proved for a symmetric matrix  $A$  in [1], for the general case in [3]:

(3,3) *Let  $A \in \mathbf{K}$  and let  $B_1, B_2$  be two matrices from  $\mathbf{Z}$  such that  $A \leq B_1 \leq B_2$ . Then  $\lambda(B_1) \leq \lambda(B_2)$ .*

The proof follows immediately from (2,6).

(3,4) *Let  $A \in \mathbf{K}$  be symmetric. Suppose that  $B \geq A$ . Put  $D = B + B^* - A$  and suppose that  $D \in \mathbf{Z}$ . Then  $B \in \mathbf{K}$ ,  $D \in \mathbf{K}$  and  $D$  is symmetric.*

Proof. If  $i \neq k$ , we have  $b_{ik} + b_{ki} \leq a_{ik}$  since  $D \in \mathbf{Z}$ . Since  $B \geq A$ , we have  $-b_{ik} \leq -a_{ik}$  which, together with the preceding inequality, yields  $b_{ki} \leq 0$ . We have thus  $B \in \mathbf{Z}$  so that  $B \in \mathbf{K}$  by (2;4,6). Since  $B \geq A$ , we have  $D \geq A$  as well and  $D \in \mathbf{Z}$  by assumption. It follows that  $D \in \mathbf{K}$ .

In the sequel, the matrix  $B$  will be taken in the form  $B = D - C^*$  where  $D$  is a symmetric matrix of class  $\mathbf{K}$  and  $C \geq 0$  is such that  $A = D - C - C^*$ . In the following theorem estimates of  $\lambda(B)$  will be given in terms of  $\lambda(D)$  using the methods of section 2:

(3,5) **Theorem.** *Let  $A$  be a symmetric positive definite matrix and  $A \in \mathbf{Z}$ . Let  $A = D - C - C^*$  where  $D \in \mathbf{K}$  and  $C \geq 0$ . Then,  $B = D - C^*$  belongs to  $\mathbf{K}$  and*

$$(\lambda(D))^2 \leq \lambda(B) \leq \frac{\lambda(D)}{2 - \lambda(D)}.$$

*Suppose that  $A$  is irreducible. Then  $\lambda(B) = (\lambda(D))^2$  if and only if  $R(D) \cup R(C) \cup R(C^*)$  is a conservative decomposition of  $R(A)$ .*

Proof. Clearly  $B \in \mathbf{Z}$  and  $B = A + C \geq A$ . Since  $A \in \mathbf{K}$  we have  $B \in \mathbf{K}$  as well according to (2;4,6). Now let  $\sigma > \lambda(B)$ ; since  $\lambda(B) = p(B^{-1}(B - A)) = p(B^{-1}C)$ , the matrix  $\sigma - B^{-1}C$  belongs to  $\mathbf{K}$  by (2,1). Further,  $\sigma B - C \in \mathbf{Z}$  and  $\sigma B - C = B(\sigma - B^{-1}C)$  where both  $B$  and  $\sigma - B^{-1}C$  belong to  $\mathbf{K}$ . It follows from (2,7) that  $\sigma B - C \in \mathbf{K}$ ; clearly  $\sigma B^* - C^* \in \mathbf{K}$  as well. Now take  $\alpha = \frac{1}{2}$  and apply theorem (2,11) to the matrices  $\sigma B - C$  and  $\sigma B^* - C^*$ . It follows that  $g(\sigma B - C, \sigma B^* - C^*) \in$

$\in \mathbf{K}$ . Denote by  $W$  the matrix  $\sigma D - \sigma^{\frac{1}{2}} C - \sigma^{\frac{1}{2}} C^*$  so that  $W \in \mathbf{Z}$ . To show that  $W \in \mathbf{K}$ , it suffices, by (2;4,6), to show that  $W \geq g(\sigma B - C, \sigma B^* - C^*)$ . Indeed,

$$(5) \quad w_{ii} = \sigma d_{ii} - 2\sigma^{\frac{1}{2}} c_{ii} \geq \sigma(d_{ii} - c_{ii}) - c_{ii};$$

for  $i \neq k$

$$w_{ik} = \sigma d_{ik} - \sigma^{\frac{1}{2}}(c_{ik} + c_{ki}) \leq 0$$

and

$$(\sigma d_{ik} - \sigma^{\frac{1}{2}}(c_{ik} + c_{ki}))^2 \leq (\sigma(d_{ik} - c_{ik}) - c_{ki})(\sigma(d_{ik} - c_{ki}) - c_{ik})$$

since

$$(6) \quad 0 \leq -\sigma(1 - \sigma^{\frac{1}{2}})^2 d_{ik}(c_{ik} + c_{ki}) + (1 - \sigma)^2 c_{ik}c_{ki}.$$

