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**A NOTE ON REGULAR POINTS FOR SOLUTIONS  
OF NONLINEAR ELLIPTIC SYSTEMS**

JOSEF DANĚČEK AND EUGEN VISZUS

ABSTRACT. It is shown in this paper that gradient of vector valued function  $u(x)$ , solution of a nonlinear elliptic system, cannot be too close to a straight line without  $u(x)$  being regular.

**0. - Introduction**

In this paper we shall deal with points of regularity for weak solutions of nonlinear elliptic systems of the second order

$$(0.1) \quad -D_i a_i^r(x, u, Du) + a^r(x, u, Du) = -D_i f_i^r(x) + f^r(x), \quad r = 1, \dots, N,$$

in an bounded open set  $\Omega \subset \mathcal{R}^n$ ,  $n \geq 3$ , with Lipschitz boundary  $\partial\Omega$ . Here the summation over repeated subscript is understood and  $x = (x_1, \dots, x_n) \in \Omega$ ,  $u = (u_1, \dots, u_N)$ ,  $N \geq 2$ ,  $D_i = \partial/\partial x_i$ ,  $Du = (Du_1, \dots, Du_N)$ . By a weak solution of (0.1) we mean a function  $u \in W^{1,2}(\Omega, \mathcal{R}^N)$  (for informations see [4], [5]) such that

$$(0.2) \quad \int_{\Omega} (a_i^r(x, u, Du) D_i \varphi^r + a^r(x, u, Du) \varphi^r) dx = \int_{\Omega} (f_i^r(x) D_i \varphi^r + f^r(x) \varphi^r) dx, \quad \varphi \in C_0^\infty(\Omega, \mathcal{R}^N).$$

For the sake of simplification we denote by  $|\cdot|$  and  $\langle \cdot, \cdot \rangle$  the norm and scalar product in  $\mathcal{R}^n$  as well as in  $\mathcal{R}^N$  and  $\mathcal{R}^{nN}$ . If  $x \in \mathcal{R}^n$  and  $r$  is a positive real number, we set  $B(x, r) = \{y \in \mathcal{R}^n : |y - x| < r\}$ , i.e., the open ball in  $R^n$ ,  $\Omega(x, r) = B(x, r) \cap \Omega$ . The meaning of  $\Omega_0 \Subset \Omega$  is that the closure of  $\Omega_0$  is contained in  $\Omega$ , i.e.  $\overline{\Omega}_0 \subset \Omega$ .

We will use the space  $C_0^\infty(\Omega, R^N)$ , Hölder spaces  $C^{0,\alpha}(\overline{\Omega}, R^N)$ ,  $C^{0,\alpha}(\Omega, R^N)$  and Sobolev spaces  $W^{k,p}(\Omega, R^N)$ ,  $W_{loc}^{k,p}(\Omega, R^N)$ ,  $W_0^{k,p}(\Omega, R^N)$  (for detailed informations see, e.g. [4]).

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Denote by

$$f_{x_0,R} = \frac{1}{|B(x_0,R)|} \int_{B(x_0,R)} f(x)dx = \int_{B(x_0,R)} f(x)dx$$

the mean value over the set  $B(x_0,R)$  of the function  $f \in L^1(B(x_0,R), \mathcal{R}^N)$ .

About parameters of system (0.1) we suppose:

$$(0.3) \quad a_i^r, a^r \in C^1(\Omega \times \mathcal{R}^N \times \mathcal{R}^{nN}).$$

For  $(x, \xi, p) \in \Omega \times \mathcal{R}^N \times \mathcal{R}^{nN}$  with  $|\xi| \leq L$ ,  $L > 0$  is a constant

$$(0.4) \quad |a_i^r(x, \xi, p)|, |a^r(x, \xi, p)| \leq C_1(L)(1 + |p|),$$

$$(0.5) \quad \left| \frac{\partial a_i^r(x, \xi, p)}{\partial p_j^s} \right|, \left| \frac{\partial a^r(x, \xi, p)}{\partial p_j^s} \right| \leq C_1(L),$$

$$(0.6) \quad \left| \frac{\partial a_i^r(x, \xi, p)}{\partial \xi_k} \right|, \left| \frac{\partial a_i^r(x, \xi, p)}{\partial x_l} \right|, \left| \frac{\partial a^r(x, \xi, p)}{\partial \xi_k} \right|,$$

