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SOME GEOMETRICAL EXAMPLES OF AN IMC-QUASIGROUP

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A quasigroup $Q(\cdot)$, i. e. a non-vacuous set Q with a binary operation for which each the equations $a \cdot x = b$ and $y \cdot a = b$ have a unique solution for any $a, b \in Q$ is called

(a) *medial if*

$$(1) \quad (x \cdot y) \cdot (u \cdot v) = (x \cdot u) \cdot (y \cdot v) \text{ for any } x, y, u, v \in Q,$$

(b) *idempotent if*

$$(2) \quad x^2 = x \cdot x = x \text{ for any } x \in Q,$$

(c) *commutative if*

$$(3) \quad x \cdot y = y \cdot x \text{ for any } x, y \in Q.$$

A medial, idempotent and commutative quasigroup is said to be an *A-structure*.

Example 1. An n -dimensional real affine space A^n with respect to the „mid-point of the couple of points“ is an operation \cdot .

Example 2. Let A, B, C be three different copies of the space A^n and φ_{AB} an affine mapping of A onto B . Similarly define $\varphi_{BA}, \varphi_{AC}, \varphi_{CA}, \varphi_{BC}, \varphi_{CB}$, so that $\varphi_{AB} = \varphi_{BA}^{-1}, \varphi_{AC} = \varphi_{CA}^{-1}, \varphi_{BC} = \varphi_{CB}^{-1}, \varphi_{AB}\varphi_{BC} = \varphi_{AC}$. On the point set $Q = A \cup B \cup C$ the following binary operation is defined: if x, y belong to one of the spaces A, B, C then $x \cdot y$ (according to Example 1) is the mid-point of the couple x, y ; if x, y belong to different spaces of A, B, C (suppose $x \in A, y \in B$), then we define $x \cdot y = \varphi_{AC}^x \cdot \varphi_{BC}^y$. It is not difficult to prove that $Q(\cdot)$ forms an A-structure.

In the following we shall write xy instead of $x \cdot y$.

In the theory of quasigroups there are introduced two important mappings L_a -left translation and R_a -right translation by the relations

$$L_a x = ax, \quad R_a x = xa.$$

Because $L_a = R_a$ holds in an A-structure Q for any $a \in Q$, we shall introduce

only one mapping denoted by G_a , namely

$$(4) \quad G_a : Q \rightarrow Q : x \rightarrow ax = xa ; x \in Q ;$$

this mapping is termed as a homology, according to Example 1.

It is clear that the homology G_a is a permutation of the set Q i. e. a 1 – 1 mapping of Q onto Q .

The inverse permutation to G_a is denoted by G_a^{-1} , the identical permutation by I . In the group of all permutations of Q the set of all homologies G_a generates a group Q , which is said to be an A-group of the structure $Q(\cdot)$.

Proposition 1. *The homologies G_a, G_{-1}^a are automorphisms of the A-structure Q . There is exactly one fixed point of G_a , namely the point a .*

Proof. From (1), (2) it follows that the A-structure is distributive, i. e.

$$(5) \quad x \cdot yz = xy \cdot xz$$

holds for any $x, y, z \in Q$. Hence G_a and G_a^{-1} are automorphisms. The rest of our assertion can be checked directly by calculation.

Proposition 2. *For any A-structure*

$$(6) \quad G_{xy}z = G_xz \cdot G_yz ,$$

$$(7) \quad G_{xy}^{-1}z = G_x^{-1}z \cdot G_y^{-1}z ,$$

$$(8) \quad x \cdot G_x^{-1}y = y .$$

Proof. The identity (6) is a distributive law. To prove (7) we denote $G_{xy}^{-1}z = w, G_y^{-1}z = u, G_x^{-1}z = v$. Hence $z = w \cdot xy, z = xu, z = yv$. Thus by using these equations and identities (1), (2), we obtain $xy \cdot uv = xu \cdot yv = -z \cdot z = z = w \cdot xy$, therefore $w = uv$. According to the definition $G_{xy} = -y \cdot G_x = xy$. If we multiply this equality from the left by G_x^{-1} we obtain (8).

Proposition 3. *Let $x \in Q$ be such an element for which $G_ax = G_bx$ or $G_a^{-1}x = G_b^{-1}x$ holds. Then $a = b$.*

Proof. The first assertion is clear. If $G_a^{-1}x = G_b^{-1}x$, then $bx = G_bx = -G_bG_aG_a^{-1}x = G_bG_aG_b^{-1}x = G_b(a \cdot G_b^{-1}x) = (G_ba) \cdot x$. Thus $b = G_ba = ab \Rightarrow a = b$.

Proposition 4. *For any $a \in Q$ the mapping $S_a : x \rightarrow G_x^{-1}a$ is an endomorphism.*

Proof. The proof follows directly from (7). The mapping S_a is said to be a *symmetry* with respect to the element a .

