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QUADRATIC CONVERGENCE  
OF MONOTONE ITERATIONS  
OF DIFFERENTIAL-ALGEBRAIC EQUATIONS

ANITA DĄBROWICZ-TLĄŁKA — TADEUSZ JANKOWSKI

(Communicated by Milan Medved')

ABSTRACT. The general quasilinearization method is applied to differential-algebraic equations with initial conditions showing that corresponding linear monotone iterations converge to a unique solution.

1.

Consider the following differential-algebraic equations of the form

$$\begin{aligned}x'(t) &= f(t, x(t), y(t)), & t \in J = [0, b], & \quad x(0) = x_0, \\0 &= g(t, x(t), y(t)), & t \in J, & \end{aligned} \tag{1}$$

where  $f, g \in C(J \times \mathbb{R} \times \mathbb{R}, \mathbb{R})$  and  $x_0 \in \mathbb{R}$  are given. By a solution of (1) we mean a pair  $(x, y) \in C^1(J, \mathbb{R}) \times C(J, \mathbb{R})$  for which equations (1) are satisfied.

To find a solution of (1) we can construct some iterations showing that under some assumptions they are convergent to this solution (see, for example [1], [4], [7]). In [6], approximate solution for (1) is constructed by corresponding numerical procedures while in [5] the existence of extremal solutions is proved for a special case of (1). Method based on lower and upper solutions combined with monotone iterations is very useful too (for details, see [8], [9]). In [3] such approach is given for problem (1) and it is proved that the corresponding monotone sequences converge quadratically to the unique solution of problem (1) if among other things we assume that  $f$  and  $g$  are  $\Omega$ -convex functions. The purpose of this paper is to continue this topic, that is, we show that when we split  $f$  and  $g$  into the sum of two  $\Omega$ -convex or  $\Omega$ -concave functions we can obtain a result for (1) with the same conclusion as in [3]. An example is given at the end of this paper.

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## 2.

Let us introduce the following definition:

**DEFINITION 1.** A pair  $(y_0, u_0) \in C^1(J, \mathbb{R}) \times C(J, \mathbb{R})$  is said to be a *lower solution* of (1) if

$$\begin{aligned} y_0'(t) &\leq f(t, y_0(t), u_0(t)), & t \in J, & \quad y_0(0) \leq x_0, \\ 0 &\leq g(t, y_0(t), u_0(t)), & t \in J, \end{aligned} \quad (2)$$

and a pair  $(z_0, w_0)$  is an *upper solution* of (1) if the above inequalities are reversed.

Put

$$\Omega = \{(t, u, v) : y_0(t) \leq u \leq z_0(t), \quad u_0(t) \leq v \leq w_0(t), \quad t \in J\}$$

and assume that  $\Omega$  is not empty.

The notation  $f \in C^{0,2,2}(\Omega, \mathbb{R})$  means that  $f, f_x, f_y, f_{xx}, f_{xy}, f_{yx}, f_{yy} \in C(\Omega, \mathbb{R})$ .

We say that a function  $\alpha \in C^{0,2,2}(\Omega, \mathbb{R})$  is  $\Omega$ -convex if  $\alpha_{xx}(t, x, y) \geq 0$ ,  $\alpha_{xy}(t, x, y) \geq 0$ ,  $\alpha_{yy}(t, x, y) \geq 0$  for  $(t, x, y) \in \Omega$ , and it is  $\Omega$ -concave if the above inequalities are reversed.

In this paper we shall discuss problem (1) when  $f$  and  $g$  can be split as the sum of two functions, namely  $f = F + P$ ,  $g = G + Q$  assuming that  $F$  and  $G$  are  $\Omega$ -convex while  $P$  and  $Q$  are  $\Omega$ -concave.

For given functions  $F, G, P$  and  $Q$  let us define some functions by the following relations for convenience,

$$\begin{aligned} V_1(t, y, z, u, w) &= F_x(t, y, u) + P_x(t, z, w), \\ V_2(t, y, z, u, w) &= F_y(t, y, u) + P_y(t, z, w), \\ W_1(t, y, z, u, w) &= G_x(t, y, u) + Q_x(t, z, w), \\ W_2(t, y, z, u, w) &= G_y(t, y, u) + Q_y(t, z, w). \end{aligned}$$

Now, we can formulate the following lemma:

**LEMMA 1.** Let  $f = F + P$  and  $F, P \in C^{0,2,2}(\Omega, \mathbb{R})$ . Assume that  $F$  is  $\Omega$ -convex and  $P$  is  $\Omega$ -concave. Then, for  $y_0(t) \leq \bar{y} \leq \bar{z} \leq z_0(t)$  and  $u_0(t) \leq \bar{u} \leq \bar{w} \leq w_0(t)$ , we have

$$f(t, \bar{y}, \bar{u}) - f(t, \bar{z}, \bar{w}) \leq -V_1(t, \bar{y}, \bar{z}, \bar{u}, \bar{w})[\bar{z} - \bar{y}] - V_2(t, \bar{z}, \bar{z}, \bar{u}, \bar{w})[\bar{w} - \bar{u}], \quad t \in J.$$

*Proof.* Using a mean value theorem and assumptions, we obtain

$$\begin{aligned} & f(t, \bar{y}, \bar{u}) - f(t, \bar{z}, \bar{w}) \\ &= f(t, \bar{y}, \bar{u}) - f(t, \bar{z}, \bar{u}) + f(t, \bar{z}, \bar{u}) - f(t, \bar{z}, \bar{w}) \\ &= -f_x(t, \xi, \bar{u})(\bar{z} - \bar{y}) - f_y(t, \bar{z}, \delta)(\bar{w} - \bar{u}) \\ &= -[F_x(t, \xi, \bar{u}) + P_x(t, \xi, \bar{u})](\bar{z} - \bar{y}) - [F_y(t, \bar{z}, \delta) + P_y(t, \bar{z}, \delta)](\bar{w} - \bar{u}) \\ &\leq -[F_x(t, \bar{y}, \bar{u}) + P_x(t, \bar{z}, \bar{u})](\bar{z} - \bar{y}) - [F_y(t, \bar{z}, \bar{u}) + P_y(t, \bar{z}, \bar{w})](\bar{w} - \bar{u}), \end{aligned}$$

where  $\bar{y} < \xi < \bar{z}$  and  $\bar{u} < \delta < \bar{w}$ . Hence we have the assertion. It ends the proof.  $\square$

**Remark 1.** Similarly if  $g = G + Q$ ,  $G, Q \in C^{0,2,2}(\Omega, \mathbb{R})$  and  $G$  is  $\Omega$ -convex while  $Q$  is  $\Omega$ -concave, then

$$g(t, \bar{y}, \bar{u}) - g(t, \bar{z}, \bar{w}) \leq -W_1(t, \bar{y}, \bar{z}, \bar{u}, \bar{u})[\bar{z} - \bar{y}] - W_2(t, \bar{z}, \bar{z}, \bar{u}, \bar{w})[\bar{w} - \bar{u}]$$

for  $y_0(t) \leq \bar{y} \leq \bar{z} \leq z_0(t)$ ,  $u_0(t) \leq \bar{u} \leq \bar{w} \leq w_0(t)$ ,  $t \in J$ .