$$\left| \frac{\partial a^r(x, \xi, p)}{\partial x_l} \right| \leq C_1(L)(1 + |p|),$$

$$(0.7) \quad \frac{\partial a_i^r(x, \xi, p)}{\partial p_j^s} \longrightarrow d_{ij}^r(x, \xi), \quad \text{if } |p| \rightarrow \infty, \text{ uniformly in } \Omega \times \mathcal{R}^N$$

$$(0.8) \quad f_i^r(x) \in W^{1,q}(\Omega), \quad f^r(x) \in W^{1,q/2}(\Omega), \quad q > n,$$

$$(0.9) \quad \sum_{i,r} \|f_i^r(x)\|_{1,q} + \sum_r \|f^r(x)\|_{1,q} \leq C_2, C_2 > 0 \text{ is a constant,}$$

$$(0.10) \quad \frac{\partial a_i^r(x, \xi, p)}{\partial p_j^s} \eta_i^r \eta_j^s \geq \mu(L)|\eta|^2 \quad \text{for all } \eta \in \mathcal{R}^{nN},$$

$$(x, \xi, p) \in \Omega \times \mathcal{R}^N \times \mathcal{R}^{nN}.$$

It is known that if  $u \in W^{1,2}(\Omega, \mathcal{R}^N)$  solves (0.1) in weak sense and conditions stated above are fulfilled then  $u \in W_{loc}^{2,2}(\Omega, \mathcal{R}^N)$  (see e.g.[1]). Main result of this paper is the following theorem:

**Theorem 0.11.** *Let  $M > 0$  be a constant and  $u \in W^{1,2} \cap C^{0,\beta}(\Omega, \mathcal{R}^N)$ , ( $0 < \beta < 1$ ) be a weak solution of system (0.1) with conditions (0.3) - (0.10). There exist constants  $\varepsilon_1 > 0$ ,  $R_1 > 0$  such that if for some  $x^0 \in \Omega$ ,  $R < \min(R_1, \text{dist}(x^0, \partial\Omega))$ ,  $\nu \in \mathcal{S}^{nN-1}$ ,  $\pi \in \mathcal{R}^{nN}$ ,  $|\pi| \leq M$  we have*

$$(0.12) \quad \int_{B(x^0, R)} |Du(x) - (Du)_{x^0, R}|^2 dx \leq M^2,$$

$$(0.13) \quad \int_{B(x^0, R)} |Du(x) - (Du)_{x^0, R} - \pi| dx - \int_{B(x^0, R)} |(Du(x) - (Du)_{x^0, R} - \pi, \nu)| dx < \varepsilon_1,$$

then  $u$  is regular in a neighborhood of  $x^0$  (there is  $\delta > 0$  such that

$$u \in C^{1,\alpha}(\overline{B(x^0, \delta)}, \mathcal{R}^N), \alpha \in (0, 1 - n/q).$$

**Remark.** The condition that a weak solution  $u \in W^{1,2}(\Omega, \mathcal{R}^N)$  of system (0.1) is in addition from the space  $C^{0,\beta}(\Omega, \mathcal{R}^N)$  be fulfilled for  $n = 3$  by means of Sobolev imbedding theorem ( $W_{loc}^{2,2}(\Omega, \mathcal{R}^N) \hookrightarrow C^{0,1/2}(\Omega, \mathcal{R}^N)$ , see [4]). For a motivation to this result we refer to [3]. The proof of theorem 0.11 is based on some considerations of paper [2] and the fact that from (0.2) we obtain an equation in variation which has the following form (for information see e.g. [5])

$$(0.14) \quad \int_{\Omega} \delta_{kl} [B_{ij}^{rs}(x, U) D_j U_s^l D_i \varphi_k^r + B_j^{rs}(x, U) D_j U_s^l \varphi_k^r] dx \\ = \int_{\Omega} [G_i^{rk} D_i \varphi_k^r + G^{rk} \varphi_k^r] dx, \quad \varphi \in C_0^\infty(\Omega, \mathcal{R}^{nN}),$$

where  $i, j, k, l = 1, \dots, n$ ,  $r, s = 1, \dots, N$ ,  $U = \{U_s^l\} = \{D_l u_s\}_{l=1, \dots, n}^{s=1, \dots, N}$ ,  $\delta_{kl}$  - Kronecker delta,