We have thus shown that  $W \in \mathbf{K}$ . It follows that  $\sigma^{\frac{1}{2}} D - C - C^* \in \mathbf{K}$  as well. Denote by  $F$  the matrix  $\sigma^{\frac{1}{2}} - D^{-1}(C + C^*)$  so that  $F \in \mathbf{Z}$ . Since  $DF = \sigma^{\frac{1}{2}} D - C - C^* \in \mathbf{K}$  and  $D \in \mathbf{K}$ , it follows from (2,8) that  $F \in \mathbf{K}$  whence

$$\sigma^{\frac{1}{2}} > p(D^{-1}(C + C^*)) = p(D^{-1}(D - A)) = \lambda(D).$$

To prove the estimate of  $\lambda(B)$  from above, we shall denote by  $M$  the matrix

$$\frac{p_2}{2 - p_2} E - (D - C^*)^{-1} C$$

where  $p_2 = \lambda(D)$ .

The matrix  $(D - C^*)^{-1} C$  is nonnegative and  $M \in \mathbf{Z}$ . We know already that  $B \in \mathbf{K}$ . Let us consider the matrix

$$BM = \frac{p_2}{2 - p_2} (D - C^*) - C.$$

The matrix  $p_2 D - (C + C^*)$  belongs to  $\mathbf{K}_0$  by (2,1) and is, accordingly, nonnegative definite.

Since

$$BM + (BM)^* = \frac{2p_2}{2 - p_2} \left[ D - \frac{1}{p_2} (C + C^*) \right]$$

is nonnegative definite as well and  $BM \in \mathbf{Z}$ , it follows from lemma (2,12) that  $BM \in \mathbf{K}_0$ . An application of (2,8) shows that  $M \in \mathbf{K}_0$ . It follows that  $p_2/(2 - p_2) \geq p[(D - C^*)^{-1} C] = \lambda(B)$ .

Suppose now that  $\lambda(B) = \lambda(D)^2$ . We shall distinguish two cases.

If  $\lambda(D) = 0$ , we shall show that  $C = 0$ . Indeed, we have  $p(D^{-1}(C + C^*)) = \lambda(D) = 0$  and  $D^{-1}$ , being inverse to a matrix of class  $\mathbf{K}$ , has positive diagonal elements. Since  $C + C^*$  is nonnegative and symmetric, it follows from lemma (2,2) that  $C + C^* = 0$ . Since  $C \geq 0$ , we have  $C = 0$  as well. It is easy to see that, conver-

sely,  $C = 0$  implies  $\lambda(B) = \lambda(D) = 0$ . The assertion of the theorem is easily seen to be valid.

Suppose now that  $\lambda(D) \neq 0$  and that  $A$  is irreducible. Write  $\tau$  for  $\lambda(B)$  and observe that  $\tau B - C$  is singular. Further  $g(\tau B - C, \tau B^* - C^*) \leq \tau D - \tau^{\frac{1}{2}}C - \tau^{\frac{1}{2}}C^* = \tau^{\frac{1}{2}}(\tau^{\frac{1}{2}}D - C - C^*) = \tau^{\frac{1}{2}}(\lambda(D)D - C - C^*) = \tau^{\frac{1}{2}}D(\lambda(D) - D^{-1}(D - A))$  and this last matrix is singular. Since  $\tau \neq 0$  and  $D - C - C^* = A$  is irreducible, the matrix  $\tau D - \tau^{\frac{1}{2}}C - \tau^{\frac{1}{2}}C^*$  is irreducible as well. By lemma (2,4) we have

$$g(\tau B - C, \tau B^* - C^*) = \tau D - \tau^{\frac{1}{2}}C - \tau^{\frac{1}{2}}C^*.$$

It follows that equality is attained both in (5) and (6) for  $\sigma = \tau$ . Equation (5) yields  $c_{ii} = 0$  for all  $i$ . From (6) we obtain that for each  $i, k, i \neq k$ , at most one of the numbers  $d_{ik}, c_{ik}, c_{ki}$  is different from zero.

We know already that both matrices  $\tau B - C$  and  $\tau B^* - C^*$  are singular. Clearly they are irreducible as well so that there exist (essentially unique) vectors  $x > 0$  and  $y > 0$  for which  $(\tau B - C)x = 0$  and  $(\tau B^* - C^*)y = 0$ . Further we have just seen that  $g(\tau B - C, \tau B^* - C^*) = \tau D - \tau^{\frac{1}{2}}C - \tau^{\frac{1}{2}}C^*$  is singular and irreducible.

