

Acta Universitatis Palackianae Olomucensis. Facultas Rerum
Naturalium. Mathematica

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Acta Universitatis Palackianae Olomucensis. Facultas Rerum Naturalium. Mathematica, Vol. 24 (1985), No. 1, 97--105

Persistent URL: <http://dml.cz/dmlcz/120157>

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**THE EXPECTED DISCOUNTED REWARD FROM
 A MARKOV REPLACEMENT PROCESS**

PAVLA KUNDEROVÁ

(Received March 21, 1984)

1. Basic definitions and notations

Let a homogeneous Markov process with rewards $\{X_t, t \geq 0\}$ describing the evolution of a system in state space $I = \{1, 2, \dots, r\}$ be defined by exit intensities $(\mu(1), \dots, \mu(r))$, $0 < \mu(j) \leq \infty$, $j = 1, \dots, r$, and by a stochastic matrix $\mathbf{P} = \|p(i, j)\|_{i, j=1}^r$, $p(i, i) = 0$ of transition probabilities in the moment of exit. We constitute a matrix of so called transition intensities $\mathbf{M} = \|\mu(i, j)\|_{i, j=1}^r$, where $\mu(i, j) = \mu(i)p(i, j)$ for $i \neq j$, $\mu(i, i) = -\mu(i)$,

$$\mu(i, i) = -\sum_{j \neq i} \mu(i, j). \quad (1)$$

The system being in state i at time t passes during the infinitesimal interval $(t, t + dt)$ into state j with the probability $\mu(i, j) dt$.

Consider a situation, where the development of the process can be influenced by an action called replacement, see [2]. Under a *replacement of type $(i, +j)$* we mean the instantaneous shift of the system from state i into state j . The information of the evolution of the process up to the n -th state change is given by the sequence of states visited

$$i_0, i_1, \dots, i_{n-1}, i_n = j \quad (2)$$

by the corresponding sojourn times

$$t_0, t_1, \dots, t_{n-1}, \quad (3)$$

and by the sequence

$$\delta_0, \delta_1, \dots, \delta_{n-1}, \quad (4)$$

where $\delta_m = 0$ if the system was left i_m without interference and $\delta_m = 1$ if the passage from i_m into i_{m+1} was the result of replacement. For the history of the process up to the n -th state change we use the notation

$$\omega_n = [i_0, t_0, \delta_0; i_1, t_1, \delta_1; \dots; i_{n-1}, t_{n-1}, \delta_{n-1}; i_n],$$

and we note the complete history of the process (according to [2])

$$\omega = [i_0, t_0, \delta_0; i_1, t_1, \delta_1; \dots].$$

A replacement policy (see [2]) is a decision for all possible sequences (2)–(4) and all states j , on how long the system will be left in j without shifting (maximal sojourn time) and in what state is to be shifted. Since we do not want to exclude the random choice of these quantities, we identify a replacement policy with a sequence of functions

$$F = \{ {}^n F_k(t/\omega_n) \}, \quad k = 1, 2, \dots, r; n = 0, 1, 2, \dots \quad (5)$$

where ${}^n F_k(t/\omega_n)$ is the probability that the maximal sojourn time in i_n will be less than t and that the eventual shift will be into $k \neq i_n$. We make

Assumption 1. We consider only such replacement policies F where with probability 1

- a) there exists only a finite number of replacements in every finite interval,
- b) there are not two or more replacements in the same moment.

According to the assumption to nearly every ω is assigned the trajectory $\{Y_t, t \geq 0\}$, being not left continuous at time of the transition and not right continuous at time of the replacement. In what follows we denote by

$\sigma_0 = 0, \sigma_1, \sigma_2, \dots$ the moments in which the trajectory is not continuous,
 $Y_t^- = Y_t, t > 0; Y_0^- = Y_0; Y_t^+ = Y_{t+}, t \geq 0;$

E_j the mathematical expectation in a process without replacements under the condition $i_0 = j$,

E_j^F the mathematical expectation in a replacement process under the replacement policy F and under the condition $i_0 = j$,

D the set of couples $(i, +j)$ meaning the admissible replacements,

$D_i = \{j : (i, +j) \in D\}$.

The reward from the process (see [2]) is defined by the following sets of numbers:
 $q^i, i \in I,$ the reward per a time unit in state i ;

$r^i, i, j \in I,$ the reward from transition (i, j) , we set $r(i, i) = 0$;

$v(i, j), i, j \in I,$ the reward from the replacement $(i, +j)$, we set $v(i, i) = 0$.