The next lemma is useful to get some relations between elements of monotone sequences.

**LEMMA 2.** Assume that  $K_1 \in C(J, \mathbb{R})$ ,  $K_2, L \in C(J, \mathbb{R}_+)$  with  $\mathbb{R}_+ = [0, +\infty)$ . If  $(p, q) \in C^1(J, \mathbb{R}) \times C(J, \mathbb{R})$  satisfy the inequalities

$$\begin{aligned} p'(t) &\leq K_1(t)p(t) + K_2(t)q(t), & t \in J, \quad p(0) \leq 0, \\ q(t) &\leq L(t)p(t), & t \in J, \end{aligned}$$

then  $p(t) \leq 0$  and  $q(t) \leq 0$  on  $J$ .

*Proof.* Put  $K(t) = K_1(t) + K_2(t)L(t)$ ,  $t \in J$ . Under our assumptions we see that  $p'(t) \leq K(t)p(t)$ ,  $t \in J$ . This yields the inequality

$$p(t) \leq p(0) e^{\int_0^t K(\tau) d\tau}, \quad t \in J.$$

Since  $p(0) \leq 0$ , it proves that  $p(t) \leq 0$  and  $q(t) \leq 0$  on  $J$ . It ends the proof.  $\square$

The next theorem gives some sufficient conditions for the uniqueness of the solution of (1) but it does not guarantee the existence of the solution.

**THEOREM 1.** Assume that  $f, g, f_x, f_y, g_x, g_y \in C(J \times \mathbb{R} \times \mathbb{R}, \mathbb{R})$  and that there exist nonnegative constants  $\tilde{K}, \tilde{L}, \tilde{k}, \tilde{l}$ , where  $\tilde{l} > 0$  such that the conditions

- (i)  $|f(t, x, y) - f(t, \bar{x}, \bar{y})| \leq \tilde{K}|x - \bar{x}| + \tilde{L}|y - \bar{y}|$ ,
- (ii)  $|g(t, x, \bar{y}) - g(t, \bar{x}, \bar{y})| \leq \tilde{k}|x - \bar{x}|$ ,
- (iii)  $|g(t, \bar{x}, y) - g(t, \bar{x}, \bar{y})| \geq \tilde{l}|y - \bar{y}|$

are satisfied for  $t \in J$ ,  $x, y, \bar{x}, \bar{y} \in \mathbb{R}$ . Then problem (1) has at most one solution.

**P r o o f.** Assume that (1) has two distinct solutions  $(x, y)$  and  $(\bar{x}, \bar{y})$ . Put  $p = |x - \bar{x}|$ ,  $q = |y - \bar{y}|$ . Indeed  $p(0) = 0$ . Then, by assumptions, we obtain

$$\begin{aligned} \tilde{l}|y(t) - \bar{y}(t)| &\leq |g(t, x(t), \bar{y}(t)) - g(t, x(t), y(t))| \\ &= |g(t, x(t), \bar{y}(t)) - g(t, \bar{x}(t), \bar{y}(t))| \\ &\leq \tilde{k}|x(t) - \bar{x}(t)|, \quad t \in J, \end{aligned}$$

and hence

$$\begin{aligned} p(t) &\leq \int_0^t |f(s, x(s), y(s)) - f(s, \bar{x}(s), \bar{y}(s))| \, ds \\ &\leq \int_0^t [\tilde{K}p(s) + \tilde{L}q(s)] \, ds \\ &\leq \left( \tilde{K} + \frac{\tilde{L}\tilde{k}}{\tilde{l}} \right) \int_0^t p(s) \, ds, \quad t \in J. \end{aligned}$$

By Gronwall's inequality,  $p(t) = 0$ ,  $t \in J$ , and then  $q(t) = 0$ ,  $t \in J$ , showing that  $x = \bar{x}$ ,  $y = \bar{y}$ . It ends the proof.  $\square$

**Remark 2.** Note that problem (1) has at most one solution in  $\Delta$  if assumptions (i)–(iii) of Theorem 1 are satisfied in the set  $\Omega$  instead of  $J \times \mathbb{R} \times \mathbb{R}$ . Here

$$\Delta = \{(x, y) \in C^1(J, \mathbb{R}) \times C(J, \mathbb{R}) : y_0(t) \leq x(t) \leq z_0(t), \\ u_0(t) \leq y(t) \leq w_0(t), \quad t \in J\}$$

assuming that it is not empty.

### 3.

Now we can formulate the main results of this paper.

**THEOREM 2.** Assume that  $F, G, P, Q \in C^{0,2,2}(\Omega, \mathbb{R})$ ,  $f = F + P$ ,  $g = G + Q$ , and:

- (i)  $(y_0, u_0) \in C^1(J, \mathbb{R}) \times C(J, \mathbb{R})$  and  $(z_0, w_0) \in C^1(J, \mathbb{R}) \times C(J, \mathbb{R})$  are lower and upper solutions of problem (1), respectively such that  $y_0(t) \leq z_0(t)$ ,  $u_0(t) \leq w_0(t)$ ,  $t \in J$ ,
- (ii)  $F, G$  are  $\Omega$ -convex, and  $P, Q$  are  $\Omega$ -concave,
- (iii)  $W_1(t, y, z, u, w) \geq 0$  and  $V_2(t, y, z, u, w) \geq 0$  for  $(t, y, u), (t, z, w) \in \Omega$ ,
- (iv)  $g_y(t, u, v) < 0$  for  $(t, u, v) \in \Omega$ .

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Then there exist monotone sequences  $\{y_n, u_n\}$ ,  $\{z_n, w_n\}$  which converge uniformly and monotonically on  $J$  to the unique solution in  $\Delta$  of problem (1), and this convergence is quadratic.