It follows from (2,11) that there exists a positive diagonal matrix  $H$  such that

$$(7) \quad (\tau B - C)X = H(\tau B^* - C^*)Y$$

where  $X = \text{diag}(x_1, \dots, x_n)$  and  $Y = \text{diag}(y_1, \dots, y_n)$ . On comparing the diagonal elements and taking into account the fact that  $c_{ii} = 0$  we obtain for the diagonal elements  $h(i)$  of  $H$  the equation

$$h(i) = \frac{x_i}{y_i}.$$

Now let  $i \neq k$ . If  $c_{ik} \neq 0$ , then  $d_{ik} = 0$  and  $c_{ki} = 0$  and it follows from (7) that  $-c_{ik}x_k = -h(i)\tau c_{ik}y_k$ , or, in other words,

$$(8) \quad \tau h(i) = h(k).$$

If  $d_{ik} \neq 0$ , we have  $c_{ik} = c_{ki} = 0$  and it follows in the same way that

$$(9) \quad h(i) = h(k).$$

For  $i \neq k$ , let us define a number  $p(i, k)$  in the following manner:

$$\begin{aligned} p(i, k) &= -1 \quad \text{if } c_{ik} \neq 0, \\ p(i, k) &= 1 \quad \text{if } c_{ki} \neq 0, \\ p(i, k) &= 0 \quad \text{otherwise.} \end{aligned}$$

This is possible since  $c_{ik}c_{ki} = 0$  for all  $i, k$ .

Since  $A = D - C - C^*$ , we see that  $a_{ik} \neq 0$  if and only if exactly one of the

elements  $d_{ik}, c_{ik}, c_{ki}$  is different from zero. This enables us to replace (8) and (9) by a single formula

$$\frac{h(i)}{h(k)} = \tau^{p(k,i)}$$

whenever  $a_{ik} \neq 0$ .

Suppose now that  $i_1, i_2, \dots, i_m$  is a cycle in  $R(A)$ ; in other words, all the elements  $a_{i_1 i_2}, a_{i_2 i_3}, \dots, a_{i_{m-1} i_m}, a_{i_m i_1}$  are different from zero. Clearly

$$\frac{h(i_1)}{h(i_2)} \frac{h(i_2)}{h(i_3)} \dots \frac{h(i_{m-1})}{h(i_m)} \frac{h(i_m)}{h(i_1)} = 1$$

whence,  $\tau$  being different from 1,  $p(i_1, i_2) + p(i_2, i_3) + \dots + p(i_{m-1}, i_m) + p(i_m, i_1) = 0$ .

Thus,  $R(D) \cup R(C) \cup R(C^*)$  is a conservative decomposition of  $R(A)$ .

Conversely, it is easily seen that if  $R(D) \cup R(C) \cup R(C^*)$  is a conservative decomposition of  $R(A)$  then  $(\lambda(D))^2 = \lambda(B)$ .

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#### Резюме

### НЕКОТОРЫЕ РЕЗУЛЬТАТЫ О МАТРИЦАХ КЛАССА $K$ И ИХ ПРИМЕНЕНИЯ К СКОРОСТИ СХОДИМОСТИ ИТЕРАТИВНЫХ МЕТОДОВ

МИРОСЛАВ ФИДЛЕР, ВЛАСТИМИЛ ПТАК, (Miroslav Fiedler, Vlastimil Pták), Прага

Новые результаты и уточнения известных результатов о матрицах классов  $K$  и  $K_0$  применяются к изучению скорости сходимости обобщенных итерационных методов Гаусса-Зейделя. Основная теорема обобщает результаты Р. С. Варги,

следовательно которому консервативные методы имеют наибольшую скорость сходимости среди циклических итеративных методов для матриц типа Янга  $A$ .

Если  $A$  данная матрица и  $B$  некоторая невырожденная матрица, потом скорость сходимости итеративного метода

$$Bx_{n+1} = (B - A)x_n + b$$

измеряется спектральным радиусом матрицы  $B^{-1}(B - A)$ , обозначаемым  $\lambda(B)$ .

В главной теореме 5,5 доказывается следующая оценка для  $\lambda(B)$ : Если  $A$  симметрическая, положительно определенная матрица такая, что  $a_{ik} \leq 0$  для  $i \neq k$ , и если  $A = D - C - C^*$  ( $C^*$  — транспонированная матрица к  $C$ ), где  $C \geq 0$  и  $D$  положительно определенная матрица такая, что  $d_{ik} \leq 0$  для  $i \neq k$ , потом

$$[\lambda(D)]^2 \leq \lambda(B) \leq \lambda(D)/(2 - \lambda(D))$$

Дается комбинаторная характеристика случая равенства в левом неравенстве.