Corollary 1. (Of Proposition 1). *If there exists $x \in Q$ such that $S_ax = S_bx$, then $a = b$.*

Corollary 2. *There is exactly one invariant point of the symmetry S_a , namely the point a .*

Proposition 5. *For any $x, y, z \in Q$*

$$(9) \quad y \cdot S_x y = x ,$$

$$(10) \quad S_{xy} x = y ,$$

$$(11) \quad (S_y x)(S_z x) = S_{yz} x .$$

Proof. From $G_y^{-1}x = S_x y$ it follows that $x = G_y S_x y = y \cdot S_x y$. Hence (9) holds. Multiplying $xy = G_x y$ from the left by G_x^{-1} we find (10) by means of (8). Identity (11) shows that the reflection $y \rightarrow S_y$ is an automorphism.

Proposition 6. *For any $x, y, z \in Q$*

$$(12) \quad S_y x = x \Leftrightarrow x = y ,$$

$$(13) \quad S_z x = y \Leftrightarrow xy = z .$$

Proof. According to the definition the equation $x = S_y x$ is equivalent to the equation $x = G_x^{-1}y$, (i. e. $G_x x = y$), hence to the equation $x = y$. If we rewrite $xy = z$ in the form $G_x y = z$ and multiply this from the left by G_x^{-1} we obtain (13).

Proposition 7. *For an arbitrary $a \in Q$*

$$(14) \quad S_a^2 = S_a S_a = I .$$

Proof. From (13) and (3) we obtain $S_a x = y \Leftrightarrow xy = a \Leftrightarrow S_a y = x$ thus $S_a^2 x = S_a(S_a x) = S_a y = x$.

Corollary 3. *The endomorphism S_a is an automorphism.*

The subgroup of the group of all permutations on Q generated by the set of all symmetries S_a , $a \in Q$ is termed the symmetry group (of the quasigroup Q) and is denoted by \mathcal{S} .

Now we turn our attention to the structure of the group \mathcal{S} . First the notion of transfer is to be introduced. An automorphism $S_y S_x$, $x, y \in Q$ is said to be a *transfer* (with respect to the elements x, y) on Q and will be denoted by W_{xy} .

The subgroup of the group of all permutations on Q generated by the set of all transfers W_{xy} , $x, y \in Q$ is called a *transfer group* (of the quasigroup Q) and denoted by \mathcal{W} .

From Proposition 7 it follows immediately:

$$(15) \quad W_{xx} = I ,$$

$$(16) \quad W_{xy}W_{yx} = I, \quad W_{xy} = W_{yx}^{-1},$$

$$(17) \quad W_{zy}W_{xz} = W_{xy}.$$

Proposition 8. *Let $a \neq b$, $a, b \in Q$. Then there is no invariant element x of the transfer W_{ab} .*

Proof. We assume that there exists $x \in Q$ such that $W_{ab}x = x$. Making use of relation (9) and denoting $y = S_b x$, we obtain $a = y S_a y = (S_b x)(S_a S_b x) = S_b x W_{ab} x = x S_b x = b$. But this contradicts the assumption $a \neq b$.

Proposition 9. *For any $a, b, c \in Q$*

$$(18) \quad ad = bc \Leftrightarrow W_{ab} = W_{ca}.$$

Proof. Let $ad = bc$ and $x \in Q$. If we denote $y = W_{ab}x = S_b S_a x$, then from (1) and (9) we obtain $cb = ad = (x \cdot S_a x)(y \cdot S_a y) = (x \cdot S_a y)(y \cdot S_a x) = x \cdot S_a y [(S_b S_a x)(S_a x)] = (x \cdot S_a y)b$. Thus, $c = x \cdot S_a y = x \cdot S_a S_b S_a x$, and also $c = x S_c x$. Comparing the last two equations we find $x \cdot S_c x = x \cdot S_a S_b S_a x$. Hence $S_c x = S_a S_b S_a x$ or $S_c = S_a S_b S_a$; thus we obtain $W_{ca} = S_a S_c = S_a S_a S_b S_a = S_b S_a = W_{ab}$. The converse assertion should be proved easily.

Corollary 4. *Let S_a, S_b and S_c be three symmetries on Q ; then there exists one and only one symmetry S_d such that $S_d = S_a S_b S_c$.*

Proof. The element d can be found from the equation $bc = ad$. The uniqueness of S_d follows from Corollary 1.

Corollary 5. *Let W_{ab} be a transfer on Q and $p \in Q$. Then there exists one and only one element $x \in Q$ such that $W_{px} = W_{ab}$.*

Proof. x is determined by the equation $pb = ax$.

Now we shall show a very important consequence concerning the structure of the group \mathcal{W} .

Proposition 10. *Let p be a fixed point of Q . Then the set \mathcal{W}_p of the transfers W_{px} , $x \in Q$, forms an Abelian group with respect to the operation of composition. The neutral element of \mathcal{W}_p is $W_{pp} = I$ and the inverse to the element W_{px} is W_{py} , where $y = S_p x$.*

Proof. For any $W_{pa}, W_{pb} \in \mathcal{W}_p$ there is

$$(19) \quad W_{pb} \cdot W_{pa} = W_{pc}, \quad \text{where } pc = ab.$$

Indeed, defining c by the equation $pc = ab$, we obtain $W_{ac} = W_{pb}$. From (18) and regarding (17) we find $W_{pb}W_{pa} = W_{ac}W_{pa} = W_{pc}$; from $ab = ba$ and (19) we obtain $W_{pb} \cdot W_{pa} = W_{pc} = W_{pa}W_{pb}$.