*P r o o f.* Using assumption (ii), we see that

$$\begin{aligned} V_i(t, y, \bar{z}, u, \bar{w}) &\leq V_i(t, \bar{y}, z, \bar{u}, w), & i = 1, 2, \\ W_i(t, y, \bar{z}, u, \bar{w}) &\leq W_i(t, \bar{y}, z, \bar{u}, w), & i = 1, 2 \end{aligned} \tag{3}$$

if  $(t, y, u), (t, \bar{y}, \bar{u}), (t, z, w), (t, \bar{z}, \bar{w}) \in \Omega$ ,  $y \leq \bar{y}$ ,  $u \leq \bar{u}$ ,  $z \leq \bar{z}$ ,  $w \leq \bar{w}$ .

For  $n = 0, 1, \dots$ ,  $t \in J$  and  $y_{n+1}(0) = x_0$ ,  $z_{n+1}(0) = x_0$ , let us consider the systems

$$\begin{aligned} y'_{n+1}(t) &= f(t, y_n(t), u_n(t)) + V_1(t, n)[y_{n+1}(t) - y_n(t)] \\ &\quad + V_2(t, n)[u_{n+1}(t) - u_n(t)], \\ 0 &= g(t, y_n(t), u_n(t)) + W_1(t, n)[y_{n+1}(t) - y_n(t)] \\ &\quad + W_2(t, n)[u_{n+1}(t) - u_n(t)] \end{aligned}$$

and

$$\begin{aligned} z'_{n+1}(t) &= f(t, z_n(t), w_n(t)) + V_1(t, n)[z_{n+1}(t) - z_n(t)] \\ &\quad + V_2(t, n)[w_{n+1}(t) - w_n(t)], \\ 0 &= g(t, z_n(t), w_n(t)) + W_1(t, n)[z_{n+1}(t) - z_n(t)] \\ &\quad + W_2(t, n)[w_{n+1}(t) - w_n(t)], \end{aligned}$$

where, for  $i = 1, 2$ ,

$$\begin{aligned} V_i(t, n) &= V_i(t, y_n(t), z_n(t), u_n(t), w_n(t)), \\ W_i(t, n) &= W_i(t, y_n(t), z_n(t), u_n(t), w_n(t)). \end{aligned}$$

Note that the pair  $(y_{n+1}, u_{n+1})$  is a solution of the linear system

$$\begin{aligned} y'_{n+1}(t) &= V_1(t, n)y_{n+1}(t) + V_2(t, n)u_{n+1}(t) + \Lambda(t, n), & y_{n+1}(0) = x_0, \\ 0 &= W_1(t, n)y_{n+1}(t) + W_2(t, n)u_{n+1}(t) + \Gamma(t, n), \end{aligned} \tag{4}$$

$t \in J$ , with

$$\begin{aligned} \Lambda(t, n) &= f(t, y_n(t), u_n(t)) - V_1(t, n)y_n(t) - V_2(t, n)u_n(t), \\ \Gamma(t, n) &= g(t, y_n(t), u_n(t)) - W_1(t, n)y_n(t) - W_2(t, n)u_n(t). \end{aligned}$$

In view of assumption (iv) and (3), we see that for  $n = 0$

$$\begin{aligned} W_2(t, 0) &= W_2(t, y_0(t), z_0(t), u_0(t), w_0(t)) \\ &\leq W_2(t, z_0(t), z_0(t), w_0(t), w_0(t)) \\ &= g_y(t, z_0(t), w_0(t)) < 0, & t \in J, \end{aligned}$$

so

$$\begin{aligned} u_1(t) &= -\frac{W_1(t, 0)}{W_2(t, 0)}y_1(t) - \frac{\Gamma(t, 0)}{W_2(t, 0)}, \\ y_1'(t) &= V(t)y_1(t) + W(t), \quad y_1(0) = x_0 \end{aligned}$$

with

$$\begin{aligned} V(t) &= V_1(t, 0) - V_2(t, 0)\frac{W_1(t, 0)}{W_2(t, 0)}, \\ W(t) &= \Lambda(t, 0) - V_2(t, 0)\frac{\Gamma(t, 0)}{W_2(t, 0)}. \end{aligned}$$

It proves that system (4) has a unique solution for  $n = 0$ . It means that  $y_1$ ,  $u_1$  are well defined. By the same way we can show that  $z_1$ ,  $w_1$  are well defined, too.

By assumption (i), we have  $y_0(t) \leq z_0(t)$  and  $u_0(t) \leq w_0(t)$  for  $t \in J$ . Now, we need to show that

$$\begin{aligned} y_0(t) &\leq y_1(t) \leq z_1(t) \leq z_0(t), \\ u_0(t) &\leq u_1(t) \leq w_1(t) \leq w_0(t), \end{aligned} \quad t \in J. \quad (5)$$

To do it let  $p = y_0 - y_1$ ,  $q = u_0 - u_1$ , so  $p(0) \leq 0$ . Then, knowing that  $(y_0, u_0)$  is a lower solution of (1), we see that

$$\begin{aligned} p'(t) &\leq f(t, y_0(t), u_0(t)) - f(t, y_0(t), u_0(t)) - V_1(t, 0)[y_1(t) - y_0(t)] \\ &\quad - V_2(t, 0)[u_1(t) - u_0(t)] \\ &= V_1(t, 0)p(t) + V_2(t, 0)q(t) \end{aligned}$$

and

$$\begin{aligned} 0 &\leq g(t, y_0(t), u_0(t)) - g(t, y_0(t), u_0(t)) - W_1(t, 0)[y_1(t) - y_0(t)] \\ &\quad - W_2(t, 0)[u_1(t) - u_0(t)] \\ &= W_1(t, 0)p(t) + W_2(t, 0)q(t). \end{aligned}$$

Since  $W_2(t, 0) < 0$ ,  $t \in J$ , by (iii) and Lemma 2, we obtain  $p(t) \leq 0$ ,  $q(t) \leq 0$  on  $J$ , and as a result we get  $y_0(t) \leq y_1(t)$  and  $u_0(t) \leq u_1(t)$ ,  $t \in J$ . Similarly, we can show that  $z_1(t) \leq z_0(t)$  and  $w_1(t) \leq w_0(t)$  on  $J$ , too.

