

Lubomír Kubáček

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ESTIMATION OF COVARIANCE COMPONENTS IN A REPEATED REGRESSION EXPERIMENT

LUBOMÍR KUBÁČEK

Dedicated to Academician Štefan Schwarz on the occasion of his 70th birthday

Introduction

In the regression model $\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon}$ the covariance matrix of the error vector $\boldsymbol{\varepsilon}$ is considered in the form $\boldsymbol{\Sigma} = \sum_{i=1}^m \mathbf{J}_i \mathbf{C} \mathbf{J}_i'$ [3]; $(n \times s)$ -matrices \mathbf{J}_i , $i = 1, \dots, m$ are known.

The elements of the unknown matrix \mathbf{C} are called covariance components. When $s = 1$ and $\mathbf{J}_i \mathbf{J}_i'$ is denoted \mathbf{V}_i , $i = 1, \dots, m$, the situation studied in [2] occurs. This paper completes paper [2].

The aim is to determine the estimator of the covariance components on the basis of the matrix \mathbf{S} ,

$$k\mathbf{S} = \sum_{j=1}^{k+1} (\mathbf{Y}_j - \bar{\mathbf{Y}})(\mathbf{Y}_j - \bar{\mathbf{Y}})' \left(\bar{\mathbf{Y}} = [1/(k+1)] \sum_{j=1}^{k+1} \mathbf{Y}_j \right),$$

which is generated from the $(k+1)$ -tuple stochastically independent random vectors $\mathbf{Y}_1, \dots, \mathbf{Y}_{k+1}$ with the same normal distribution $N_n(\mathbf{X}\boldsymbol{\beta}, \boldsymbol{\Sigma})$. Thus the matrix $k\mathbf{S}$ has the Wishart distribution $W_n(k, \boldsymbol{\Sigma})$ [1].

1. Assumptions and auxiliary statements

Let $(\mathcal{L}_n, \langle \cdot, \cdot \rangle)$ be a Hilbert space of symmetric $(n \times n)$ -matrices, $\langle \cdot, \cdot \rangle$ denotes the inner product given by $\langle \mathbf{A}, \mathbf{B} \rangle = \text{Tr}(\mathbf{A}\mathbf{B})$, $\mathbf{A}, \mathbf{B} \in \mathcal{L}_n$ [4]; $\text{Tr}(\mathbf{A}\mathbf{B})$ denotes the trace of the matrix $\mathbf{A}\mathbf{B}$.

Let \mathbf{J}_i , $i = 1, \dots, m$ be given $(n \times s)$ -matrices and let the covariance matrix $\boldsymbol{\Sigma}$ of the random vector $\mathbf{Y} \sim N_n(\mathbf{X}\boldsymbol{\beta}, \boldsymbol{\Sigma})$ be an element of the set

$$\boldsymbol{\Sigma}_* = \left\{ \boldsymbol{\Sigma} : \boldsymbol{\Sigma} = \sum_{i=1}^m \mathbf{J}_i \mathbf{C} \mathbf{J}_i', \mathbf{C} \in \mathcal{C} \right\},$$

where $\mathcal{C} (\subset \mathcal{L}_s)$ is a set of symmetric $(s \times s)$ -matrices which satisfies the following condition:

$$(*) \left\{ \begin{array}{l} \text{If for } \mathbf{M} \in \mathcal{S}, \text{ there exists } \mathbf{A} \in \mathcal{S}_n \text{ such that for each} \\ \text{matrix } \mathbf{\Sigma} \in \mathbf{\Sigma}^* \text{ it is } \text{Tr}(\mathbf{M}\mathbf{C}) = \text{Tr}(\mathbf{A}\mathbf{\Sigma}) \left(= \text{Tr} \left(\sum_{i=1}^m \mathbf{J}'_i \mathbf{A} \mathbf{J}_i \mathbf{C} \right) \right), \\ \text{then } \sum_{i=1}^m \mathbf{J}'_i \mathbf{A} \mathbf{J}_i = \mathbf{M}. \end{array} \right.$$

Further it is assumed that each element of $\mathbf{\Sigma}^*$ is a positive definite matrix. $g(\cdot)$ denotes the function $g(\cdot): \mathcal{C} \rightarrow \mathcal{R}$, $g(\mathbf{C}) = \text{Tr}(\mathbf{M}\mathbf{C})$, which is to be unbiasedly estimated on the basis of the realization of the matrix $k\mathbf{S} \sim W_n(k, \mathbf{\Sigma})$. (Procedure for estimating the function $g(\cdot)$ based on the realization of the vector \mathbf{Y} see in [3].) The estimator of the function $g(\cdot)$ is considered in the form $\text{Tr}(\mathbf{A}\mathbf{S})$, $\mathbf{A} \in \mathcal{S}_n$.

By the symbol $\mathcal{M}_{m,n}$ the set of $(m \times n)$ -matrices is denoted.

Definition 1.1. *The mappings*

$$\begin{aligned} \text{vec}(\cdot) &: \mathcal{M}_{m,n} \rightarrow \mathcal{R}^{mn}; \\ \text{vech}(\cdot) &: \mathcal{S}_n \rightarrow \mathcal{R}^{n(n+1)/2}; \\ (\text{cR})[\text{vec}(\cdot)] &: \mathcal{S}_n \rightarrow \mathcal{R}^{n(n+1)/2} \end{aligned}$$

are given by

$$\begin{aligned} \text{vec}(\mathbf{T}) &= (t_{1,1}, t_{2,1}, \dots, t_{m,1}; t_{1,2}, t_{2,2}, \dots, t_{m,2}; \dots; t_{1,n}, t_{2,n}, \dots, t_{m,n})'; \\ \text{vech}(\mathbf{T}) &= (t_{1,1}, t_{2,1}, \dots, t_{n,1}; t_{2,2}, t_{3,2}, \dots, t_{n,2}; \dots; t_{n-1,n-1}, t_{n,n-1}; t_{n,n})'; \\ (\text{cR})[\text{vec}(\mathbf{T})] &= (t_{1,1}, 2t_{2,1}, \dots, 2t_{n,1}; t_{2,2}, 2t_{3,2}, \dots, 2t_{n,2}; \dots; t_{n-1,n-1}, 2t_{n,n-1}; t_{n,n}). \end{aligned}$$

Here $t_{ij} = \{\mathbf{T}\}_{i,j}$ is the (i, j) -th element of the matrix \mathbf{T} .