$$B_{ij}^{rs}(x, U) = \frac{\partial a_i^r}{\partial p_j^s}(x, u(x), U), \quad B_j^{rs}(x, U) = \frac{\partial a^r}{\partial p_j^s}(x, u(x), U),$$

$$G_i^{rk}(x) = D_k f_i^r - \frac{\partial a_i^r}{\partial x_k} - \frac{\partial a_i^r}{\partial \xi_s} \frac{\partial u_s}{\partial x_k}, \quad G^{rk}(x) = D_k f^r - \frac{\partial a^r}{\partial x_k} - \frac{\partial a^r}{\partial \xi_s} \frac{\partial u_s}{\partial x_k}.$$

Because the system (0.14) is quasilinear elliptic system and  $U = Du$ , it is sufficient to prove an assertion for quasilinear elliptic system analogous to theorem 0.11.

**1. - The quasilinear case**

Let us consider a quasilinear elliptic system

$$(1.1) \quad -D_i(A_{ij}^{rs}(x, u)D_j u^s) + A_j^{rs}(x, u)D_j u^s = -D_i g_i^r + g^r,$$

$x = (x_1, \dots, x_n) \in \Omega$ ,  $\Omega \subset \mathbb{R}^n$ ,  $n \geq 3$  is a bounded open set with Lipschitz boundary  $\partial\Omega$ ,  $u = (u^1, \dots, u^N)$ ,  $N \geq 2$ ,  $i, j = 1, \dots, n$ ,  $r, s = 1, \dots, N$ .

We suppose

$$(1.2) \quad A_{ij}^{rs}, A_j^{rs} \in C(\overline{\Omega} \times \mathbb{R}^N)$$

$$(1.3) \quad \sum_{i,j,r,s} |A_{ij}^{rs}| + \sum_{j,r,s} |A_j^{rs}| \leq L \text{ on } \Omega \times \mathbb{R}^N, \quad L > 0 \text{ is a constant,}$$

$$(1.4) \quad \text{there is } \lambda > 0 \text{ such that } A_{ij}^{rs}(x, \xi)\eta_i^r \eta_j^s \geq \lambda|\eta|^2 \text{ for all } \eta \in \mathbb{R}^{nN}, \\ (x, \xi) \in \overline{\Omega} \times \mathbb{R}^N$$

$$(1.5) \quad A_{ij}^{rs}(x, \xi) \longrightarrow d_{ij}^{rs}(x), \quad \text{as } |\xi| \rightarrow \infty, \text{ uniformly in } \Omega,$$

$$(1.6) \quad g_i^r \in L^p(\Omega), \quad g^r \in L^{p/2}(\Omega), \quad p > n.$$

By a weak solution of system (1.1) we mean a function  $u \in W^{1,2}(\Omega, \mathbb{R}^N)$  such that

$$(1.7) \quad \int_{\Omega} [A_{ij}^{rs}(x, u)D_j u^s D_i \varphi^r + A_j^{rs}(x, u)D_j u^s \varphi^r] dx \\ = \int_{\Omega} [g_i^r D_i \varphi^r + g^r \varphi^r] dx, \quad \varphi \in C_0^\infty(\Omega, \mathbb{R}^N).$$

It is matter of simple calculation to find that the type of system (0.14) is the same as the one of system (1.7) with assumptions (1.2) - (1.6). Now we may state

**Theorem 1.8.** *Let  $\Omega' \Subset \Omega$ . For every  $M > 0$  there exist a constants  $\varepsilon_1 > 0$ ,  $R_1 > 0$  such that if  $u \in W^{1,2}(\Omega, \mathbb{R}^N)$  is a weak solution of the system (1.1) with conditions (1.2) - (1.6) and if for some  $x^0 \in \Omega'$ ,  $R < \min(R_1, \text{dist}(x^0, \partial\Omega))$ ,  $\nu \in \mathcal{S}^{N-1}$ ,  $\pi \in \mathbb{R}^N$ ,  $|\pi| \leq M$  we have*

$$(1.9) \quad \int_{B(x^0, R)} |u(x) - (u)_{x^0, R}|^2 dx \leq M^2,$$

$$(1.10) \quad \int_{B(x^0, R)} |u(x) - (u)_{x^0, R} - \pi| dx - \int_{B(x^0, R)} |u(x) - (u)_{x^0, R} - \pi, \nu| dx < \varepsilon_1,$$

then  $u$  is regular in a neighborhood of  $x^0$  (there is  $\delta > 0$  such that

$$u \in C^{0,\alpha}(\overline{B(x^0, \delta)}, \mathcal{R}^N), \alpha \in (0, 1 - n/p).$$

It is clear that if theorem 1.8 will be proved then theorem 0.11 will be proved as well.

