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Katedra matematické analýzy a numerické matematiky  
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**BOUNDS FOR SOLUTIONS  
OF A NONLINEAR DIFFERENTIAL EQUATION  
OF THE THIRD ORDER**

SVATOSLAV STANĚK

(Received December 15th, 1985)

Dedicated to Professor M.Laitoch on his 65th birthday

1. Introduction

The aim of this paper is to find bounds for solutions of the differential equation

$$\begin{aligned} (p(t)(p(t)x')')' + 4p(t)q(t)x' + 2(p(t)q(t))'x = \\ = f(t, x, x', (p(t)x')') \end{aligned} \quad (1)$$

Throughout we will assume that

$$p, q \in C^0(J), pq \in C^1(J), f \in C^0(D), p(t) > 0 \text{ for } t \in J,$$

where  $J = [0, \infty)$ ,  $D = J \times \mathbb{R}^3$ .

Somewhat analogous results for nonlinear differential equations of the second order are given in [2].

2. Supplementary lemmas

Let  $u(t)$ ,  $v(t)$  be the solutions (on  $J$ ) of the differential

equation

$$(p(t)z')' + q(t)z = 0 \quad (2)$$

satisfying the initial conditions  $u(t_0)=1, u'(t_0)=0, v(t_0)=0, v'(t_0)=1$  at a point  $t_0 \in J$ . Then  $y = c_1 u^2(t) + c_2 u(t)v(t) + c_3 v^2(t)$  is a solution of the differential equation

$$(p(t)(p(t)y')')' + 4p(t)q(t)y' + (p(t)q(t))' y = 0 \quad (3)$$

and

$$y(t_0)=c_1, y'(t_0)=c_2, (p(t)y'(t))'|_{t=t_0} = -2c_1q(t_0)+2c_3p(t_0).$$

Let us put  $J_0 = [t_0, \infty)$  and

$$a(t) = \max \{|u(t)|, |v(t)|\}, \quad b(t) = \max \{|u'(t)|, |v'(t)|\}, \\ c(t) = |q(t)| a^2(t) + p(t)b^2(t), \quad t \in J.$$

Lemma 1. Suppose  $y = c_1 u^2(t) + c_2 u(t)v(t) + c_3 v^2(t)$  is a solution of (3). Setting  $C = |c_1| + |c_2| + |c_3|$ , yields

$$|y(t)| \leq Ca^2(t), \\ |y'(t)| \leq 2Ca(t)b(t), \\ |(p(t)y'(t))'| \leq 2Cc(t), \quad t \in J.$$

P r o o f. The estimates immediately follows from the definition of the functions  $a, b, c$  and from the equalities

$$y = c_1 u^2 + c_2 uv + c_3 v^2, \\ y' = 2c_1 uu' + c_2(u'v + uv') + 2c_3 vv', \\ (py')' = -2q(c_1 u^2 + c_2 uv + c_3 v^2) + 2p(c_1 u'^2 + c_2 u'v' + c_3 v'^2).$$

Lemma 2. The solution of (1) is equivalent to the solution of the integral equation

$$x(t) = y(t) + \frac{1}{2p^2(t_0)} \int_{t_0}^t (u(t)v(s) - u(s)v(t))^2 ds, \quad (4)$$

$$f(s, x(s), x'(s), (p(s)x'(s))')$$

where  $y(t)$  is the solution of (3) satisfying the same initial conditions at the point  $t=t_0$  as the solution  $x(t)$  of (1).

P r o o f. This may be verified by a direct calculation.

### 3. Main results

Theorem 1. Suppose  $D_1 = J_0 \times J^3$  and  $\omega = \omega(t, x_1, x_2, x_3) \in C^0(D_1)$  is a nondecreasing function in the variables  $x_1, x_2, x_3$  for any fixed  $t \in J_0$ . Suppose next that

$$|f(t, x_1, x_2, x_3)| \leq \omega(t, |x_1|, |x_2|, |x_3|) \text{ for } (t, x_1, x_2, x_3) \in D_1$$

and there exists a positive function  $\mathcal{L} \in C^0(J_0)$  such that

$$\begin{aligned} \varepsilon + \frac{2}{p^2(t_0)} \int_{t_0}^t a^2(s) \omega(s, \mathcal{L}(s)a^2(s), 2\mathcal{L}(s)a(s)b(s), \\ 2\mathcal{L}(s)c(s)) ds \leq \mathcal{L}(t) \end{aligned} \quad (5)$$

for  $t \in J_0$ .