Lemma 1.1. *For arbitrary matrices $\mathbf{A} \in \mathcal{M}_{m,n}$, $\mathbf{X} \in \mathcal{M}_{n,p}$, $\mathbf{B} \in \mathcal{M}_{p,r}$, $\mathbf{C} \in \mathcal{M}_{m,r}$, it is true that $\mathbf{A}\mathbf{X}\mathbf{B} = \mathbf{C} \Leftrightarrow (\mathbf{B}' \otimes \mathbf{A})\text{vec}(\mathbf{X}) = \text{vec}(\mathbf{C})$ (\otimes denotes the tensor product).*

PROOF is obvious.

Definition 1.2. *The mappings*

$$\begin{aligned} (\text{cC})(\cdot) &: \{\mathbf{B}' \otimes \mathbf{A} : \mathbf{A}, \mathbf{B}' \in \mathcal{M}_{p,r}\} \rightarrow \mathcal{M}_{p^2, (p+1)/2}; \\ (\text{cR})(\cdot) &: \{\mathbf{B}' \otimes \mathbf{A} : \mathbf{A}, \mathbf{B}' \in \mathcal{M}_{p,r}\} \rightarrow \mathcal{M}_{p(p+1)/2, r^2} \end{aligned}$$

are given by

$$\begin{aligned} \{(\text{cC})[\mathbf{B}' \otimes \mathbf{A}]\}_{[p+(i+i)(2-r)/2]} &= \{\mathbf{B}' \otimes \mathbf{A}\}_{(i+i+r)}, \quad i=0, 1, \dots, r-1; \\ \{(\text{cC})[\mathbf{B}' \otimes \mathbf{A}]\}_{[p+i+j-i(i+1)/2]} &= \{\mathbf{B}' \otimes \mathbf{A}\}_{(i+i+r)} + \{\mathbf{B}' \otimes \mathbf{A}\}_{(i+i-1)r+i+1}, \\ & \quad i=0, 1, \dots, r-2; \quad j=2, 3, \dots, r-i \end{aligned}$$

and

$$\begin{aligned} \{(\text{cR})[\mathbf{B}' \otimes \mathbf{A}]\}_{[p+(i+i)(2-r)/2]} &= \{\mathbf{B}' \otimes \mathbf{A}\}_{(p+i+1)}, \quad i=0, 1, \dots, p-1, \\ \{(\text{cR})[\mathbf{B}' \otimes \mathbf{A}]\}_{[p+i+j-i(i+1)/2]} &= \{\mathbf{B}' \otimes \mathbf{A}\}_{(ip+i+1)} + \{\mathbf{B}' \otimes \mathbf{A}\}_{[(i+i-1)p+i+1]}, \\ & \quad i=0, 1, \dots, p-2; \quad j=2, 3, \dots, p-i. \end{aligned}$$

Here $\{\mathbf{M}\}_j$ and $\{\mathbf{M}\}_i$ denote the j -th column and the i -th row of the matrix \mathbf{M} .

Corollary 1.1. For arbitrary matrices \mathbf{A} , $\mathbf{B}' \in \mathcal{M}_{p,r}$, $\mathbf{X} \in \mathcal{S}_r$, $\mathbf{C} \in \mathcal{S}_p$ it is true that $\mathbf{AXB} = \mathbf{C} \Leftrightarrow (\mathbf{B}' \otimes \mathbf{A})\text{vec}(\mathbf{X}) = \text{vec}(\mathbf{C}) \Leftrightarrow (\text{cR})[\text{vec}(\mathbf{C})] = (\text{cR})(\text{cC})[\mathbf{B}' \otimes \mathbf{A}]\text{vech}(\mathbf{X})$.

Lemma 1.2. The estimator $\text{Tr}(\mathbf{AS})$ of the function $g(\mathbf{C}) = \text{Tr}(\mathbf{MC})$, $\mathbf{C} \in \mathcal{C}$ is unbiased iff $\sum_{i=1}^m \mathbf{J}'_i \mathbf{A} \mathbf{J}_i = \mathbf{M}$.

Proof. It is a consequence of the relation

$$E_{\mathcal{C}}[\text{Tr}(\mathbf{AS})] = \text{Tr}(\mathbf{A}\Sigma) = \text{Tr} \left(\sum_{i=1}^m \mathbf{J}'_i \mathbf{A} \mathbf{J}_i \mathbf{C} \right),$$

$\mathbf{C} \in \mathcal{C}$ and of the assumption (*).

Lemma 1.3. The function $g(\mathbf{C}) = \text{Tr}(\mathbf{MC})$, $\mathbf{C} \in \mathcal{C}$ is unbiasedly estimable iff

$$(\text{cR})[\text{vec}(\mathbf{M})] \in \mathcal{M} \left\{ (\text{cR})(\text{cC}) \left[\sum_{i=1}^m \mathbf{J}'_i \otimes \mathbf{J}_i \right] \right\}$$

($\mathcal{M}(\mathbf{D})$ denotes the column space of the matrix \mathbf{D}).

Proof. It is a consequence of Lemma 1.2, Lemma 1.1 and Corollary 1.1.