A stationary replacement policy f is given by function $f(j)$ defined on a subset $I_f \subset I$ and taking values in I such that $f(j) \in D_j$ for $j \in I_f, f(j) \neq j$. The replacement policy f is the prescription to realize instantaneously the replacement $j \rightarrow f(j)$ whenever the transition in state $j \in I_f$ occurs. No replacements are made in states $j \notin I_f$.

Let us make yet

Assumption 2.

$$(i, +j) \in D, (j, +k) \in D \Rightarrow (i, +k) \in D \text{ or } i = k, \\ v(i, j) + v(j, k) \leq v(i, k).$$

2. The expected discounted reward from the process

Let R_T be the reward from the process up to the time T , in accordance with the previous definitions

$$R_T = \int_0^T \varrho(Y_t) dt + \sum_{n=0}^N [r(Y_{\sigma_n}^-, Y_{\sigma_n}) + v(Y_{\sigma_n}, Y_{\sigma_n}^+)], \quad \sigma_N \leq T < \sigma_{N+1}.$$

The Laplace – Stieltjes transform

$$R = \int_0^{\infty} e^{-\lambda T} dR(T), \quad \lambda > 0$$

is the discounting of the reward, λ is so called discount factor (see [3]).

In the sequel we use the following statement given in [2], page 349, formula (7): For $\lambda > 0$ holds

$$(\mu(j) + \lambda) E_j R = \varrho(j) + \sum_{k \neq j} \mu(j, k) [r(j, k) + E_k R], \quad j = 1, 2, \dots, r, \quad (6)$$

moreover the expected discounted rewards $E_j R$, $j = 1, 2, \dots, r$ are uniquely determined by (6).

We confine our study of discounted reward from the replacement process to the stationary replacement policies f only.

Let us denote for simplicity $E_f^j R = \Theta_f(j)$.

If $j \in I_f$ then (6) takes the form

$$(\mu(j) + \lambda) \Theta_f(j) = \varrho(j) + \mu(j, f(j)) [v(j, f(j)) + \Theta_f(f(j))]$$

which being modified to include $\mu(j) = \infty$,

$$\Theta_f(j) = v(j, f(j)) + \Theta_f(f(j)).$$

If $j \notin I_f$ then from (6)

$$(\mu(j) + \lambda) \Theta_f(j) = \varrho(j) + \sum_{k \neq j} \mu(j, k) [r(j, k) + \Theta_f(k)].$$

We have thus established a system of equations for determining the expected discounted reward from the process under the stationary replacement policy f :

$$\begin{aligned} v(j, f(j)) + \Theta_f(f(j)) - \Theta_f(j) &= 0, & j \in I_f, & (7) \\ \varrho(j) + \sum_{k \neq j} \mu(j, k) [r(j, k) + \Theta_f(k)] - \lambda \Theta_f(j) &= 0, & j \notin I_f. \end{aligned}$$

Theorem 1

System of equations (7) has exactly one solution $\Theta_f(j)$, $j = 1, \dots, r$.

Proof: For simplicity let us assume $I_f = \{1, \dots, j-1\}$, $1 < j \leq r$. The matrix of system (7) has then the form

$$\mathbf{M}^* = \left\| \begin{array}{ccc|ccc} -1 & 0 & \dots & 0 & \text{in any row only one unit,} & \\ & 0 & -1 & \dots & \text{the other elements zeros} & \\ \dots & \dots & \dots & \dots & & \\ & 0 & 0 & \dots & -1 & \\ \hline \mu(j, 1) & \dots & \mu(j, j-1) & & \mu(j, j) - \lambda & \dots & \mu(j, r) \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots \\ \mu(r, 1) & \dots & \mu(r, j-1) & & \mu(r, j) & \dots & \mu(r, r) - \lambda \end{array} \right\| =$$

$$= \left\| \begin{array}{c|c} \mathbf{A} & \mathbf{B} \\ \mathbf{C} & \mathbf{D} \end{array} \right\|.$$