Setting

$$C_1 = |c_1| \left(1 + \frac{q(t_0)}{p(t_0)}\right) + |c_2| + \frac{1}{2p(t_0)} |c_3|$$

for  $c_1, c_2, c_3 \in \mathbb{R}$ , then every solution  $x(t)$  of (1) satisfying the initial conditions  $x(t_0) = c_1, x'(t_0) = c_2,$

$(p(t)x'(t))'_{t=t_0} = c_3$  and  $C_1 < \varepsilon$ , exists on  $J_0$  and

$$\begin{aligned} |x(t)| \leq \mathcal{L}(t)a^2(t), \quad |x'(t)| \leq \mathcal{L}(t)a(t)b(t), \\ |(p(t)x'(t))'| \leq \mathcal{L}(t)c(t) \text{ for } t \in J_0. \end{aligned} \quad (6)$$

P r o o f. Suppose  $x$  is a solution of (1) satisfying at the point  $t=t_0$  the assumptions of Theorem 1. Following Lemma 2 there then holds (4), where  $y$  is the solution of (3) satisfying at the point  $t=t_0$  the same initial conditions as the solution  $x$ . Hence

$$y(t) = c_1 u^2(t) + c_2 u(t)v(t) + \left(\frac{q(t_0)}{p(t_0)} c_1 + \frac{1}{2p(t_0)} c_3\right) v^2(t).$$

Then the following estimates follows from Lemma 1

$$|y(t)| \leq c_1 a^2(t),$$

$$|y'(t)| \leq 2c_1 a(t)b(t),$$

$$|(p(t)y'(t))'| \leq 2c_1 c(t), \quad t \in J_0.$$

Performing the differentiation of (4) we obtain successively

$$x'(t) = y'(t) + \frac{1}{p^2(t_0)} \int_{t_0}^t (u(t)v(s) - u(s)v(t))(u'(t)v(s) -$$

$$- u(s)v'(t)) \cdot f(s, x(s), x'(s), (p(s)x'(s))') ds,$$

$$(p(t)x'(t))' = (p(t)y'(t))' + \frac{1}{p^2(t_0)} \int_{t_0}^t \{ p(t)(u'(t)v(s) -$$

$$- u(s)v'(t))^2 - q(t)(u(t)v(s) -$$

$$- u(s)v(t))^2 \} f(s, x(s), x'(s), (p(s)x'(s))') ds.$$

Herefrom and from (4) we obtain

$$|x(t)| \leq a^2(t) \left\{ C_1 + \frac{2}{p^2(t_0)} \int_{t_0}^t a^2(s) \omega(s, |x(s)|, |x'(s)|, |(p(s)x'(s))'|) ds \right\},$$

$$|x'(t)| \leq 2a(t)b(t) \left\{ C_1 + \frac{2}{p^2(t_0)} \int_{t_0}^t a^2(s) \omega(s, |x(s)|, |x'(s)|, |(p(s)x'(s))'|) ds \right\},$$

$$|(p(t)x'(t))'| \leq 2c(t) \left\{ C_1 + \frac{2}{p^2(t_0)} \int_{t_0}^t a^2(s) \omega(s, |x(s)|, |x'(s)|, |(p(s)x'(s))'|) ds \right\}.$$

Denoting  $z(t) = C_1 + \frac{2}{p^2(t_0)} \int_{t_0}^t a^2(s) \omega(s, |x(s)|, |x'(s)|,$

$|(p(s)x'(s))'|) ds$  yields

$$|x(t)| \leq a^2(t)z(t), |x'(t)| \leq 2a(t)b(t), |(p(t)x'(t))'| \leq 2c(t)z(t)$$

and

$$z(t) \leq C_1 + \frac{2}{p^2(t_0)} \int_{t_0}^t a^2(s)\omega(s), a^2(s)z(s), 2a(s)b(s)z(s), \\ 2c(s)z(s) ds.$$