2. Natural estimation and γ -estimation

Let the error vector $\boldsymbol{\varepsilon}$ be of the form $\boldsymbol{\varepsilon} = \mathbf{J}_1 \boldsymbol{\xi}_1 + \dots + \mathbf{J}_m \boldsymbol{\xi}_m$, $\boldsymbol{\xi}_j \sim N(\mathbf{0}, \mathbf{C})$, $j = 1, \dots, m$, where \mathbf{C} is a positive definite matrix and vectors $\boldsymbol{\xi}_j$, $j = 1, \dots, m$ are stochastically independent. As $k\mathbf{S} \sim W_n(k, \Sigma)$, then $k\mathbf{S} = \sum_{\alpha=1}^k \mathbf{Z}_{\alpha} \mathbf{Z}'_{\alpha}$, $\mathbf{Z}_{\alpha} \sim N(\mathbf{0}, \Sigma)$, $\alpha = 1, \dots, k$ and \mathbf{Z}_{α} , $\alpha = 1, \dots, k$ are stochastically independent [1]. Similarly as in [2] the vector \mathbf{Z}_{α} can be expressed in the form $\mathbf{Z}_{\alpha} = \mathbf{J}_1 \boldsymbol{\xi}_{\alpha,1} + \dots + \mathbf{J}_m \boldsymbol{\xi}_{\alpha,m}$, $\alpha = 1, \dots, k$, $\boldsymbol{\xi}_{\alpha,j} \sim N(\mathbf{0}, \mathbf{C})$ and $\boldsymbol{\xi}_{\alpha,j}$, $\alpha = 1, \dots, k$; $j = 1, \dots, m$ are stochastically independent.

The natural estimator $\hat{\mathbf{C}}$ of the matrix \mathbf{C} based on the realization of the vectors $\boldsymbol{\xi}_{\alpha,j}$, $\alpha = 1, \dots, k$, $j = 1, \dots, m$ (see also the corollary 3.1) is

$$\hat{\mathbf{C}} = [1/(mk)] \sum_{\alpha=1}^k \sum_{i=1}^m \boldsymbol{\xi}_{\alpha,i} \boldsymbol{\xi}'_{\alpha,i}$$

and the estimator of the function $g(\cdot)$ is then $\text{Tr}(\mathbf{M}\hat{\mathbf{C}})$. The difference between the unbiased estimator $\tau_u(\mathbf{S}) = \text{Tr}(\mathbf{AS})$ and the natural estimator $\text{Tr}(\mathbf{M}\hat{\mathbf{C}})$ is

$$\text{Tr}(\mathbf{AS}) - \text{Tr}(\mathbf{M}\hat{\mathbf{C}}) = (1/k) \text{Tr} \left\{ [(1/m)(\mathbf{I} \otimes \mathbf{M}) - \mathbf{J}' \mathbf{A} \mathbf{J}] \sum_{\alpha=1}^k \boldsymbol{\xi}_{\alpha} \boldsymbol{\xi}'_{\alpha} \right\},$$

where $\mathbf{J} = (\mathbf{J}_1, \mathbf{J}_2, \dots, \mathbf{J}_m)$ and $\boldsymbol{\xi}'_{\alpha} = (\boldsymbol{\xi}'_{\alpha,1}, \dots, \boldsymbol{\xi}'_{\alpha,m})$.

Definition 2.1. The estimator $\text{Tr}(\mathbf{AS})$ of the function $g(\mathbf{C}) = \text{Tr}(\mathbf{MC})$, $\mathbf{C} \in \mathcal{C}$ is the MINUE if

$$\mathbf{J}'_1 \mathbf{A} \mathbf{J}_1 + \dots + \mathbf{J}'_m \mathbf{A} \mathbf{J}_m = \mathbf{M} \quad \text{and} \quad \text{Tr}\{[(1/m)(\mathbf{I} \otimes \mathbf{M}) - \mathbf{J}' \mathbf{A} \mathbf{J}]^2\} = \min.$$

Theorem 2.1. The MINUE of the function $g(\mathbf{C}) = \text{Tr}(\mathbf{M}\mathbf{C})$, $\mathbf{C} \in \mathcal{C}$ is

$$\tau_g(\mathbf{S}) = \text{Tr} \left(\sum_{i=1}^m \mathbf{V}'^{-1} \mathbf{J}_i \mathbf{A} \mathbf{J}_i' \mathbf{V}'^{-1} \mathbf{S} \right),$$

where $\mathbf{V} = \mathbf{J}_1 \mathbf{J}'_1 + \dots + \mathbf{J}_m \mathbf{J}'_m$ and $\mathbf{\Lambda} \in \mathcal{L}$ is a matrix of Lagrange multipliers which satisfies the equation

$$(\text{cR})[\text{vec}(\mathbf{M})] = (\text{cR})(\text{cC}) \left[\sum_{i=1}^m \sum_{j=1}^m (\mathbf{J}_i' \mathbf{V}'^{-1} \mathbf{J}_j) \otimes (\mathbf{J}_i' \mathbf{V}'^{-1} \mathbf{J}_j) \right] \text{vech}(\mathbf{\Lambda}).$$

Proof. As $-2\text{Tr}\{(1/m)(\mathbf{I} \otimes \mathbf{M})\mathbf{J}' \mathbf{A} \mathbf{J}\} = -2(1/m) \text{Tr} \left(\mathbf{M} \sum_{i=1}^m \mathbf{J}'_i \mathbf{A} \mathbf{J}_i \right) = -(2/m) \text{Tr}(\mathbf{M}^2)$, then $\text{Tr}\{[(1/m)(\mathbf{I} \otimes \mathbf{M}) - \mathbf{J}' \mathbf{A} \mathbf{J}]^2\} = \text{Tr}(\mathbf{A}\mathbf{V}\mathbf{A}\mathbf{V}) - (1/m) \text{Tr}(\mathbf{M}^2)$. Thus it is sufficient to minimize $\text{Tr}(\mathbf{A}\mathbf{V}\mathbf{A}\mathbf{V})$ under the side condition $\mathbf{J}'_1 \mathbf{A} \mathbf{J}_1 + \dots + \mathbf{J}'_m \mathbf{A} \mathbf{J}_m = \mathbf{M}$. The method of Lagrange multipliers is used. The auxiliary function is $\phi(\mathbf{A}) = \text{Tr}(\mathbf{A}\mathbf{V}\mathbf{A}\mathbf{V}) - 2\text{Tr}[\boldsymbol{\kappa}'(\mathbf{J}'_1 \mathbf{A} \mathbf{J}_1 + \dots + \mathbf{J}'_m \mathbf{A} \mathbf{J}_m - \mathbf{M})]$, where $\boldsymbol{\kappa}'$ is a matrix of Lagrange multipliers.