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Now, we put  $p = y_1 - z_1$ ,  $q = u_1 - w_1$ , so  $p(0) = 0$ . Then, by Lemma 1, Remark 1 and (3), we have

$$\begin{aligned} p'(t) &= f(t, y_0(t), u_0(t)) - f(t, z_0(t), w_0(t)) \\ &\quad + V_1(t, 0)[y_1(t) - y_0(t) - z_1(t) + z_0(t)] \\ &\quad + V_2(t, 0)[u_1(t) - u_0(t) - w_1(t) + w_0(t)] \\ &\leq -V_1(t, y_0(t), z_0(t), u_0(t), u_0(t))[z_0(t) - y_0(t)] \\ &\quad - V_2(t, z_0(t), z_0(t), u_0(t), w_0(t))[w_0(t) - u_0(t)] \\ &\quad + V_1(t, 0)[p(t) + z_0(t) - y_0(t)] + V_2(t, 0)[q(t) + w_0(t) - u_0(t)] \\ &\leq V_1(t, 0)p(t) + V_2(t, 0)q(t), \end{aligned}$$

and

$$\begin{aligned} 0 &= g(t, y_0(t), u_0(t)) - g(t, z_0(t), w_0(t)) \\ &\quad + W_1(t, 0)[y_1(t) - y_0(t) - z_1(t) + z_0(t)] \\ &\quad + W_2(t, 0)[u_1(t) - u_0(t) - w_1(t) + w_0(t)] \\ &\leq -W_1(t, y_0(t), z_0(t), u_0(t), u_0(t))[z_0(t) - y_0(t)] \\ &\quad - W_2(t, z_0(t), z_0(t), u_0(t), w_0(t))[w_0(t) - u_0(t)] \\ &\quad + W_1(t, 0)[p(t) + z_0(t) - y_0(t)] + W_2(t, 0)[q(t) + w_0(t) - u_0(t)] \\ &\leq W_1(t, 0)p(t) + W_2(t, 0)q(t). \end{aligned}$$

By Lemma 2, we have  $y_1(t) \leq z_1(t)$  and  $u_1(t) \leq w_1(t)$ ,  $t \in J$ . This shows that (5) is satisfied.

In the next step we have to show that  $(y_1, u_1)$  and  $(z_1, w_1)$  are lower and upper solutions of problem (1), respectively. Using (ii), (3) and Lemma 1, we obtain

$$\begin{aligned} y_1'(t) &= f(t, y_0(t), u_0(t)) - f(t, y_1(t), u_1(t)) + f(t, y_1(t), u_1(t)) \\ &\quad + V_1(t, 0)[y_1(t) - y_0(t)] + V_2(t, 0)[u_1(t) - u_0(t)] \\ &\leq -V_1(t, y_0(t), y_1(t), u_0(t), u_0(t))[y_1(t) - y_0(t)] \\ &\quad - V_2(t, y_1(t), y_1(t), u_0(t), u_1(t))[u_1(t) - u_0(t)] \\ &\quad + V_1(t, 0)[y_1(t) - y_0(t)] + V_2(t, 0)[u_1(t) - u_0(t)] \\ &\quad + f(t, y_1(t), u_1(t)) \leq f(t, y_1(t), u_1(t)), \end{aligned}$$



$$\begin{aligned}
0 &= g(t, y_0(t), u_0(t)) - g(t, y_1(t), u_1(t)) + g(t, y_1(t), u_1(t)) \\
&\quad + W_1(t, 0)[y_1(t) - y_0(t)] + W_2(t, 0)[u_1(t) - u_0(t)] \\
&\leq -W_1(t, y_0(t), y_1(t), u_0(t), u_0(t))[y_1(t) - y_0(t)] \\
&\quad - W_2(t, y_1(t), y_1(t), u_0(t), u_1(t))[u_1(t) - u_0(t)] \\
&\quad + W_1(t, 0)[y_1(t) - y_0(t)] + W_2(t, 0)[u_1(t) - u_0(t)] + g(t, y_1(t), u_1(t)) \\
&\leq g(t, y_1(t), u_1(t)),
\end{aligned}$$

and

$$\begin{aligned}
z'_1(t) &= f(t, z_0(t), w_0(t)) - f(t, z_1(t), w_1(t)) + f(t, z_1(t), w_1(t)) \\
&\quad + V_1(t, 0)[z_1(t) - z_0(t)] + V_2(t, 0)[w_1(t) - w_0(t)] \\
&\geq V_1(t, z_1(t), z_0(t), w_1(t), w_1(t))[z_0(t) - z_1(t)] \\
&\quad + V_2(t, z_0(t), z_0(t), w_1(t), w_0(t))[w_0(t) - w_1(t)] \\
&\quad + V_1(t, 0)[z_1(t) - z_0(t)] + V_2(t, 0)[w_1(t) - w_0(t)] + f(t, z_1(t), w_1(t)) \\
&\geq f(t, z_1(t), w_1(t)),
\end{aligned}$$

$$\begin{aligned}
0 &= g(t, z_0(t), w_0(t)) - g(t, z_1(t), w_1(t)) + g(t, z_1(t), w_1(t)) \\
&\quad + W_1(t, 0)[z_1(t) - z_0(t)] + W_2(t, 0)[w_1(t) - w_0(t)] \\
&\geq W_1(t, z_1(t), z_0(t), w_1(t), w_1(t))[z_0(t) - z_1(t)] \\
&\quad + W_2(t, z_0(t), z_0(t), w_1(t), w_0(t))[w_0(t) - w_1(t)] \\
&\quad + W_1(t, 0)[z_1(t) - z_0(t)] + W_2(t, 0)[w_1(t) - w_0(t)] + g(t, z_1(t), w_1(t)) \\
&\geq g(t, z_1(t), w_1(t))
\end{aligned}$$

for  $t \in J$ . This shows that  $(y_1, u_1)$ ,  $(z_1, w_1)$  are lower and upper solutions of (1), respectively.

Assume that for some  $k > 1$ ,

$$\begin{aligned}
y_0(t) &\leq y_1(t) \leq \cdots \leq y_k(t) \leq z_k(t) \leq \cdots \leq z_1(t) \leq z_0(t), \\
u_0(t) &\leq u_1(t) \leq \cdots \leq u_k(t) \leq w_k(t) \leq \cdots \leq w_1(t) \leq w_0(t),
\end{aligned}$$

$t \in J$ , and let  $(y_k, u_k)$ ,  $(z_k, w_k)$  be lower and upper solutions of problem (1), respectively.

Note that, by (ii), (iv) and (3), we have

$$W_2(t, k) \leq W_2(t, z_k(t), z_k(t), w_k(t), w_k(t)) - g_y(t, z_k(t), w_k(t)) < 0, \quad t \in J$$

Moreover,  $W_1(t, k) \geq 0$  and  $V_2(t, k) \geq 0$  by assumption (iii). It proves that system (4) for  $n - k$  has a unique solution, so the elements  $J_{k+1} \cdot u_{k+1}$  are well defined. By similar argument, we see that  $J_{k+1} \cdot w_{k+1}$  are well defined, too.