Let us suppose that the solution  $x$  exists on the interval  $[t_0, T)$ . Then  $z$  exists on this interval too and is  $z(t) < \mathcal{L}(t)$ . In fact it is  $z(t_0) < \mathcal{L}(t_0)$  so that the inequality  $z(t) < \mathcal{L}(t)$  holds in a certain right neighbourhood of  $t_0$ . Let  $t_1$  be the smallest value of  $t$  such that  $z(t_1) = \mathcal{L}(t_1)$ . Then from (5) follows

$$\mathcal{L}(t_1) = z(t_1) \leq C_1 + \frac{2}{p^2(t_0)} \int_{t_0}^{t_1} a^2(s)\omega(s), \mathcal{L}(s)a^2(s), \\ 2\mathcal{L}(s)a(s)b(s), 2\mathcal{L}(s)c(s) ds \leq (C_1 - \varepsilon) + \mathcal{L}(t_1),$$

thus  $C_1 - \varepsilon \geq 0$  which is a contradiction. Thus  $z(t) < \mathcal{L}(t)$  on the whole interval  $[t_0, T)$  and with respect to  $z(t) < \mathcal{L}(t)$  we get (6) on  $[t_0, T)$ . From these inequalities we conclude that the solution  $x$  exists for all  $t \geq t_0$  and satisfies (6).

Remark 1. Theorem 1 ensures the existence of solutions of (1) on the half-line  $J_0$  (provided that a function  $\mathcal{L}$  in Theorem 1 with the given properties exists), which at a point  $t=t_0 (\in J)$  satisfy "sufficiently small" initial conditions and, besides, in applying the function  $\mathcal{L}$  with solutions of (2), it presents an estimate of such solutions and their first derivatives and their second quasi-derivatives (on  $J_0$ ). By using a certain nonlinear integral inequality we will present in the following Theorem sufficient conditions for the existence of all solutions of (1) on a half-line  $J_0$  and by using solutions of (2) we will show the estimates for solutions and their first derivatives and their second quasi-derivatives (on  $J_0$ ).

Theorem 2. Let there exist functions  $\mathcal{L}$ ,  $k_1$ ,  $k_2$ ,  $k_3$  and  $\omega$  satisfying the following assumptions:

- (i)  $\mathcal{L}$ ,  $k_1$ ,  $k_2$ ,  $k_3 \in C^0(J_0)$  are non-negative functions,  
 $k_1(t) + k_2(t) + k_3(t) > 0$  for  $t \in J_0$ ;
- (ii)  $\omega \in C^0(J)$  is a nondecreasing and positive function;
- (iii)  $|f(t, x_1, x_2, x_3)| \leq \mathcal{L}(t) (k_1(t)|x_1| + k_2(t)|x_2| + k_3(t)|x_3|)$  for  $(t, x_1, x_2, x_3) \in J_0 \times R^3$ ;
- (iv)  $\int_{\varepsilon}^{\infty} \frac{ds}{\omega(s)} = \infty$ , ( $\varepsilon > 0$ ).

Then every solution  $x(t)$  of (1),  $x(t_0) = c_1$ ,  $x'(t_0) = c_2$ ,  $(p(t)x'(t))'_{t=t_0} = c_3$  is defined on the half-line  $J_0$  and

$$k_1(t)|x(t)| + k_2(t)|x'(t)| + k_3(t)|((p(t)x'(t))'|) \leq G^{-1} \left[ G(A(t)) + \frac{2A(t)}{p^2(t_0)} \int_{t_0}^t B(s) ds \right], \quad t \in J_0, \quad (8)$$

where  $C_1 = |c_1| \left( 1 + \frac{|q(t_0)|}{p(t_0)} \right) + |c_2| + \frac{|c_3|}{2p(t_0)}$ ,

$$A(t) = C_1 \left\{ \max_{t_0 \leq s \leq t} k_1(s)a^2(s) + 2 \max_{t_0 \leq s \leq t} k_2(s)a(s)b(s) + 2 \max_{t_0 \leq s \leq t} k_3(s)c(s) \right\}, \quad B(t) = \max_{t_0 \leq s \leq t} a^2(s)\mathcal{L}(s), \quad t \in J_0,$$

and  $G^{-1}$  denotes the inverse function to the function  $G(t) = \int_{\varepsilon}^t \frac{ds}{\omega(s)}$ ,  $t \in (0, \infty)$ .

P r o o f. Let  $x$  be a solution of (1),  $x(t_0)=c_1$ ,  $x'(t_0)=c_2$ ,  $(p(t)x'(t))'_{t=t_0} = c_3$  defined on the interval  $[t_0, T)$ . By an analogous method to that used in obtaining estimates (7) in the proof of Theorem 1, we deduce now the estimates