**Remark.** If we compare Theorem 1.8 with Theorem 3 in [3], we see the following: The assumption in Theorem 3 in [3] that for some  $x_0 \in \Omega$  and  $R$  (small)  $\int_{B(x_0, R)} |u|^2 dx \leq M$  is replaced by assumptions (1.5) and  $\int_{B(x_0, R)} |u - u_{x^0, R}|^2 dx \leq M$  in Theorem 1.8. Taking into account the relation between the spaces  $BMO$  and  $L^\infty$ , Theorem 1.8 may be seen as some generalization of Theorem 3 in [3].

One can say that the structural assumption (1.5) probably imply the boundedness of the solution of (1.1) and then our result is a corollary of the result in [3]. As the following example shows, the above mentioned consideration is not true in general.

**Example.** [6] Let  $\Omega = \{x \in \mathcal{R}^n : |x| < 1\}$  and let us consider the system

$$-D_i(A_{ij}^{rs}(x, u)D_j u^s) = 0,$$

where  $A_{ij}^{rs}(x, \xi) = \delta_{ij}\delta_{rs} + \eta(|\xi|)B_{ir}(x, \xi)B_{js}(x, \xi)$ ,  $\delta_{ij}$  -Kronecker delta,  $\eta \in C^\infty([0, \infty))$ ,  $\text{supp } \eta \subset [0, 1 + \varepsilon]$ ,  $\varepsilon > 0$ ,  $0 \leq \eta \leq 1$ ,  $\eta \equiv 1$  in  $[0, 1]$ ,

$$B_{ir}(x, \xi) = c \left( \delta_{ir} + b \frac{\xi_i \xi_r |x|^{2a-2}}{1 + |\xi|^2 |x|^{2a-2}} \right),$$

$$a \in [1, \frac{n}{2}), \quad b = \frac{2n}{n-2}, \quad c^2 = \frac{a(n-a)(n-2)^2}{(n-2a)^2(n-1)^2}.$$

The coefficients of this system satisfy all assumptions (1.2)-(1.5). The function  $u(x) = x/|x|^a$  is a solution of this system and  $u$  is unbounded in origin ( $a = 2, 3, \dots, [n/2]$ ). One may see that  $u \notin BMO(\Omega)$  too.

## 2. - The proof of Theorem 1.8

We will use the following results:

**Lemma 2.1.** (see [5]) Let  $g \in W^{1,2}(B(0, 1))$  be a solution of the equation

$$(2.2) \quad \int_{B(0,1)} a_{ij} D_j g D_i \varphi dx = 0, \quad \varphi \in C_0^\infty(B(0, 1))$$

in the unit ball  $B(0, 1)$  of  $\mathcal{R}^n$ , with bounded, measurable coefficients  $a_{ij}$  satisfying

$$(2.3) \quad \sum_{i,j} |a_{ij}| \leq L,$$

$$(2.4) \quad a_{ij}(x)\xi_i\xi_j \geq \lambda|\xi|^2, \quad \xi \in \mathcal{R}^n, \quad x \in B(0, 1).$$

Then there exist constants  $\alpha$  and  $Q$  depending only on  $L$ ,  $\lambda$  such that  $g(x)$  is  $\alpha$ -Hölder continuous in  $B(0, 1/2)$  and

$$(2.5) \quad \|g\|_{C^{0,\alpha}(B(0,1/2))} = \sup_{x \in B(0,1/2)} |g(x)| + \sup_{x,y \in B(0,1/2), x \neq y} \frac{|g(x) - g(y)|}{|x - y|^\alpha} \leq Q \|g\|_{L^2(B(0,1))}.$$