$$\begin{aligned} \left(\frac{\partial \phi(\mathbf{A})}{\partial \mathbf{A}} \right) &= 4\mathbf{V}\mathbf{A}\mathbf{V} - 4 \sum_{i=1}^m \mathbf{J}_i (1/2)(\boldsymbol{\kappa} + \boldsymbol{\kappa}') \mathbf{J}'_i \\ - 2 \text{diag} \cdot \left\{ \mathbf{V}\mathbf{A}\mathbf{V} - \sum_{i=1}^m \mathbf{J}_i (1/2)(\boldsymbol{\kappa} + \boldsymbol{\kappa}') \mathbf{J}'_i \right\} &= \mathbf{0} \Leftrightarrow \mathbf{V}\mathbf{A}\mathbf{V} = \sum_{i=1}^m \mathbf{J}_i \mathbf{\Lambda} \mathbf{J}'_i, \end{aligned}$$

where $\mathbf{\Lambda} = (1/2)(\boldsymbol{\kappa} + \boldsymbol{\kappa}')$. For each matrix $\mathbf{D} \in \mathcal{L}_n$ satisfying the condition $\mathbf{J}'_1 \mathbf{D} \mathbf{J}_1 + \dots + \mathbf{J}'_m \mathbf{D} \mathbf{J}_m = \mathbf{0}$ there holds

$$\text{Tr}(\mathbf{D}\mathbf{V}\mathbf{A}\mathbf{V}) = \text{Tr} \left(\sum_{i=1}^m \mathbf{J}'_i \mathbf{D} \mathbf{J}_i \mathbf{\Lambda} \right) = 0$$

and thus

$$\text{Tr}[(\mathbf{A} + \mathbf{D})\mathbf{V}(\mathbf{A} + \mathbf{D})\mathbf{V}] = \text{Tr}(\mathbf{A}\mathbf{V}\mathbf{A}\mathbf{V}) + \text{Tr}(\mathbf{D}\mathbf{V}\mathbf{D}\mathbf{V}) \geq \text{Tr}(\mathbf{A}\mathbf{V}\mathbf{A}\mathbf{V})$$

because of $\text{Tr}(\mathbf{D}\mathbf{V}\mathbf{D}\mathbf{V}) = \text{Tr}(\mathbf{J}' \mathbf{D} \mathbf{J} \mathbf{J}' \mathbf{D} \mathbf{J}) \geq 0$. Therefore the matrix

$$\mathbf{A} = \sum_{j=1}^m \mathbf{V}^{-1} \mathbf{J}_j \mathbf{\Lambda} \mathbf{J}'_j \mathbf{V}^{-1}$$

with $\mathbf{\Lambda}$ satisfying

$$\sum_{i=1}^m \sum_{j=1}^m \mathbf{J}'_i \mathbf{V}'^{-1} \mathbf{J}_j \mathbf{\Lambda} \mathbf{J}'_j \mathbf{V}'^{-1} \mathbf{J}_i = \mathbf{M}$$

(unbiasedness) minimizes the quantity $\text{Tr}(\mathbf{A}\mathbf{V}\mathbf{A}\mathbf{V})$ under the side condition $\mathbf{J}'_1 \mathbf{A} \mathbf{J}_1 + \dots + \mathbf{J}'_m \mathbf{A} \mathbf{J}_m = \mathbf{M}$. The rest of the proof is a consequence of Corollary 1.1.

In the following the elements of the matrix \mathbf{C} are assumed to be approximately known. The corresponding matrix of approximate values is denoted by γ and it is assumed to be positive definite; $\gamma = \gamma^{1/2} \gamma'^{1/2}$. The following denotation is used

$$\mathbf{J}_i^{(\gamma)} = \mathbf{J}_i \gamma^{1/2}, \quad i = 1, \dots, m;$$

$$\xi_{\alpha, j}^{(\gamma)} = \gamma^{-1/2} \xi_{\alpha, j}, \quad j = 1, \dots, m; \quad \alpha = 1, \dots, k$$

(obviously $\xi_{\alpha, j}^{(\gamma)} \sim N_s(\mathbf{0}, \gamma^{-1/2} \mathbf{C} \gamma^{-1/2})$);

$$\xi^{(\gamma')} = (\xi_{\alpha, 1}^{(\gamma')}, \dots, \xi_{\alpha, m}^{(\gamma')});$$

$$\mathbf{M}^{(\gamma)} = \gamma^{1/2} \mathbf{M} \gamma'^{1/2};$$

$$\mathbf{C}^{(\gamma)} = \gamma'^{-1/2} \mathbf{C} \gamma^{1/2};$$

$$\mathbf{J}^{(\gamma)} = (\mathbf{J}_1^{(\gamma)}, \dots, \mathbf{J}_m^{(\gamma)}).$$

The natural estimator of the matrix $\mathbf{C}^{(\gamma)}$ based on $\xi_{\alpha, j}^{(\gamma)}$, $j = 1, \dots, m; \alpha = 1, \dots, k$, is

$$\hat{\mathbf{C}}^{(\gamma)} = [1/(km)] \sum_{\alpha=1}^k \sum_{j=1}^m \xi_{\alpha, j}^{(\gamma)} \xi_{\alpha, j}^{(\gamma)}$$

and the estimator of the function $g(\mathbf{C}) = \text{Tr}(\mathbf{M}\mathbf{C}) = \text{Tr}(\mathbf{M}^{(\gamma)}\mathbf{C}^{(\gamma)})$ resulting from it is

$$\text{Tr}(\mathbf{M}^{(\gamma)}\hat{\mathbf{C}}^{(\gamma)}) = \text{Tr} \left[(1/m)(\mathbf{I} \otimes \mathbf{M}^{(\gamma)}) (1/k) \sum_{\alpha=1}^k \xi_{\alpha}^{(\gamma)} \xi_{\alpha}^{(\gamma)} \right].$$