For finding the value of $\det \mathbf{M}^*$ we add for every $i = 1, \dots, j-1$ the i -th column to the $f(i)$ -th column. We obtain

$$\det \mathbf{M}^* = \det \left\| \begin{array}{c|c} \mathbf{A} & \mathbf{0} \\ \mathbf{C} & \mathbf{D}^* \end{array} \right\|$$

where

$$\mathbf{D}^* = \left\| \begin{array}{ccc} d_{jj} - \lambda & \dots & d_{jr} \\ \dots & \dots & \dots \\ d_{rj} & \dots & d_{rr} - \lambda \end{array} \right\|,$$

$$d_{kk} \leq 0, d_{kl} \geq 0, k \neq l, k, l = j, j+1, \dots, r; \sum_{i=j}^r d_{ki} = 0.$$

As the only nonnegative characteristic number of the quasistochastic matrix (see [4], page 181) is $\lambda = 0$, it holds $\det \mathbf{D}^* \neq 0$ for $\lambda > 0$. Thus $\det \mathbf{M}^* = \det \mathbf{A} \cdot \det \mathbf{D}^* \neq 0$ and the matrix \mathbf{M}^* is of full rank.

Let us introduce the *maximal expected discounted reward* (see [3], page 24)

$$\hat{\theta}(j) = \max_f \{\theta_f(j)\}, \quad j \in I.$$

The stationary replacement policy \hat{f} is called optimal, if

$$\hat{\theta}(j) = \theta_{\hat{f}}(j), \quad j \in I.$$

The maximal reward will be characterized by the following theorem, in whose proof Howard's iteration procedure for finding $\hat{\theta}(j)$, $j \in I$, and the responsive optimal stationary replacement policy will be described (see [1]).

Theorem 2

The maximal reward $\hat{\theta}(j)$ is the unique solution of the following equation

$$\begin{aligned} & \max \{v(j, k) + \hat{\theta}(k) - \hat{\theta}(j), k \in D_j\}; \\ e(j) + \sum_{k \neq j} \mu(j, k) [r(j, k) + \hat{\theta}(k) - \hat{\theta}(j)] - \lambda \hat{\theta}(j) &= 0, \quad j \in I. \end{aligned} \quad (8)$$

If f is such a stationary replacement policy that the maximum in the compound brackets is achieved for $j \in I_f$ by the expression $v(j, f(j)) + \hat{\Theta}(f(j)) - \hat{\Theta}(j)$ and for $j \notin I_f$ by the expression $q(j) + \sum_{k \neq j} \mu(j, k) [r(j, k) + \hat{\Theta}(k) - \hat{\Theta}(j)] - \lambda \hat{\Theta}(j)$, then f is the optimal stationary replacement policy.

Proof:

We prove first the existence of the solution of system (8) by Howard's iteration procedure. Choosing an arbitrary stationary replacement policy f_0 we successively determine the stationary replacement policies f_1, \dots, f_n, \dots as follows:

a) we solve the system of equations (to simplify the notation we write $\Theta_{f_n}(j) = \Theta_n(j)$)

$$\begin{aligned} v(j, f_n(j)) + \Theta_n(f_n(j)) - \Theta_n(j) &= 0, & j \in I_{f_n}, \\ q(j) + \sum_{k \neq j} \mu(j, k) [r(j, k) + \Theta_n(k) - \Theta_n(j)] - \lambda \Theta_n(j) &= 0, & j \notin I_{f_n}, \end{aligned} \quad (9)$$

by Theorem 1 $\Theta_n(j), j \in I$ are determined by the system uniquely;

b) for all $j \in I$ we successively determine

$$\begin{aligned} \max \{v(j, k) + \Theta_n(k) - \Theta_n(j), k \in D_j; \\ q(j) + \sum_{k \neq j} \mu(j, k) [r(j, k) + \Theta_n(k) - \Theta_n(j)] - \lambda \Theta_n(j)\}. \end{aligned}$$

The policy f_{n+1} is determined as follows:

if the maximum for a fixed $j \in I$ is reached by the expression

$$q(j) + \sum_{k \neq j} \mu(j, k) [r(j, k) + \Theta_n(k) - \Theta_n(j)] - \lambda \Theta_n(j),$$

we choose

$$j \notin I_{f_{n+1}};$$

in the contrary, if the maximum is obtained by the expression

$$v(j, k) + \Theta_n(k) - \Theta_n(j) \quad \text{for some } k \in D_j,$$

we choose

$$j \in I_{f_{n+1}}, f_{n+1}(j) = k;$$

here the choice of $k = f_n(j)$ is preferred.

c) If the policy f_{n+1} does not possess the property required by Assumption 1, namely that $f_{n+1}(j) \notin I_{f_{n+1}}$ for all $j \in I_{f_{n+1}}$, we change it to the policy f'_{n+1} as follows:

in such states $j \in I_{f_{n+1}}$ where $f_{n+1}(j) \in I_{f_{n+1}}$ we take $f'_{n+1}(j) = f_{n+1}(f_{n+1}(j))$, in the remaining states we have $f'_{n+1}(j) = f_{n+1}(j)$. We now show the correctness of the procedure in c).