We shall prove that

$$y_k(t) \leq y_{k+1}(t) \leq z_{k+1}(t) \leq z_k(t), \quad u_k(t) \leq u_{k+1}(t) \leq w_{k+1}(t) \leq w_k(t) \quad (6)$$

for  $t \in J$ . Let  $p = y_k - y_{k+1}$ ,  $q = u_k - u_{k+1}$ , so  $p(0) = 0$ . Thus we have

$$\begin{aligned} p'(t) &\leq f(t, y_k(t), u_k(t)) - f(t, y_{k+1}(t), u_{k+1}(t)) \\ &\quad - V_1(t, k)[y_{k+1}(t) - y_k(t)] - V_2(t, k)[u_{k+1}(t) - u_k(t)] \\ &= V_1(t, k)p(t) + V_2(t, k)q(t), \end{aligned}$$

$$\begin{aligned} 0 &\leq g(t, y_k(t), u_k(t)) - g(t, y_{k+1}(t), u_{k+1}(t)) \\ &\quad - W_1(t, k)[y_{k+1}(t) - y_k(t)] - W_2(t, k)[u_{k+1}(t) - u_k(t)] \\ &= W_1(t, k)p(t) + W_2(t, k)q(t). \end{aligned}$$

This and Lemma 2 yield  $y_k(t) \leq y_{k+1}(t)$  and  $u_k(t) \leq u_{k+1}(t)$ ,  $t \in J$ . Similarly, we can prove that  $z_{k+1}(t) \leq z_k(t)$ ,  $w_{k+1}(t) \leq w_k(t)$ ,  $t \in J$ .

If we put  $p = y_{k+1} - z_{k+1}$ ,  $q = u_{k+1} - w_{k+1}$ , then  $p(0) = 0$ , and

$$\begin{aligned} p'(t) &= f(t, y_k(t), u_k(t)) - f(t, z_k(t), w_k(t)) \\ &\quad + V_1(t, k)[y_{k+1}(t) - y_k(t) - z_{k+1}(t) + z_k(t)] \\ &\quad + V_2(t, k)[u_{k+1}(t) - u_k(t) - w_{k+1}(t) + w_k(t)] \\ &\leq -V_1(t, y_k(t), z_k(t), u_k(t), u_k(t))[z_k(t) - y_k(t)] \\ &\quad - V_2(t, z_k(t), z_k(t), u_k(t), w_k(t))[w_k(t) - u_k(t)] \\ &\quad + V_1(t, k)[p(t) + z_k(t) - y_k(t)] + V_2(t, k)[q(t) + w_k(t) - u_k(t)] \\ &\leq V_1(t, k)p(t) + V_2(t, k)q(t), \end{aligned}$$

$$\begin{aligned} 0 &= g(t, y_k(t), u_k(t)) - g(t, z_k(t), w_k(t)) \\ &\quad + W_1(t, k)[y_{k+1}(t) - y_k(t) - z_{k+1}(t) + z_k(t)] \\ &\quad + W_2(t, k)[u_{k+1}(t) - u_k(t) - w_{k+1}(t) + w_k(t)] \\ &\leq -W_1(t, y_k(t), z_k(t), u_k(t), u_k(t))[z_k(t) - y_k(t)] \\ &\quad - W_2(t, z_k(t), z_k(t), u_k(t), w_k(t))[w_k(t) - u_k(t)] \\ &\quad + W_1(t, k)[p(t) + z_k(t) - y_k(t)] + W_2(t, k)[q(t) + w_k(t) - u_k(t)] \\ &\leq W_1(t, k)p(t) + W_2(t, k)q(t) \end{aligned}$$

by assumption (ii), Lemma 1 and Remark 1. Now Lemma 2 yields  $y_{k+1}(t) \leq z_{k+1}(t)$  and  $u_{k+1}(t) \leq w_{k+1}(t)$ ,  $t \in J$ , showing that (6) holds. Hence, by the method of mathematical induction, we have

$$\begin{aligned} y_0(t) &\leq y_1(t) \leq \cdots \leq y_n(t) \leq z_n(t) \leq \cdots \leq z_1(t) \leq z_0(t), \\ u_0(t) &\leq u_1(t) \leq \cdots \leq u_n(t) \leq w_n(t) \leq \cdots \leq w_1(t) \leq w_0(t) \end{aligned}$$

for all  $n$  and  $t \in J$ .

This and Dini's theorem yields that the sequences  $\{y_n, u_n\}$ ,  $\{z_n, w_n\}$  converge uniformly and monotonically to the corresponding solutions of problem (1). Since  $g_y(t, u, v) < 0$  on  $\Omega$ , all assumptions of Theorem 1 hold with

$$\begin{aligned} \tilde{K} &= \max_{(t,u,v) \in \Omega} |f_x(t, u, v)|, & \tilde{L} &= \max_{(t,u,v) \in \Omega} |f_y(t, u, v)|, \\ \tilde{k} &= \max_{(t,u,v) \in \Omega} |g_x(t, u, v)|, & \tilde{l} &= \min_{(t,u,v) \in \Omega} |g_y(t, u, v)|. \end{aligned}$$

Theorem 1 and Remark 2 say that problem (1) has at most one solution  $(x, y)$  in  $\Delta$ . Hence the sequences  $\{y_n, u_n\}$ ,  $\{z_n, w_n\}$  converge to the unique solution  $(x, y)$  of (1).

It remains to show quadratic convergence. To this end we let

$$p_{n+1}(t) = x(t) - y_{n+1}(t) \geq 0, \quad q_{n+1}(t) = z_{n+1}(t) - x(t) \geq 0, \quad t \in J,$$

$$\bar{p}_{n+1}(t) = y(t) - u_{n+1}(t) \geq 0, \quad \bar{q}_{n+1}(t) = w_{n+1}(t) - y(t) \geq 0, \quad t \in J,$$

so  $p_{n+1}(0) = q_{n+1}(0) = 0$  for  $n \geq 0$ . Using assumptions and the mean value theorem, we obtain