If $W_{px}W_{py} = I = W_{pp}$, then from (19) it follows that $p = pp = xy$. Hence $y = S_p x$. In accordance with Corollary 5 any element W_{ab} can be

written in the form of W_{px} . Hence the group \mathcal{W} is not only generated by the elements W_{ab} but \mathcal{W} is directly the set of these elements and it is isomorphic with the group \mathcal{W}_p . It is clear that without being afraid of confusion we can identify group \mathcal{W}_p with the group \mathcal{W} .

Proposition 11. *The group \mathcal{W}_p acts on Q transitively and effectively.*

Proof. The effectivity is the direct consequence of Proposition 8.

For any $x, y \in Q$ we determine c by the equation $cx = p \cdot xy$ and according to (18) and (10) we find

$$W_{pcx} = W_x, \quad xyx = S_{xy}S_x x = S_{xy}x = y.$$

It is known that the mapping

$$\omega_p : Q \rightarrow \mathcal{W}_p : x \rightarrow W_{px}$$

is a 1 — 1 mapping from Q onto \mathcal{W}_p .

It is not difficult to see that the operation \circ on the set \mathcal{W}_p corresponds to the operation \circ on Q .

$$W_{px} \circ W_{py} = W_{p,xy}.$$

The mapping ω_p is an isomorphism between the quasigroups $Q(\circ)$ and $\mathcal{W}_p(\circ)$.

Proposition 12. *Let $S \in \mathcal{S}$ and $p \in Q$ be fixed. Then there exists exactly one element $x \in Q$ such that one and only one of the following relations holds*

(a)
$$S = W_{px},$$

(b)
$$S = S_p W_{px}.$$

If $S = S_p W_{px}$, then also $S = W_{pa} S_p$, where $a = S_p x$.

Proof. From Corollary 4 it follows that S may be written in one of the forms $S_a, S_a S_b$.

From Corollary 2 and Proposition 8 it follows that S may be written only in one of the forms S_a and $S_a S_b$.

From Proposition 1 it follows that if $S = S_a S_b$, then $S = W_{px}$, where x is determined uniquely. If $S = S_a$ then $S_a = S_a S_p S_p = W_{pa} S_p$. It is easy to show that there exists just one invariant element of the mapping $S_p S_a S_p$, namely the element $x = S_p a$. Thus, $S_p S_a S_p = S_x$ and therefore

$$W_{pa} S_p = S_a = S_p S_x S_p = S_p W_{px}.$$

Corollary 6. *The group \mathcal{W} is a proper subgroup of the group \mathcal{S} . Now we shall show that the group \mathcal{W} is a subgroup of the group \mathcal{G} .*

Proposition 13. *The set of all elements of the form $V_{ab} = G_a^{-1} G_b$ with respect to the composition is the group \mathcal{W} .*

Proof. It is necessary to verify that any transformation V_{ab} can be expressed as W_{xy} and any transformation W_{ab} can be expressed as V_{xy} . For proving this we shall use:

Lemma 1. For any $a, b \in Q$

$$(20) \quad V_{ab} = W_{a,ab}.$$

Proof. By means of relations (4), (9), (5), (9) and (10) we obtain

$$G_b S_a x = b \cdot S_a x = (x \cdot S_b x) S_a x = (x \cdot S_a x) \cdot (S_a x \cdot S_b x) = a \cdot S_a b x = G_a S_a b x.$$

Thus

$$G_b S_a = G_a S_a b.$$

Having multiplied the last equation from the left by G_a^{-1} and from the right by S_a and considering (14) we obtain (20).

Now it is not difficult to prove Proposition 13. If the mapping V_{ab} is given, then W_{xy} is determined by (20). And vice versa if the transfer W_{ac} is given, then $V_{ab} = W_{ac}$ holds for $b = S_c a$.

From the foregoing statements it immediately follows that $\mathcal{S} \supset \mathcal{W}, \mathcal{G} \supset \mathcal{W}$.

Proposition 14. For any a, b

$$(21) \quad V_{ab}^2 = V_{ab} V_{ab} = W_{ab}.$$

Proof. For any $x \in Q$

$$\begin{aligned} W_{a,ab} x &= S_{ab} S_a x = [S_a(S_a x)] [S_b(S_a x)] = x(S_b S_a x) = S_b(S_b x \cdot S_a x) = \\ &= S_b S_a b x = W_{ab, b} x. \end{aligned}$$

Thus

$$(22) \quad W_{a,ab} = W_{ab, b}.$$

Hence

$$V_{ab} V_{ab} x = W_{ab, b} W_{a,ab} x = S_b S_{ab} S_{ab} S_a x = W_{ab} x.$$

Some of the problems of this paper are special cases of those introduced in [2]. The main difference is in the commutativity of the structures. For instance, the groups \mathcal{W} and \mathcal{G} are proper subgroups of the group of all regular transformations C_A (notation by Belousow [1]). It might be interesting to use Belousow's results in geometry.

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