Using Lax-Milgram lemma we may prove

**Lemma 2.6.** *Let  $u \in W^{1,2}(\Omega, \mathcal{R}^N)$ ,  $x^0 \in \Omega$  and assumptions (1.2) - (1.4), (1.6) for system (1.1) be satisfied. Then there exists  $0 < R_0 \leq \text{dist}(x^0, \partial\Omega)$  such that for  $R \in (0, R_0]$  the linear elliptic system*

$$(2.7) \quad -D_i(A_{ij}^{rs}(x, u)D_j v_R^s) + A_j^{rs}(x, u)D_j v_R^s = -D_i g_i^r + g^r,$$

has a unique solution in  $W_0^{1,2}(B(x^0, R), \mathcal{R}^N)$ . Moreover

$$(2.8) \quad \int_{B(x^0, R)} |v_R(x) - (v_R)_{x^0, R}|^2 dx \leq c_3 R^{2(1-n/p)},$$

where  $c_3 = c_3(n, N, L, \lambda, R_0, \|g_i^r\|_p, \|g^r\|_{p/2})$ .

If we put  $\Omega' \subset\subset \Omega$  then the above estimate will be uniform in  $\Omega'$ .

The above lemma enables us to decompose the solution  $u$  of (1.1) as

$$(2.9) \quad u = v_{x^0, R} + w_{x^0, R} \text{ in } B(x^0, R).$$

If there will not be danger of misunderstanding, we will omit the subscripts  $x^0, R$ .

By classical way we may obtain for  $w_{x^0, R}$  Cacciopoli's inequality:

For  $x^0 \in \Omega$ ,  $0 < \rho < R < R_0 \leq \text{dist}(x^0, \partial\Omega)$

$$(2.10) \quad \int_{B(x^0, \rho)} |Dw_{x^0, R}(x)|^2 dx \leq \frac{c_4}{(R - \rho)^2} \int_{B(x^0, R)} |w_{x^0, R}(x) - (w_{x^0, R})_{x^0, R}|^2 dx,$$

where  $c_4 = c_4(n, N, L, \lambda)$ .

Now we present a fundamental result concerning the partial regularity of weak solutions to the system (1.1) with assumptions (1.2)-(1.6).

**Proposition 2.11.** (see [5], pp.147-149) Let  $\Omega' \Subset \Omega$ . There exist constants  $\varepsilon_0 > 0$ ,  $R_0 > 0$  such that if  $u \in W^{1,2}(\Omega, \mathcal{R}^N)$  is a weak solution of the system (1.1) with conditions (1.2) - (1.6) and if for some  $x^0 \in \Omega'$  and  $R < \min(R_0, \text{dist}(x^0, \partial\Omega))$

$$(2.12) \quad \int_{B(x^0, R)} |w_R(x) - (w_R)_{x^0, R}|^2 dx \leq \varepsilon_0^2,$$

then there exist  $\delta > 0$ ,  $\mu \in (0, 1 - n/p)$ , such that  $u \in C^{0,\mu}(\overline{B(x^0, \delta)}, \mathcal{R}^N)$ .

**Proof.** The proof is easy modification those in [5], Lemma 6.2.12. Our condition (1.5) substitute the condition that  $u \in L^\infty(\Omega, \mathcal{R}^N)$ , that is used in the relations (6.2.16)', (6.2.17) in [5].

We remark that the constants  $\varepsilon_0$ ,  $R_0$  depend on  $\Omega'$  and the parameters of system (1.1). Because using (2.8) it is matter of routine to find that

$$(2.13) \quad \begin{aligned} & \lim_{R \rightarrow 0^+} \left[ \int_{B(x^0, R)} |w_R(x) - (w_R)_{x^0, R} - \pi| dx \right. \\ & \quad \left. - \int_{B(x^0, R)} |(w_R(x) - (w_R)_{x^0, R} - \pi, \nu)| dx \right] \\ & = \lim_{R \rightarrow 0^+} \left[ \int_{B(x^0, R)} |u(x) - (u)_{x^0, R} - \pi| dx \right. \\ & \quad \left. - \int_{B(x^0, R)} |(u(x) - (u)_{x^0, R} - \pi, \nu)| dx \right] \end{aligned}$$