$$\begin{aligned} p'_{n+1}(t) &= f(t, x(t), y(t)) - f(t, y_n(t), y(t)) + f(t, y_n(t), y(t)) - f(t, y_n(t), u_n(t)) \\ &\quad + V_1(t, n)[p_{n+1}(t) - p_n(t)] + V_2(t, n)[q_{n+1}(t) - q_n(t)] \\ &= f_x(t, \xi_1(t), y(t))p_n(t) + f_y(t, y_n(t), \delta_1(t))\bar{p}_n(t) \\ &\quad + V_1(t, n)[p_{n+1}(t) - p_n(t)] + V_2(t, n)[\bar{p}_{n+1}(t) - \bar{p}_n(t)] \\ &\leq \left[ F_x(t, x(t), y(t)) - F_x(t, y_n(t), y(t)) + F_x(t, y_n(t), y(t)) \right. \\ &\quad - F_x(t, y_n(t), u_n(t)) + P_x(t, y_n(t), y(t)) - P_x(t, z_n(t), y(t)) \\ &\quad \left. + P_x(t, z_n(t), y(t)) - P_x(t, z_n(t), w_n(t)) \right] p_n(t) \\ &\quad + \left[ F_y(t, y_n(t), y(t)) - F_y(t, y_n(t), u_n(t)) + P_y(t, y_n(t), u_n(t)) \right. \\ &\quad \left. - P_y(t, z_n(t), u_n(t)) + P_y(t, z_n(t), u_n(t)) - P_y(t, z_n(t), w_n(t)) \right] \bar{p}_n(t) \\ &\quad + V_1(t, n)p_{n+1}(t) + V_2(t, n)\bar{p}_{n+1}(t) \\ &= \left\{ F_{xx}(t, \xi_2(t), y(t))p_n(t) + F_{xy}(t, y_n(t), \delta_2(t))\bar{p}_n(t) \right. \\ &\quad \left. + P_{xx}(t, \xi_3(t), y(t))[y_n(t) - z_n(t)] - P_{xy}(t, z_n(t), \delta_3(t))\bar{q}_n(t) \right\} p_n(t) \\ &\quad + \left\{ F_{yy}(t, y_n(t), \delta_4(t))\bar{p}_n(t) + P_{yx}(t, \xi_4(t), u_n(t))[y_n(t) - z_n(t)] \right. \\ &\quad \left. + P_{yy}(t, z_n(t), \delta_5(t))[u_n(t) - w_n(t)] \right\} \bar{p}_n(t) \\ &\quad + V_1(t, n)p_{n+1}(t) + V_2(t, n)\bar{p}_{n+1}(t) \\ &\leq M_1 p_{n+1}(t) + M_2 \bar{p}_{n+1}(t) + B_1 p_n^2(t) + B_2 \bar{p}_n^2(t) + B_3 q_n^2(t) + B_4 \bar{q}_n^2(t) \end{aligned}$$

CONVERGENCE OF ITERATIONS OF DIFFERENTIAL-ALGEBRAIC EQUATIONS

where  $y_n(t) < \xi_1(t), \xi_2(t) < x(t)$ ,  $y_n(t) < \xi_3(t), \xi_4(t) < z_n(t)$ ,  $u_n(t) < \delta_1(t), \delta_2(t), \delta_4(t) < y(t)$ ,  $y(t) < \delta_3(t) < w_n(t)$ ,  $u_n(t) < \delta_5(t) < w_n(t)$  on  $J$ , and

$$B_1 = A_1 + A_5 + \frac{1}{2}(A_2 + 3A_4), \quad B_2 = A_3 + A_5 + \frac{1}{2}(A_2 + 3A_6),$$

$$B_3 = \frac{1}{2}(A_4 + A_5), \quad B_4 = \frac{1}{2}(A_5 + A_6),$$

$$|f_x(t, x, y)| \leq M_1, \quad |f_y(t, x, y)| \leq M_2, \quad (t, x, y) \in \Omega,$$

$$|F_{xx}(t, x, y)| \leq A_1, \quad |F_{xy}(t, x, y)| \leq A_2, \quad |F_{yy}(t, x, y)| \leq A_3, \quad (t, x, y) \in \Omega,$$

$$|P_{xx}(t, x, y)| \leq A_4, \quad |P_{xy}(t, x, y)| \leq A_5, \quad |P_{yy}(t, x, y)| \leq A_6, \quad (t, x, y) \in \Omega.$$

Moreover

$$\begin{aligned} 0 &= g(t, x(t), y(t)) - g(t, y_n(t), y(t)) + g(t, y_n(t), y(t)) - g(t, y_n(t), u_n(t)) \\ &\quad + W_1(t, n)[p_{n+1}(t) - p_n(t)] + W_2(t, n)[\bar{p}_{n+1}(t) - \bar{p}_n(t)] \\ &= g_x(t, \xi_5(t), y(t))p_n(t) + g_y(t, y_n(t), \delta_6(t))\bar{p}_n(t) \\ &\quad + W_1(t, n)[p_{n+1}(t) - p_n(t)] + W_2(t, n)[\bar{p}_{n+1}(t) - \bar{p}_n(t)] \\ &\leq \left[ G_{xx}(t, \xi_6(t), y(t))p_n(t) + G_{xy}(t, y_n(t), \delta_7(t))\bar{p}_n(t) \right. \\ &\quad \left. + Q_{xx}(t, \xi_7(t), y(t))(y_n(t) - z_n(t)) - Q_{xy}(t, z_n(t), \delta_8(t))\bar{q}_n(t) \right] p_n(t) \\ &\quad + \left[ G_{yy}(t, y_n(t), \delta_9(t))\bar{p}_n(t) + Q_{yx}(t, \xi_8(t), u_n(t))(y_n(t) - z_n(t)) \right. \\ &\quad \left. + Q_{yy}(t, z_n(t), \delta_{10}(t))(u_n(t) - w_n(t)) \right] \bar{p}_n(t) \\ &\quad + W_1(t, n)p_{n+1}(t) + W_2(t, n)\bar{p}_{n+1}(t) \\ &\leq N_1 p_{n+1}(t) - N_2 \bar{p}_{n+1}(t) + D_1 p_n^2(t) + D_2 \bar{p}_n^2(t) + D_3 q_n^2(t) + D_4 \bar{q}_n^2(t) \end{aligned}$$

where  $y_n(t) < \xi_5(t), \xi_6(t) < x(t)$ ,  $y_n(t) < \xi_7(t), \xi_8(t) < z_n(t)$ ,  $u_n(t) < \delta_6(t), \delta_7(t), \delta_9(t) < y(t)$ ,  $y(t) < \delta_8(t) < w_n(t)$ ,  $u_n(t) < \delta_{10}(t) < w_n(t)$  on  $J$ , and

$$D_1 = C_1 + C_5 + \frac{1}{2}(C_2 + 3C_4), \quad D_2 = C_3 + C_5 + \frac{1}{2}(C_2 + 3C_6),$$

$$D_3 = \frac{1}{2}(C_4 + C_5), \quad D_4 = \frac{1}{2}(C_5 + C_6),$$

$$|g_x(t, x, y)| \leq N_1, \quad g_y(t, x, y) \leq -N_2 < 0, \quad (t, x, y) \in \Omega,$$

$$|G_{xx}(t, x, y)| \leq C_1, \quad |G_{xy}(t, x, y)| \leq C_2, \quad |G_{yy}(t, x, y)| \leq C_3, \quad (t, x, y) \in \Omega,$$

$$|Q_{x_1}(t, x, y)| \leq C_4, \quad |Q_{xy}(t, x, y)| \leq C_5, \quad |Q_{yy}(t, x, y)| \leq C_6, \quad (t, x, y) \in \Omega.$$