Suppose that $f_n(j) \notin I_{f_n}$ for all $j \in I_{f_n}$ and that the policy f_{n+1} was constructed in the above described way. Let

$$j \in I_{f_{n+1}}, f_{n+1}(j) = k \in I_{f_{n+1}}, f_{n+1}(k) = k'. \quad (10)$$

By the construction of the replacement policy f_{n+1} this implies that

$$v(k, k') + \Theta_n(k') - \Theta_n(k) \geq 0,$$

and therefore by Assumption 2

$$\begin{aligned} v(j, k) + \Theta_n(k) - \Theta_n(j) &\leq v(j, k) + v(k, k') + \Theta_n(k') - \Theta_n(j) \leq \\ &\leq v(j, k') + \Theta_n(k') - \Theta_n(j). \end{aligned}$$

The equality must hold here, because the expression

$$v(j, k) + \Theta_n(k) - \Theta_n(j)$$

is maximal (replacement $j \rightarrow k$ under the policy f_{n+1} in the state j) from all expressions $v(j, i) + \Theta_n(i) - \Theta_n(j)$, $i \in D_j$. We are thus led to the conclusion that k' is equivalent to k for state j , moreover

$$v(k, k') + \Theta_n(k') - \Theta_n(k) = 0. \quad (11)$$

We can prove (by contradiction) that also $k \in I_{f_n}$, $k' = f_n(k)$. Therefore there cannot occur the situation

$$f_{n+1}(j) = k, \quad f_{n+1}(k) = k', \quad f_{n+1}(k') = k'',$$

then it would be also

$$f_n(k) = k', \quad f_n(k') = k'',$$

which however contradicts the assumption on the replacement policy f_n . It suffices therefore to change the constructed policy f_{n+1} in the way described in c).

For thus constructed replacement policy then

$$\begin{aligned} v(j, f_{n+1}(j)) + \Theta_n(f_{n+1}(j)) - \Theta_n(j) &\geq 0, \quad j \in I_{f_{n+1}}, \quad (12) \\ \varrho(j) + \sum_{k \neq j} \mu(j, k) [r(j, k) + \Theta_n(k) - \Theta_n(j)] - \lambda \Theta_n(j) &\geq 0, \quad j \notin I_{f_{n+1}}. \end{aligned}$$

By Theorem 1

$$\begin{aligned} v(j, f_{n+1}(j)) + \Theta_{n+1}(f_{n+1}(j)) - \Theta_{n+1}(j) &= 0, \quad j \in I_{f_{n+1}}, \quad (13) \\ \varrho(j) + \sum_{k \neq j} \mu(j, k) [r(j, k) + \Theta_{n+1}(k) - \Theta_{n+1}(j)] - \lambda \Theta_{n+1}(j) &= 0, \quad j \notin I_{f_{n+1}}. \end{aligned}$$

Subtracting (12) from (13) we obtain

$$\begin{aligned} \Theta_{n+1}(f_{n+1}(j)) - \Theta_n(f_{n+1}(j)) - \Theta_{n+1}(j) + \Theta_n(j) &\leq 0, \quad j \in I_{f_{n+1}}, \quad (14) \\ \sum_{k \neq j} \mu(j, k) [\Theta_{n+1}(k) - \Theta_n(k) - \Theta_{n+1}(j) + \Theta_n(j)] - \lambda(\Theta_{n+1}(j) - \Theta_n(j)) &\leq 0, \quad j \notin I_{f_{n+1}}. \end{aligned}$$