The difference between the unbiased estimator $\text{Tr}(\mathbf{A}\mathbf{S})$ and the natural γ -estimator $\text{Tr}(\mathbf{M}^{(\gamma)}\hat{\mathbf{C}}^{(\gamma)})$ is

$$\text{Tr}(\mathbf{A}\mathbf{S}) - \text{Tr}(\mathbf{M}^{(\gamma)}\hat{\mathbf{C}}^{(\gamma)}) =$$

$$= \text{Tr} \left\{ [\mathbf{J}^{(\gamma)'} \mathbf{A} \mathbf{J}^{(\gamma)} - (1/m)(\mathbf{I} \otimes \mathbf{M}^{(\gamma)})] \sum_{\alpha=1}^k \xi_{\alpha}^{(\gamma)} \xi_{\alpha}^{(\gamma)} \right\}.$$

Definition 2.2. The estimator $\tau_g(\mathbf{S}) = \text{Tr}(\mathbf{A}\mathbf{S})$ of the function $g(\mathbf{C}) = \text{Tr}(\mathbf{M}\mathbf{C})$, $\mathbf{C} \in \mathcal{C}$ is the MINU γ E if

$$\mathbf{J}_1' \mathbf{A} \mathbf{J}_1 + \dots + \mathbf{J}_m' \mathbf{A} \mathbf{J}_m = \mathbf{M} \quad \text{and} \quad \text{Tr} \{ [\mathbf{J}^{(\gamma)'} \mathbf{A} \mathbf{J}^{(\gamma)} - (1/m)(\mathbf{I} \otimes \mathbf{M}^{(\gamma)})]^2 \} = \min.$$

Theorem 2.2. The MINU γ E of the function $g(\mathbf{C}) = \text{Tr}(\mathbf{M}\mathbf{C})$, $\mathbf{C} \in \mathcal{C}$, is

$$\tau_g(\mathbf{S}) = \text{Tr} \left(\sum_{i=1}^m \mathbf{V}^{(\gamma)-1} \mathbf{J}_i \mathbf{\Lambda}^{(\gamma)} \mathbf{J}_i' \mathbf{V}^{(\gamma)-1} \mathbf{S} \right),$$

where $\mathbf{V}^{(\gamma)} = \sum_{i=1}^m \mathbf{J}_i \gamma \mathbf{J}_i'$. The matrix $\mathbf{\Lambda}^{(\gamma)} \in \mathcal{L}_s$ is a solution of the matrix equation

$$\mathbf{M} = \sum_{i=1}^m \sum_{j=1}^m \mathbf{J}_i' \mathbf{V}^{(\gamma)-1} \mathbf{J}_j \mathbf{\Lambda}^{(\gamma)} \mathbf{J}_j' \mathbf{V}^{(\gamma)-1} \mathbf{J}_i.$$

This equation can be expressed in the form

$$(**) \quad (\mathbf{cR})[\text{vec}(\mathbf{M})] = (\mathbf{cR})(\mathbf{cC}) \left[\sum_{i=1}^m \sum_{j=1}^m (\mathbf{J}'_i \mathbf{V}^{(\gamma)} \mathbf{J}_i) \otimes (\mathbf{J}'_i \mathbf{V}^{(\gamma)} \mathbf{J}_i) \right] \text{vech}(\mathbf{\Lambda}^{(\gamma)}).$$

The proof is analogous to the proof of Theorem 2.1.

3. Properties of the MINU γ E

Theorem 3.1. *The MINU γ E of the function $g(\mathbf{C}) = \text{Tr}(\mathbf{MC})$, $\mathbf{C} \in \mathcal{C}$ is the locally best estimator in $\gamma \in \mathcal{C}$.*

Proof. With respect to Lemma 1.4 [2] (the denotation $\mathbf{V}^{(\gamma)} = \mathbf{\Sigma}$ is used) we have

$$\text{cov} \left\{ \text{Tr} \left(\sum_{i=1}^m \mathbf{\Sigma} \mathbf{J}_i \mathbf{\Lambda}^{(\gamma)} \mathbf{J}'_i \mathbf{\Sigma}^{-1} \mathbf{S} \right), \text{Tr}(\mathbf{A}_0 \mathbf{S}) \right\} = (2/k) \text{Tr} \left(\sum_{i=1}^m \mathbf{J}'_i \mathbf{A}_0 \mathbf{J}_i \mathbf{\Lambda}^{(\gamma)} \right).$$

The last expression is zero for each matrix $\mathbf{A}_0 \in \mathcal{L}_n$ satisfying the condition

$$\forall \{\gamma \in \mathcal{C}\} E_{\gamma}[\text{Tr}(\mathbf{A}_0 \mathbf{S})] = 0 \left(\Leftrightarrow \forall \{\gamma \in \mathcal{C}\} \text{Tr} \left(\sum_{i=1}^m \mathbf{J}'_i \mathbf{A}_0 \mathbf{J}_i \gamma \right) = 0 \right).$$

With respect to the assumption (*) this condition is equivalent with $\sum_{i=1}^m \mathbf{J}'_i \mathbf{A}_0 \mathbf{J}_i = \mathbf{0}$.

On the basis of the Lehmann—Scheffé theorem (see also Lemma 1.5 [2]) the statement is immediately proved.