Hence

$$\begin{aligned} p'_{n+1}(t) &\leq M_1 p_{n+1}(t) + M_2 \bar{p}_{n+1}(t) + L_1(t), \\ \bar{p}_{n+1}(t) &\leq \frac{1}{N_2} [N_1 p_{n+1}(t) + L_2(t)], \end{aligned}$$

where

$$\begin{aligned} L_1(t) &= B_1 p_n^2(t) + B_2 \bar{p}_n^2(t) + B_3 q_n^2(t) + B_4 \bar{q}_n^2(t), \\ L_2(t) &= D_1 p_n^2(t) + D_2 \bar{p}_n^2(t) + D_3 q_n^2(t) + D_4 \bar{q}_n^2(t). \end{aligned}$$

Thus

$$p'_{n+1}(t) \leq \bar{M} p_{n+1}(t) + \frac{M_2}{N_2} L_2(t) + L_1(t) \quad \text{with} \quad \bar{M} = M_1 + \frac{M_2 N_1}{N_2}.$$

Now, the differential inequality implies

$$0 \leq p_{n+1}(t) \leq \int_0^t \left[ \frac{M_2}{N_2} L_2(s) + L_1(s) \right] e^{\bar{M}(t-s)} ds \leq S \max_{s \in J} \left[ \frac{M_2}{N_2} L_2(s) + L_1(s) \right],$$

and hence

$$\begin{aligned} \max_{t \in J} |x(t) - y_{n+1}(t)| &\leq a_1 \max_{t \in J} |x(t) - y_n(t)|^2 + a_2 \max_{t \in J} |y(t) - u_n(t)|^2 \\ &\quad + a_3 \max_{t \in J} |x(t) - z_n(t)|^2 + a_4 \max_{t \in J} |y(t) - w_n(t)|^2 \end{aligned}$$

and

$$\begin{aligned} \max_{t \in J} |y(t) - u_{n+1}(t)| &\leq b_1 \max_{t \in J} |x(t) - y_n(t)|^2 + b_2 \max_{t \in J} |y(t) - u_n(t)|^2 \\ &\quad + b_3 \max_{t \in J} |x(t) - z_n(t)|^2 + b_4 \max_{t \in J} |y(t) - w_n(t)|^2 \end{aligned}$$

for

$$\begin{aligned} a_i &= S \left[ \frac{M_2}{N_2} D_i + B_i \right], \quad b_i = \frac{1}{N_2} [N_1 a_i + D_i], \quad i = 1, 2, 3, 4, \\ &\quad \text{with} \quad S = \frac{1}{\bar{M}} e^{\bar{M}b}. \end{aligned}$$

In a similar way, using assumptions and the mean value theorem, we can obtain

$$\begin{aligned} q'_{n+1}(t) &= f(t, z_n(t), w_n(t)) - f(t, x(t), w_n(t)) + f(t, x(t), w_n(t)) \\ &\quad - f(t, x(t), y(t)) + V_1(t, n) [q_{n+1}(t) - q_n(t)] + V_2(t, n) [\bar{q}_{n+1}(t) - \bar{q}_n(t)] \end{aligned}$$

$$\begin{aligned}
 &= f_x(t, \xi_9(t), w_n(t))q_n(t) + f_y(t, x(t), \delta_{11}(t))\bar{q}_n(t) \\
 &\quad - V_1(t, n)q_n(t) + V_1(t, n)q_{n+1}(t) - V_2(t, n)\bar{q}_n(t) + V_2(t, n)\bar{q}_{n+1}(t) \\
 &\leq \left[ F_{xx}(t, \xi_{10}(t), w_n(t))(z_n(t) - y_n(t)) \right. \\
 &\quad \left. + F_{xy}(t, y_n(t), \delta_{12}(t))(w_n(t) - u_n(t)) - P_{xx}(t, \xi_{11}(t), w_n(t))q_n(t) \right] q_n(t) \\
 &\quad + \left[ F_{yy}(t, y_n(t), \delta_{13}(t))(w_n(t) - u_n(t)) + F_{yx}(t, \xi_{12}(t), w_n(t))p_n(t) \right. \\
 &\quad \left. - P_{yx}(t, \xi_{13}(t), y(t))q_n(t) - P_{yy}(t, z_n(t), \delta_{14}(t))\bar{q}_n(t) \right] \bar{q}_n(t) \\
 &\quad + V_1(t, n)q_{n+1}(t) + V_2(t, n)\bar{q}_{n+1}(t) \\
 &\leq M_1q_{n+1}(t) + M_2\bar{q}_{n+1}(t) + E_1p_n^2(t) + E_2\bar{p}_n^2(t) + E_3q_n^2(t) + E_4\bar{q}_n^2(t),
 \end{aligned}$$

where

$$\begin{aligned}
 E_1 &= \frac{1}{2}(A_1 + A_2), & E_2 &= \frac{1}{2}(A_2 + A_3), \\
 E_3 &= A_2 + A_4 + \frac{1}{2}(3A_1 + A_5), & E_4 &= A_2 + A_6 + \frac{1}{2}(3A_3 + A_5),
 \end{aligned}$$

and

$$\begin{aligned}
 y_n(t) &< \xi_{12}(t) < x(t), & y_n(t) &< \xi_{10}(t) < z_n(t), \\
 x(t) &< \xi_9(t), \xi_{11}(t), \xi_{13}(t) < z_n(t), \\
 y(t) &< \delta_{11}(t), \delta_{14}(t) < w_n(t), & \text{for } t \in J. \\
 u_n(t) &< \delta_{12}(t), \delta_{13}(t) < w_n(t)
 \end{aligned}$$