theorem 1.8 will be proved if we prove the following

**Lemma 2.14.** Let  $\Omega' \Subset \Omega$ . For every  $M > 0$  there exist a constants  $\varepsilon_1 > 0$ ,  $R_1 > 0$  such that if  $u \in W^{1,2}(\Omega, \mathcal{R}^N)$  is a weak solution of the system (1.1) with conditions (1.2) - (1.6) and if for some  $x^0 \in \Omega'$ ,  $R < \min(R_1, \text{dist}(x^0, \partial\Omega))$ ,  $\nu \in \mathcal{S}^{N-1}$ ,  $\pi \in \mathcal{R}^N$ ,  $|\pi| \leq M$  we have

$$(2.15) \quad \int_{B(x^0, R)} |u(x) - (u)_{x^0, R}|^2 dx \leq M^2,$$

$$(2.16) \quad \int_{B(x^0, R)} |w_R(x) - (w_R)_{x^0, R} - \pi| dx - \int_{B(x^0, R)} |(w_R(x) - (w_R)_{x^0, R} - \pi, \nu)| dx \leq \varepsilon_1,$$

then there exist  $\delta > 0$ ,  $\mu \in (0, 1 - n/p)$  such that  $u \in C^{0,\mu}(\overline{B(x^0, \delta)}, \mathcal{R}^N)$ .

**Proof.** Let  $M > 0$  and  $\Omega' \subset\subset \Omega$ . We shall reduce to Proposition 2.11. For that let  $\varepsilon_0 > 0$ ,  $R_0 > 0$  be the constants in Proposition 2.11.



Let  $\tau = \min\{1/2, (\varepsilon_0/4\sqrt{14}QM\omega_n)^{1/\alpha}\}$ , where  $\alpha, Q$  are the constant in Lemma 2.1,  $\omega_n = \text{meas}(B(0, 1))$ . We shall prove that for  $M > 0$  there exist constants  $\varepsilon_1$  and  $R_1 < R_0$  such that if  $u$  is a solution of (1.1) satisfying all conditions in Lemma 2.14, then

$$(2.17) \quad \int_{B(x^0, \tau R)} |w_{\tau R}(x) - (w_{\tau R})_{x^0, \tau R}|^2 dx \leq \varepsilon_0^2,$$

from which the conclusion follows using Proposition 2.11. Let us suppose that our assertion is false. Then it would exist

- (i) sequences  $\{x^k\}_1^\infty \subset \Omega', \{\pi_k\}_1^\infty \subset \mathcal{R}^N, |\pi_k| \leq M, \{\nu_k\}_1^\infty \subset \mathcal{S}^{N-1}$ ,
- (ii) two infinitesimal sequences  $\{\varepsilon_k\}_1^\infty, \{R_k\}_1^\infty$ ,
- (iii) a sequence  $\{u^k\}_1^\infty$  ( $u^k = w_{R_k}^k + v_{R_k}^k$  in  $B(x^k, R_k)$ ) of solutions of the system (1.1) such that

$$(2.17) \quad \int_{B(x^k, R_k)} |u^k(x) - (u^k)_{x^k, R_k}|^2 dx \leq M^2,$$

$$(2.18) \quad \int_{B(x^k, R_k)} |w_{R_k}^k(x) - (w_{R_k}^k)_{x^k, R_k} - \pi_k| dx \\ - \int_{B(x^k, R_k)} |(w_{R_k}^k(x) - (w_{R_k}^k)_{x^k, R_k} - \pi_k, \nu_k)| dx \leq \varepsilon_k,$$

but

$$(2.19) \quad \int_{B(x^k, \tau R_k)} |w_{\tau R_k}^k(x) - (w_{\tau R_k}^k)_{x^k, \tau R_k}|^2 dx > \varepsilon_0^2.$$

Put  $x = x^k + R_k y, y \in B(0, 1)$  and  $h_k(y) := u^k(x^k + R_k y), t_k(y) := w_{R_k}^k(x^k + R_k y), m_k(y) := v_{R_k}^k(x^k + R_k y)$ . Clearly  $h_k(y) = t_k(y) + m_k(y)$ . Using Lemma 2.6 we obtain from (1.1)

$$(2.20) \quad \int_{B(0,1)} A_{ij,k}^{r,s}(y, h_k(y)) D_j t_k^s(y) D_i \varphi^r(y) dy \\ + R_k \int_{B(0,1)} A_j^{r,s}(y, h_k(y)) D_j t_k^s(y) \varphi^r(y) dy = 0, \\ \varphi \in C_0^\infty(B(0, 1), \mathcal{R}^N),$$