$$\begin{aligned}
 |x(t)| &\leq a^2(t) \left\{ c_1 + \frac{2}{p^2(t_0)} \int_{t_0}^t a^2(s) \omega(k_1(s) |x(s)| + \right. \\
 &\quad \left. + k_2(s) |x'(s)| + k_3(s) |(p(s)x'(s))'|) ds \right\}, \\
 |x'(t)| &\leq 2a(t)b(t) \left\{ c_1 + \frac{2}{p^2(t_0)} \int_{t_0}^t a^2(s) \omega(k_1(s) |x(s)| + \right. \\
 &\quad \left. + k_2(s) |x'(s)| + k_3(s) |(p(s)x'(s))'|) ds \right\}, \tag{9}
 \end{aligned}$$

$$\begin{aligned}
 |(p(t)x'(t))'| &\leq 2c(t) \left\{ c_1 + \frac{2}{p^2(t_0)} \int_{t_0}^t a^2(s) \omega(k_1(s) |x(s)| + \right. \\
 &\quad \left. + k_2(s) |x'(s)| + k_3(s) |(p(s)x'(s))'|) ds \right\}.
 \end{aligned}$$

From this it follows

$$\begin{aligned}
 &k_1(t) |x(t)| + k_2(t) |x'(t)| + k_3(t) |(p(s)x'(s))'| \leq A(t) + \\
 &+ \frac{2A(t)}{p(t_0)} \int_{t_0}^t B(s) \omega(k_1(s) |x(s)| + k_2(s) |x'(s)| + k_3(s) |(p(s)x'(s))'|) ds
 \end{aligned}$$

and from Theorem 1.19 [1] immediately follows (8) for  $t \in [t_0, T)$ . Thus on this interval a bounded function is  $k_1|x| + k_2|x'| + k_3|(px')'|$ . Naturally, then the boundedness of functions  $x$ ,  $x'$ ,  $(px')'$  follows from (9) and from (1) follows the boundedness of the function  $(p(px')')'$  on the interval  $[t_0, T)$ . Consequently the solution  $x$  is defined on  $J_0$  with (8) being valid here.



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## SOUHRN

Hranice řešení nelineární diferenciální rovnice 3. řádu

S v a t o s l a v S t a n ě k

Nechť  $p, q \in C^0(J)$ ,  $pq \in C^1(J)$ ,  $f \in C^0(D)$ ,  $p(t) > 0$  pro  $t \in J$ , kde  $J = [0, \infty)$ ,  $D = J \times \mathbb{R}^3$ . Nechť  $t_0 \in J$  a  $u, v$  jsou řešení diferenciální rovnice

$$(p(t)z')' + q(t)z = 0,$$

splňující počáteční podmínky  $u(t_0) = 0$ ,  $u'(t_0) = 1$ ,  $v(t_0) = 1$ ,  $v'(t_0) = 0$ . Položme

$$a(t) = \max \{ |u(t)|, |v(t)| \}, \quad b(t) = \max \{ |u'(t)|, |v'(t)| \},$$

$$c(t) = |q(t)|a^2(t) + p(t)b^2(t) \quad \text{pro } t \in [t_0, \infty)$$

Užitím funkcí  $a(t)$ ,  $b(t)$ ,  $c(t)$  jsou v práci uvedeny apriorní odhady řešení a jejich derivací (na  $[t_0, \infty)$ ) diferenciální rovnice

$$(p(t)(p(t)x')')' + 4p(t)q(t)x' + 2(p(t)q(t))'x = f(t, x, x'), \\ (p(t)x')' ).$$

## РЕЗЮМЕ

### Границы решений нелинейного дифференциального уравнения

С в а т о с л а в   С т а н е к

Пусть  $p, q \in C^0(J)$ ,  $pq \in C^1(J)$ ,  $f \in C^0(D)$ ,  $p(t) > 0$  для  $t \in J$ , где  $J = [0, \infty)$ ,  $D = J \times R^3$ . Пусть  $t_0 \in J$  и  $u, v$  - решения дифференциального уравнения

$$(p(t)z')' + q(t)z = 0,$$

удовлетворяющие начальным условиям  $u(t_0)=0, u'(t_0)=1, v(t_0)=1, v'(t_0)=0$ . Положим

$$a(t) = \max \{|u(t)|, |v(t)|\}, \quad b(t) = \max \{|u'(t)|, |v'(t)|\},$$

$$c(t) = |q(t)|a^2(t) + p(t)b^2(t) \quad \text{для } t \in [t_0, \infty).$$

В работе с помощью функций  $a(t)$ ,  $b(t)$ ,  $c(t)$  приведены априорные оценки решений и их производных (на  $[t_0, \infty)$ ) дифференциального уравнения

$$(p(t)(p(t)x')')' + 4p(t)q(t)x' + 2(p(t)q(t))'x = f(t, x, x', (px')')$$