Moreover

$$\begin{aligned}
 0 &= g(t, z_n(t), w_n(t)) - g(t, x(t), w_n(t)) + g(t, x(t), w_n(t)) - g(t, x(t), y(t)) \\
 &\quad + W_1(t, n)[z_{n+1}(t) - z_n(t)] + W_2(t, n)[w_{n+1}(t) - w_n(t)] \\
 &= g_x(t, \xi_{14}(t), w_n(t))q_n(t) + g_y(t, x(t), \delta_{15}(t))\bar{q}_n(t) \\
 &\quad + W_1(t, n)q_{n+1} - W_1(t, n)q_n(t) + W_2(t, n)\bar{q}_{n+1}(t) - W_2(t, n)\bar{q}_n(t) \\
 &\leq \left[ G_{xx}(t, \xi_{15}(t), w_n(t))(z_n(t) - y_n(t)) + G_{xy}(t, y_n(t), \delta_{16}(t))(w_n(t) - u_n(t)) \right. \\
 &\quad \left. - Q_{xx}(t, \xi_{16}(t), w_n(t))q_n(t) \right] q_n(t) \\
 &\quad + \left[ G_{yx}(t, \xi_{17}(t), w_n(t))p_n(t) + G_{yy}(t, y_n(t), \delta_{17}(t))(w_n(t) - u_n(t)) \right. \\
 &\quad \left. - Q_{yx}(t, \xi_{18}(t), y(t))q_n(t) - Q_{yy}(t, z_n(t), \delta_{18}(t))\bar{q}_n(t) \right] \bar{q}_n(t) \\
 &\quad + W_1(t, n)q_{n+1}(t) + W_2(t, n)\bar{q}_{n+1}(t) \\
 &\leq N_1q_{n+1}(t) - N_2\bar{q}_{n+1}(t) + F_1p_n^2(t) + F_2\bar{p}_n^2(t) + F_3q_n^2(t) + F_4\bar{q}_n^2(t),
 \end{aligned}$$

where

$$F_1 = \frac{1}{2}(C_1 + C_2), \quad F_2 = \frac{1}{2}(C_2 + C_3),$$

$$F_3 = C_2 + C_4 + \frac{1}{2}(3C_1 + C_5), \quad F_4 = C_2 + C_6 + \frac{1}{2}(3C_3 + C_5),$$

and

$$y_n(t) < \xi_{17}(t) < x(t), \quad y_n(t) < \xi_{15}(t) < z_n(t),$$

$$x(t) < \xi_{14}(t), \xi_{16}(t), \xi_{18}(t) < z_n(t),$$

$$y(t) < \delta_{15}(t), \delta_{18}(t) < w_n(t),$$

$$u_n(t) < \delta_{16}(t), \delta_{17}(t) < w_n(t)$$

for  $t \in J$ .

This implies

$$\max_{t \in J} |x(t) - z_{n+1}(t)| \leq c_1 \max_{t \in J} |x(t) - y_n(t)|^2 + c_2 \max_{t \in J} |y(t) - u_n(t)|^2$$

$$+ c_3 \max_{t \in J} |x(t) - z_n(t)|^2 + c_4 \max_{t \in J} |y(t) - w_n(t)|^2$$

and

$$\max_{t \in J} |y(t) - w_{n+1}(t)| \leq d_1 \max_{t \in J} |x(t) - y_n(t)|^2 + d_2 \max_{t \in J} |y(t) - u_n(t)|^2$$

$$+ d_3 \max_{t \in J} |x(t) - z_n(t)|^2 + d_4 \max_{t \in J} |y(t) - w_n(t)|^2$$

with

$$c_i = S \left[ \frac{M_2}{N_2} F_i + E_i \right], \quad d_i = \frac{1}{N_2} [N_1 c_i + F_i], \quad i = 1, 2, 3, 4,$$

which yields the quadratic convergence and the proof is therefore complete.  $\square$

**Remark 3.** Theorem 2 holds if  $f = F + P$ ,  $g = G + Q$  for some  $\Omega$ -convex or  $\Omega$ -concave functions (assumption (ii)). Note that this representation holds always.

For example, if

$$\min_{(t,x,y) \in \Omega} f_{xx}(t, x, y) = A, \quad \min_{(t,x,y) \in \Omega} f_{xy}(t, x, y) = B, \quad \min_{(t,x,y) \in \Omega} f_{yy}(t, x, y) = -2C$$

for some constants  $A, B, C \geq 0$ , then it is enough to choose  $F = f - P$  with  $P(t, x, y) = -Cy^2$ .

EXAMPLE. Let us consider the nonlinear differential-algebraic problem of the form

$$x'(t) = x^2(t) + \frac{1}{3}[1 + \sin y(t) + t^2] \equiv f(t, x, y), \quad t \in J = [0, 1],$$

$$x(0) = 0,$$

$$0 = \frac{1}{5}x(t) - y(t) - y^3(t) \equiv g(t, x, y), \quad t \in J. \tag{7}$$

Note that

$$\frac{1}{3}t^2 \leq f(t, x, y) \leq 1 + x^2(t), \quad t \in J.$$

This shows that  $(y_0, u_0), (z_0, w_0)$  are lower and upper solutions of (7) with

$$\begin{aligned} y_0(t) &= \frac{1}{9}t^3, & z_0(t) &= \tan t, \\ u_0(t) &= 0, & w_0(t) &= t. \end{aligned}$$

If we take

$$\begin{aligned} F(t, x, y) &= f(t, x, y) + y^2, & P(t, x, y) &= -y^2, \\ G(t, x, y) &= \frac{1}{5}x, & Q(t, x, y) &= -y - y^3, \end{aligned}$$

then  $F, G$  are  $\Omega$ -convex,  $P, Q$  are  $\Omega$ -concave,  $f = F + P, g = G + Q$  with

$$\Omega = \{(t, u, v) : \frac{1}{9}t^3 \leq u \leq \tan t, 0 \leq v \leq t, t \in [0, 1]\}.$$

Furthermore, for  $(t, x, y), (t, \bar{x}, \bar{y}) \in \Omega$  we have

$$\begin{aligned} W_1(t, x, \bar{x}, y, \bar{y}) &= \frac{1}{5} > 0, & V_2(t, x, \bar{x}, y, \bar{y}) &= \frac{1}{3} \cos y > 0, \\ g_y(t, x, y) &= -1 - 3y^2 < 0. \end{aligned}$$

Note that all assumptions of Theorem 1 hold for  $(t, x, y), (t, \bar{x}, \bar{y}) \in \Omega$  with

$$\tilde{K} = 2 \tan 1, \quad \tilde{L} = \frac{1}{3}, \quad \tilde{k} = \frac{1}{5}, \quad \tilde{l} = 1.$$

It proves that the assertion of Theorem 2 holds for problem (7).

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