Remark 3.1. The matrix \mathbf{A} from the MINU γ E minimizes the quantity $\text{Tr}(\mathbf{AV}^{(\gamma)}\mathbf{AV}^{(\gamma)})$ under the side condition of the unbiasedness $\sum_{i=1}^m \mathbf{J}'_i \mathbf{A} \mathbf{J}_i = \mathbf{M}$. If $\mathbf{C} = \gamma$, then $\mathbf{V}^{(\gamma)}$ is the covariance matrix of the vector \mathbf{Y} and regarding Lemma 1.4 [2] $(2/k)\text{Tr}(\mathbf{AV}^{(\gamma)}\mathbf{AV}^{(\gamma)})$ is dispersion of the statistic $\text{Tr}(\mathbf{AS})$.

Lemma 3.1. *The Fisher information matrix of the distribution of the matrix*

$$k\mathbf{S} \sim W_n \left(k, \mathbf{\Sigma} = \sum_{i=1}^m \mathbf{J}_i \mathbf{C} \mathbf{J}'_i \right)$$

with respect to the parameter $\text{vech}(\mathbf{C})$ is

$$\mathbf{F}(\mathbf{C}) = (k/2)(\mathbf{cR})(\mathbf{cC}) \left[\sum_{i=1}^m \sum_{j=1}^m (\mathbf{J}'_i \mathbf{\Sigma}^{-1} \mathbf{J}_i) \otimes (\mathbf{J}'_i \mathbf{\Sigma}^{-1} \mathbf{J}_i) \right].$$

Proof. The probability density function of the matrix \mathbf{S} is

$$f(\mathbf{S}, \mathbf{C}) = (k/2)^{kn} 2\pi^{-n(n+1)/2} \left\{ \prod_{j=1}^k [(1/2)(k+1-j)] \right\}^{-1} \det(\mathbf{S}) \cdot \exp \{ -(k/2) \text{Tr}(\mathbf{\Sigma}^{-1} \mathbf{S}) \} [\det(\mathbf{\Sigma})]^{-k/2},$$

where $\Sigma = \sum_{i=1}^m \mathbf{J}_i \mathbf{C} \mathbf{J}_i'$. If in the following $\{\mathbf{C}\}_{i,i} = c_{i,i}$ and the relations

$$\begin{aligned} \partial \Sigma^{-1} / \partial c_{i,i} &= -\Sigma^{-1} (\partial \Sigma / \partial c_{i,i}) \Sigma^{-1}, \\ \partial \ln \det(\Sigma) / \partial c_{i,i} &= \text{Tr}(\Sigma^{-1} \partial \Sigma / \partial c_{i,i}) \end{aligned}$$

and

$$\partial \Sigma / \partial c_{i,i} = \begin{cases} \sum_{r=1}^m \{\mathbf{J}_r\}_{\cdot,i} \{\mathbf{J}_r\}'_{\cdot,i} & \text{for } i=j, \\ \sum_{r=1}^m [\{\mathbf{J}_r\}_{\cdot,i} \{\mathbf{J}_r\}'_{\cdot,i} + \{\mathbf{J}_r\}_{\cdot,j} \{\mathbf{J}_r\}'_{\cdot,j}] & \text{for } i \neq j \end{cases}$$

are used, then

$$\begin{aligned} & \partial \ln f(\mathbf{S}, \mathbf{C}) / \partial c_{i,i} = \\ & = \begin{cases} (k/2) \sum_{r=1}^m \{\mathbf{J}_r\}'_{\cdot,i} \Sigma^{-1} \mathbf{S} \Sigma^{-1} \{\mathbf{J}_r\}_{\cdot,i} - (k/2) \sum_{r=1}^m \{\mathbf{J}_r\}'_{\cdot,i} \Sigma^{-1} \{\mathbf{J}_r\}_{\cdot,i}, & i=j, \\ 2 \left\langle (k/2) \sum_{r=1}^m \{\mathbf{J}_r\}'_{\cdot,i} \Sigma^{-1} \mathbf{S} \Sigma^{-1} \{\mathbf{J}_r\}_{\cdot,j} - (k/2) \sum_{r=1}^m \{\mathbf{J}_r\}'_{\cdot,i} \Sigma^{-1} \{\mathbf{J}_r\}_{\cdot,i} \right\rangle, & i \neq j. \end{cases} \end{aligned}$$

If in the same way the second derivatives are determined and $E(\mathbf{S}) = \Sigma$ is used, then

$$E(-\partial^2 \ln f(\mathbf{S}, \mathbf{C}) / \partial c_{i,i} \partial c_{r,r}) = (k/2) \sum_{p=1}^m \sum_{t=1}^m \langle \{\mathbf{J}_t\}'_{\cdot,r} \Sigma^{-1} \{\mathbf{J}_p\}_{\cdot,i} \rangle^2;$$

$$\begin{aligned} & E(-\partial^2 \ln f(\mathbf{S}, \mathbf{C}) / \partial c_{i,i} \partial c_{r,q}) = \\ & = 2 \left\langle (k/2) \sum_{p=1}^m \sum_{t=1}^m \{\mathbf{J}_p\}'_{\cdot,i} \Sigma^{-1} \{\mathbf{J}_t\}_{\cdot,q} \{\mathbf{J}_p\}'_{\cdot,i} \Sigma^{-1} \{\mathbf{J}_t\}_{\cdot,r} \right\rangle, \quad r \neq q; \end{aligned}$$

$$\begin{aligned} E(-\partial^2 \ln f(\mathbf{A}, \mathbf{C}) / \partial c_{i,j} \partial c_{r,q}) &= 2 \left\langle (k/2) \sum_{p=1}^m \sum_{t=1}^m [\{\mathbf{J}_t\}'_{\cdot,r} \Sigma^{-1} \{\mathbf{J}_p\}_{\cdot,i} \cdot \right. \\ & \left. \cdot \{\mathbf{J}_p\}'_{\cdot,i} \Sigma^{-1} \{\mathbf{J}_t\}_{\cdot,q} + \{\mathbf{J}_t\}'_{\cdot,r} \Sigma^{-1} \{\mathbf{J}_p\}_{\cdot,i} \{\mathbf{J}_p\}'_{\cdot,i} \Sigma^{-1} \{\mathbf{J}_t\}_{\cdot,q}] \right\rangle, \quad i \neq j, \quad r \neq s. \end{aligned}$$

The last three relations imply the statement.