where  $k = 1, 2, \dots$ ,  $A_{ij,k}^{r,s}(y, h_k(y)) = A_{ij}^{r,s}(x^k + R_k y, h_k(y))$ ,  $A_j^{r,s}(y, h_k(y)) = A_j^{r,s}(x^k + R_k y, h_k(y))$ . Using the transformation from above the inequalities (2.18) and (2.19) will obtain the following forms

$$(2.21) \quad \int_{B(0,1)} |t_k(y) - (t_k)_{0,1} - \pi_k| dy - \int_{B(0,1)} |t_k(y) - (t_k)_{0,1} - \pi_k, \nu_k| dy \leq \varepsilon_k,$$

where  $(t_k)_{0,1} = \int_{B(0,1)} t_k(y) dy$  and

$$(2.22) \quad \int_{B(0,\tau)} |t_{k\tau}(y) - (t_{k\tau})_{0,\tau}|^2 dy > \varepsilon_0^2,$$

where

$$t_{k\tau}(y) = w_{\tau R_k}^k(x^k + R_k y), \quad (t_{k\tau})_{0,\tau} = \int_{B(0,\tau)} t_{k\tau}(y) dy.$$

Let now  $k \rightarrow \infty$ . Passing possibly to a subsequence we may suppose that  $x^k \rightarrow x^0 \in \overline{\Omega}'$ ,  $\nu_k \rightarrow \nu \in \mathcal{S}^{N-1}$ ,  $\pi_k \rightarrow \pi$ ,  $|\pi| \leq M$ . Because we have (2.17), using Lemma 2.6 we obtain

$$\begin{aligned} & \int_{B(0,1)} |t_k(y) - (t_k)_{0,1}|^2 dy = R_k^{-n} \int_{B(x^k, R_k)} |w_{R_k}^k(x) - (w_{R_k}^k)_{x^k, R_k}|^2 dx \\ & \leq 2R_k^{-n} \left[ \int_{B(x^k, R_k)} |u^k(x) - (u^k)_{x^k, R_k}|^2 dx + \int_{B(x^k, R_k)} |v_{R_k}^k(y) - (v_{R_k}^k)_{x^k, R_k}|^2 dx \right] \\ & \leq \omega_n(2M^2 + c_5 R_k^{2(1-n/p)}), \quad (p > n). \end{aligned}$$

From above estimate it follows that

$$(2.23) \quad \int_{B(0,1)} |t_k(y) - (t_k)_{0,1}|^2 dy \leq M_1$$

and we may suppose that  $M_1 \leq 3\omega_n M^2$ . The estimate (2.23) implies that (passing possibly to a subsequence)  $(t_k - (t_k)_{0,1}) \rightharpoonup t$  weakly in  $L^2(B(0, 1), \mathcal{R}^N)$ . From Cacciopoli's inequality (2.10) we see that

$$(2.24) \quad \int_{B(0,\rho)} |Dt_k(y)|^2 dy \leq \frac{c_6}{(1-\rho)^2} \int_{B(0,1)} |t_k(y) - (t_k)_{0,1}|^2 dy, \quad 0 < \rho < 1.$$

From the last inequality it follows that

$$(t_k - (t_k)_{0,1}) \rightharpoonup t \text{ weakly in } W_{loc}^{1,2}(B(0, 1), \mathcal{R}^N),$$

$$(t_k - (t_k)_{0,1}) \rightarrow t \text{ strongly in } L^2_{loc}(B(0,1), \mathcal{R}^N).$$

Passing possibly to a subsequence we may suppose that

$$(t_k(y) - (t_k)_{0,1}) \rightarrow t(y) \text{ a.e. in } B(0, \rho), \quad (0 < \rho < 1).$$

From estimate (2.8) it follows that  $\|m_k\|_{L^2(B(0,1), \mathcal{R}^N)} \rightarrow 0$  as  $k \rightarrow \infty$  and we may suppose (as above)  $m_k(y) \rightarrow 0$  a.e. in  $B(0,1)$ .