For $j \notin I_{f_{n+1}}$ we obtain from (14)

$$[\Theta_n(j) - \Theta_{n+1}(j)] (\lambda + \sum_{k \neq j} \mu(j, k)) \leq \sum_{k \neq j} \mu(j, k) (\Theta_n(k) - \Theta_{n+1}(k)),$$

whence after some modification

$$\Theta_n(j) - \Theta_{n+1}(j) \leq \frac{\mu(j)}{\lambda + \mu(j)} \sum_{k \in I} p(j, k) [\Theta_n(k) - \Theta_{n+1}(k)]$$

it means by using the notation

$$c = \max_{j \in I_{f_{n+1}}} \left\{ \frac{\mu(j)}{\lambda + \mu(j)} \right\}$$

we have for $j \notin I_{f_{n+1}}$

$$\Theta_n(j) - \Theta_{n+1}(j) \leq c \max_{k \in I} \{\Theta_n(k) - \Theta_{n+1}(k)\}. \quad (15)$$

Relation (15) is valid also for $j \in I_{f_{n+1}}$ since for these j by the first row in (14)

$$\Theta_n(j) - \Theta_{n+1}(j) \leq \Theta_n(f_{n+1}(j)) - \Theta_{n+1}(f_{n+1}(j)),$$

and Assumption 1 yields $f_{n+1}(j) \notin I_{f_{n+1}}$.

Thus, from (15) we have

$$\max_{j \in I} \{\Theta_n(j) - \Theta_{n+1}(j)\} \leq c \max_{k \in I} \{\Theta_n(k) - \Theta_{n+1}(k)\}.$$

The last inequality may be satisfied by $0 < c < 1$ if and only if

$$\Theta_n(j) - \Theta_{n+1}(j) \leq 0, \quad j \in I,$$

i.e. if

$$\Theta_n(j) \leq \Theta_{n+1}(j), \quad j \in I.$$

The sequence $\Theta_n(j)$ is nondecreasing if n is increasing. As the set of the stationary replacement policies is finite, there exists m such that

$$\Theta_m(j) = \Theta_{m+1}(j), \quad j \in I.$$

Using (9) and constructing the policy f_{m+1} in the above way we obtain for $j \in I_{f_{m+1}}$

$$\begin{aligned} & \max \{v(j, k) + \Theta_m(k) - \Theta_m(j), k \in D_j\}; \\ \varrho(j) + \sum_{k \neq j} \mu(j, k) [r(j, k) + \Theta_m(k) - \Theta_m(j)] - \lambda \Theta_m(j) &= \\ &= v(j, f_{m+1}(j)) + \Theta_m(f_{m+1}(j)) - \Theta_m(j) = \\ &= v(j, f_{m+1}(j)) + \Theta_{m+1}(f_{m+1}(j)) - \Theta_{m+1}(j) = 0. \end{aligned}$$

For $j \notin I_{f_{m+1}}$ we have

$$\begin{aligned} & \max \{v(j, k) + \Theta_m(k) - \Theta_m(j), k \in D_j\}; \\ \varrho(j) + \sum_{k \neq j} \mu(j, k) [r(j, k) + \Theta_m(k) - \Theta_m(j)] - \lambda \Theta_m(j) &= \\ &= \varrho(j) + \sum_{k \neq j} \mu(j, k) [r(j, k) + \Theta_m(k) - \Theta_m(j)] - \lambda \Theta_m(j) = \\ &= \varrho(j) + \sum_{k \neq j} \mu(j, k) [r(j, k) + \Theta_{m+1}(k) - \Theta_{m+1}(j)] - \lambda \Theta_{m+1}(j) = 0. \end{aligned}$$

We can see that $\hat{\Theta}(j) = \Theta_m(j)$, $j \in I$, is a solution of equation (8). We verify now that (8) determines $\hat{\Theta}(j)$ uniquely.

Let $\bar{\Theta}(j)$, $j \in I$, be another solution of equation (8), i.e. let

$$\begin{aligned} & \max \{v(j, k) + \bar{\theta}(k) - \bar{\theta}(j), \quad k \in D_j; \\ e(j) + \sum_{k \neq j} \mu(j, k) [r(j, k) + \bar{\theta}(k) - \bar{\theta}(j)] - \lambda \bar{\theta}(j) \} = 0, \quad j \in I. \end{aligned} \quad (16)$$

Let f be the replacement policy defined by Theorem 2. Then

$$\begin{aligned} & v(j, f(j)) + \hat{\theta}(f(j)) - \hat{\theta}(j) = 0, \quad j \in I_f, \\ e(j) + \sum_{k \neq j} \mu(j, k) [r(j, k) + \hat{\theta}(k) - \hat{\theta}(j)] - \lambda \hat{\theta}(j) = 0, \quad j \notin I_f. \end{aligned} \quad (17)$$