Theorem 3.2. *The dispersion of the MINU γ E of the function $g(\mathbf{C}) = \text{Tr}(\mathbf{M}\mathbf{C})$, $\mathbf{C} \in \mathcal{C}$, attains in $\mathbf{C} = \boldsymbol{\gamma}$ the Rao—Cramér lower bound.*

Proof. With respect to Lemma 1.4 [2] the dispersion of the MINU γ E is $\mathcal{D}_\gamma[\text{Tr}(\mathbf{A}\mathbf{S})] =$

$$\begin{aligned} & = (2/k) \text{Tr} \left(\sum_{i=1}^m \Sigma^{-1} \mathbf{J}_i \boldsymbol{\Lambda}^{(\gamma)} \mathbf{J}_i' \Sigma^{-1} \Sigma \sum_{j=1}^m \Sigma^{-1} \mathbf{J}_j \boldsymbol{\Lambda}^{(\gamma)} \mathbf{J}_j' \Sigma^{-1} \Sigma \right) = \\ & = (2/k) \text{Tr} \left(\sum_{i=1}^m \sum_{j=1}^m \mathbf{J}_j' \Sigma^{-1} \mathbf{J}_i \boldsymbol{\Lambda}^{(\gamma)} \mathbf{J}_i' \Sigma^{-1} \mathbf{J}_j \boldsymbol{\Lambda}^{(\gamma)} \right) = \end{aligned}$$

$$\begin{aligned}
&= (2/k) \left[\text{vec} \left\langle \sum_{i=1}^m \sum_{j=1}^m \mathbf{J}_i' \boldsymbol{\Sigma}^{-1} \mathbf{J}_i \boldsymbol{\Lambda}^{(\gamma)} \mathbf{J}_i' \boldsymbol{\Sigma}^{-1} \mathbf{J}_i \right\rangle \right]' \text{vec}(\boldsymbol{\Lambda}^{(\gamma)}) = \\
&= (2/k) \left\{ (\text{cR})(\text{cC}) \left[\sum_{i=1}^m \sum_{j=1}^m (\mathbf{J}_i' \boldsymbol{\Sigma}^{-1} \mathbf{J}_i) \otimes (\mathbf{J}_i' \boldsymbol{\Sigma}^{-1} \mathbf{J}_i) \right] \text{vec}(\boldsymbol{\Lambda}^{(\gamma)}) \right\}' \text{vec}(\boldsymbol{\Lambda}^{(\gamma)}).
\end{aligned}$$

Regarding Lemma 3.1, the last expression can be rewritten as $(2/k)^2 \{ \text{vech}(\boldsymbol{\Lambda}^{(\gamma)}) \}' \mathbf{F}(\gamma) \text{vech}(\boldsymbol{\Lambda}^{(\gamma)})$ and regarding (***) in Theorem 2.2 it can again be rewritten as $\{ (\text{cR})[\text{vec}(\mathbf{M})] \}' \mathbf{F}^{-1}(\gamma) (\text{cR}) \text{vec}(\mathbf{M})$. This is the Rao—Cramér lower bound of dispersions of unbiased estimators of the function $g(\mathbf{C}) = \{ (\text{cR})[\text{vec}(\mathbf{M})] \}' \text{vech}(\mathbf{C}) = \text{Tr}(\mathbf{MC})$, $\mathbf{C} \in \mathcal{C}$ for the value γ of the parameter \mathbf{C} .

Corollary 3.1. *If $m = 1$, $\mathbf{J}_1 = \mathbf{I}$ and $g(\mathbf{C}) = \text{Tr}(\mathbf{MC}) = c_{i,j} = \{ \boldsymbol{\Sigma} \}_{i,j}$, $i, j = 1, \dots, n$, then regarding Theorem 2.2 the MINU γ E is*

$$\tau_q(\mathbf{S}) = \text{Tr}(\mathbf{V}^{(\gamma)})^{-1} \boldsymbol{\Lambda}^{(\gamma)} \mathbf{V}^{(\gamma)}^{-1} \mathbf{S} \quad \text{and} \quad \mathbf{M} = \mathbf{V}^{(\gamma)}^{-1} \boldsymbol{\Lambda}^{(\gamma)} \mathbf{V}^{(\gamma)}^{-1}.$$

Thus $\tau_q(\mathbf{S}) = \{ \mathbf{S} \}_{i,j}$. This estimator does not depend on γ and attains the Rao—Cramér lower bound in its dispersion. Thus it is uniformly best.

Corollary 3.2. *If $s = 1$, i.e. $\boldsymbol{\Sigma} = c\mathbf{V} = c \sum_{i=1}^n \mathbf{J}_i \mathbf{J}_i'$, where $(\mathbf{J}_1, \dots, \mathbf{J}_n) = \mathbf{V}^{1/2}$ and $g(c) = c$, $c \in (0, \infty)$, then by Theorem 2.2 the MINU γ E is $\tau_q(\mathbf{S}) = \text{Tr}[(1/n)\mathbf{V}^{-1}\mathbf{S}]$ (the same result follows from Theorem 3.2 [2]). Its dispersion (see also Lemma 1.4 [2]) is $\mathcal{D}(\tau_q(\mathbf{S})) = [2/(kn)]c^2$ and by Theorem 3.2 this is identical with the lower Rao—Cramér bound. As $\tau_q(\mathbf{S})$ does not depend on γ , this estimator is the uniformly best one. It is necessary to remark that the distribution of the estimator $\text{Tr}[(1/n)\mathbf{V}^{-1}\mathbf{S}]$ is identical with the distribution of the random variable $c\chi_{kn}^2/(kn)$, where χ_{kn}^2 has the chi-square distribution with (kn) degrees of freedom.*

Remark 3.2. Similarly as in [2] the comparison of the estimator based on the realization of the vector $\mathbf{Y} \sim N_n(\mathbf{X}\boldsymbol{\beta}, \boldsymbol{\Sigma})$ with the estimator based on the realization of the matrix $k\mathbf{S} \sim W_n(k, \boldsymbol{\Sigma})$ (from a repeated regression experiment) can be done.

Let $\mathbf{F}(\boldsymbol{\beta}, \mathbf{C})$ be the Fisher information matrix of the distribution of the vector \mathbf{Y} related to the parameter $(\boldsymbol{\beta}', [\text{vech}(\mathbf{C})]')$. Analogously to Lemma 3.1 we obtain

$$(***) \quad \mathbf{F}(\boldsymbol{\beta}, \mathbf{C}) = \begin{bmatrix} \mathbf{X}' \boldsymbol{\Sigma}^{-1} \mathbf{X}, & \mathbf{0} \\ \mathbf{0}, & (1/k)\mathbf{F}(\mathbf{C}) \end{bmatrix},$$

where $\mathbf{F}(\mathbf{C})$ is the matrix from Lemma 3.1. The unbiased estimator based on the realization of the vector \mathbf{Y} and respecting the approximate values of the elements of the matrix γ is $\mathbf{Y}' \mathbf{A}_* \mathbf{Y}$. The matrix \mathbf{A}_* minimizes the quantity $\text{Tr}(\mathbf{A} \mathbf{V}^{(\gamma)} \mathbf{A} \mathbf{V}^{(\gamma)})$ under the side condition $\mathbf{X}' \mathbf{A} \mathbf{X} = \mathbf{0}$ and $\sum_{i=1}^m \mathbf{J}_i' \mathbf{A} \mathbf{J}_i = \mathbf{M}$, respectively (see [3]). There is

$$\mathbf{A}_* = \sum_{j=1}^m \mathbf{V}^{(\gamma)-1} \mathbf{J}_j \Lambda^{(\gamma)} \mathbf{J}_j' - \sum_{j=1}^m \mathbf{V}^{(\gamma)-1} \mathbf{X} (\mathbf{X}' \mathbf{V}^{(\gamma)-1} \mathbf{X})^{-1} \mathbf{X}' \mathbf{V}^{(\gamma)-1} \cdot \mathbf{J}_j \Lambda^{(\gamma)} \mathbf{J}_j' \mathbf{V}^{(\gamma)-1} \mathbf{X} (\mathbf{X}' \mathbf{V}^{(\gamma)-1} \mathbf{X})^{-1} \mathbf{X}' \mathbf{V}^{(\gamma)-1},$$

where the matrix of the Lagrange multipliers $\Lambda^{(\gamma)}$ satisfies the matrix equation

$$\mathbf{M} = \sum_{j=1}^m \mathbf{J}_j' \mathbf{A}_* \mathbf{J}_j.$$

If the second term of the right-hand side, the expression (***) , Theorem 3.2 and the expression (**) are taken into account then it can be seen that the dispersion of $\mathbf{Y}' \mathbf{A}_* \mathbf{Y}$ cannot in general attain its Rao—Cramér lower bound. Therefore, if there exists a possibility to obtain the realization of the matrix \mathbf{S} from results of a repeated regression experiment, then the estimator should be based on the matrix \mathbf{S} instead the vector \mathbf{Y} (see also Part 4 of [2]).

Example. Let $\mathbf{Y} \sim N_n(\mathbf{X}\beta, c\mathbf{V})$ (see corollary 3.2). Then the MINQUE (see [3]) of the parameter c is $\hat{c} = \mathbf{Y}' [\mathbf{V}^{-1} - \mathbf{V}^{-1} \mathbf{X} (\mathbf{X}' \mathbf{V}^{-1} \mathbf{X})^{-1} \mathbf{X}' \mathbf{V}^{-1}] \mathbf{Y} / [n - R(\mathbf{X})]$ and its dispersion is $\mathcal{D}(\hat{c}) = 2c^2 / [n - R(\mathbf{X})]$. Repeating this experiment $(k+1)$ -times we get $\mathcal{D}\{[1/(k+1)](\hat{c}_1 + \dots + \hat{c}_{k+1})\} = 2c^2 / \{(k+1)[n - R(\mathbf{X})]\}$, while $\mathcal{D}\{\text{Tr}[(1/n)\mathbf{V}^{-1}\mathbf{S}]\} = 2c^2 / (kn)$ and this value is substantially smaller; e.g. for $n = 5$, $R(\mathbf{X}) = 2$, $k+1 = 7$ we have $\mathcal{D}\{[1/(k+1)](\hat{c}_1 + \dots + \hat{c}_{k+1})\} / \mathcal{D}\{\text{Tr}[(1/n)\mathbf{V}^{-1}\mathbf{S}]\} = 1,43$.

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Matematický ústav SAV
Obrancov mieru 49
814 73 Bratislava

ОЦЕНКА КОВАРИАЦИОННЫХ КОМПОНЕНТ
В ПОВТОРЕННОМ РЕГРЕССИОННОМ ЭКСПЕРИМЕНТЕ

Lubomír Kubáček

Резюме

Предложена несмещенная оценка минимальной нормы (MINUE) элементов матрицы \mathbf{C} , которые названы ковариационными компонентами случайного вектора

$$\mathbf{Y} \sim N_n \left(\mathbf{X}\boldsymbol{\beta}, \boldsymbol{\Sigma} = \sum_{i=1}^m \mathbf{J}_i \mathbf{C} \mathbf{J}_i' \right),$$

основанная на реализации матрицы

$$\mathbf{S} = (1/k) \sum_{i=1}^{k+1} (\mathbf{Y}_i - \bar{\mathbf{Y}})(\mathbf{Y}_i - \bar{\mathbf{Y}})'$$

Исследованы некоторые статистические свойства MINUE.