According to (16)

$$\begin{aligned} & v(j, f(j)) + \bar{\theta}(f(j)) - \bar{\theta}(j) \leq 0, \quad j \in I_f, \\ e(j) + \sum_{k \neq j} \mu(j, k) [r(j, k) + \bar{\theta}(k) - \bar{\theta}(j)] - \lambda \bar{\theta}(j) \leq 0, \quad j \notin I_f. \end{aligned} \quad (18)$$

Subtracting (17) from (18) we obtain

$$\begin{aligned} & \bar{\theta}(f(j)) - \hat{\theta}(f(j)) - \bar{\theta}(j) + \hat{\theta}(j) \leq 0, \quad j \in I_f, \\ \sum_{k \neq j} \mu(j, k) [\bar{\theta}(k) - \hat{\theta}(k) - \bar{\theta}(j) + \hat{\theta}(j)] - \lambda(\bar{\theta}(j) - \hat{\theta}(j)) \leq 0, \quad j \notin I_f. \end{aligned} \quad (19)$$

For simplicity we write $\bar{\theta}(j) - \hat{\theta}(j) = w(j)$, $j \in I$, and obtain for $j \notin I_f$ from the second equation of (19)

$$w(j) \geq \frac{\mu(j)}{\lambda + \mu(j)} \sum_{k \neq j} p(j, k) w(k) \geq d \min_{k \in I} \{w(k)\},$$

where

$$d = \min_{j \notin I_f} \left\{ \frac{\mu(j)}{\lambda + \mu(j)} \right\}.$$

The relation

$$w(j) \geq d \min_{k \in I} \{w(k)\}$$

is valid for all $j \in I$ with respect to (19) and to Assumption 1. This yields

$$\min_{j \in I} \{w(j)\} \geq d \min_{k \in I} \{w(k)\}.$$

Since $0 < d < 1$, this inequality may hold only if $\min_{j \in I} \{w(j)\} \geq 0$, i.e. if

$$w(j) = \bar{\theta}(j) - \hat{\theta}(j) \geq 0, \quad j \in I,$$

it is

$$\bar{\theta}(j) \geq \hat{\theta}(j), \quad j \in I.$$

Analogous may be proved that $\bar{\theta}(j) \leq \hat{\theta}(j)$, $j \in I$, therefrom

$$\bar{\theta}(j) = \hat{\theta}(j), \quad j \in I.$$

It still remains to verify that the policy f is an optimal stationary one.

Theorem 1 tells us that the system

$$\begin{aligned} v(j, \hat{f}(j)) + \Theta(\hat{f}(j)) - \Theta(j) &= 0, & j \in I_{\hat{f}}, \\ \varrho(j) + \sum_{k \neq j} \mu(j, k) [r(j, k) + \Theta(k) - \Theta(j)] - \lambda \Theta(j) &= 0, & j \notin I_{\hat{f}}, \end{aligned} \quad (20)$$

determines $\Theta_{\hat{f}}(j)$, $j \in I$, uniquely. Comparing (20) and (19) we obtain $\Theta_{\hat{f}}(j) = \hat{\Theta}(j)$, $j \in I$.

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OČEKÁVANÝ DISKONTOVANÝ VÝNOS Z MARKOVOVA PROCESU S VÝNOSY A OBNOVAMI

Souhrn

Uvažuje se Markovův proces s výnosy a obnovami popsáný v článku [2]. Je odvozena soustava rovnic pro určování očekávaného diskontovaného výnosu z procesu (viz [3]) při užití stacionární strategie obnovy. Maximální očekávaný diskontovaný výnos je charakterizován větou 2, v jejímž důkaze je popsána Howardova iterační metoda (viz [1]) nacházení maximálního výnosu a metoda určování odpovídající optimální stacionární strategie.

ОЖИДАЕМЫЙ ДОХОД С ПЕРЕОЦЕНКОЙ ИЗ МАРКОВСКОГО ПРОЦЕССА С ДОХОДАМИ И ВОССТАНОВЛЕНИЯМИ

Резюме

В работе рассмотрен процесс Маркова с восстановлениями и доходами определенный в [2]. Найдена система уравнений для определения ожидаемого дохода с переоценкой (смотри [3]) при использовании стационарной стратегии восстановления. Максимальный ожидаемый доход с переоценкой характеризуется теоремой 2, в доказательстве которой описан итерационный метод Ховарда для нахождения максимального дохода и нахождения отвечающей оптимальной стационарной стратегии.