In our consideration we must take into account two cases

- (a) the sequence  $\{(t_k)_{0,1}\}_1^\infty$  is bounded in  $\mathcal{R}^N$ , or  
 (b)  $|(t_k)_{0,1}| \rightarrow \infty$  as  $k \rightarrow \infty$ .

(a) In this case passing possibly to a subsequence we may suppose that  $(t_k)_{0,1} \rightarrow b \in \mathcal{R}^N$ . Then (1.2) and the above properties imply

$$\begin{aligned} A_{ij,k}^{rs}(y, h_k(y)) &= A_{ij}^{rs}(x^k + R_k y, t_k(y) - (t_k)_{0,1} + (t_k)_{0,1} + m_k(y)) \\ &\rightarrow A_{ij}^{rs}(x^0, t(y) + b) \text{ a.e. in } B(0, \rho) \text{ as } k \rightarrow \infty. \end{aligned}$$

Arguing as in [5] (chapt.6) we conclude that  $t$  satisfies

$$(2.25) \quad \int_{B(0,1)} A_{ij}^{rs}(x^0, b + t(y)) D_j t^s(y) D_i \varphi^r(y) dy = 0, \quad \varphi \in C_0^\infty(B(0,1), \mathcal{R}^N),$$

(b) In this case because (1.5) we have

$$A_{ij,k}^{rs}(y, h_k(y)) \rightarrow d_{ij}^{rs}(x^0) \text{ as } k \rightarrow \infty.$$

By the same argumentation as in the case (a) we find that  $t$  satisfies

$$(2.26) \quad \int_{B(0,1)} d_{ij}^{rs}(x^0) D_j t^s(y) D_i \varphi^r(y) dy = 0, \quad \varphi \in C_0^\infty(B(0,1), \mathcal{R}^N),$$

By trivial calculation we have

$$\begin{aligned} &\int_{B(0,\tau)} |t_{k\tau}(y) - (t_{k\tau})_{0,\tau}|^2 dy \\ &= \int_{B(0,\tau)} |t_k(y) + m_k(y) - m_{k\tau}(y) - (t_k)_{0,\tau} - (m_k)_{0,\tau} + (m_{k\tau})_{0,\tau}|^2 dy \\ &= \int_{B(0,\tau)} |t_k(y) - (t_k)_{0,\tau}|^2 dy + 2 \int_{B(0,\tau)} \langle t_k(y) - (t_k)_{0,\tau}, m_k(y) - (m_k)_{0,\tau} \rangle dy \\ &\quad - 2 \int_{B(0,\tau)} \langle t_k(y) - (t_k)_{0,\tau}, m_{k\tau}(y) - (m_{k\tau})_{0,\tau} \rangle dy \\ &\quad - 2 \int_{B(0,\tau)} \langle m_k(y) - (m_k)_{0,\tau}, m_{k\tau}(y) - (m_{k\tau})_{0,\tau} \rangle dy \\ &\quad + \int_{B(0,\tau)} |m_k(y) - (m_k)_{0,\tau}|^2 dy + \int_{B(0,\tau)} |m_{k\tau}(y) - (m_{k\tau})_{0,\tau}|^2 dy \end{aligned}$$

and

$$\begin{aligned} \int_{B(0,\tau)} |t_k(y) - (t_k)_{0,\tau}|^2 dy &= \int_{B(0,\tau)} |(t_k(y) - (t_k)_{0,1}) - (t_k(y) - (t_k)_{0,1})_{0,\tau}|^2 dy \\ &\rightarrow \int_{B(0,\tau)} |t(y) - (t)_{0,\tau}|^2 dy \text{ as } k \rightarrow \infty. \end{aligned}$$

This fact and estimations analogous to (2.8) imply

$$\int_{B(0,\tau)} |t_{k\tau}(y) - (t_{k\tau})_{0,\tau}|^2 dy \rightarrow \int_{B(0,\tau)} |t(y) - (t)_{0,\tau}|^2 dy, \text{ as } k \rightarrow \infty.$$

From the last information and (2.22) we have

$$(2.27) \quad \int_{B(0,\tau)} |t(y) - (t)_{0,\tau}|^2 dy \geq \varepsilon_0^2.$$

On the other hand we have for every  $0 < \rho < 1$  (using (2.21))

$$\begin{aligned} 0 &\leq \int_{B(0,\rho)} \left[ |t_k(y) - (t_k)_{0,1} - \pi_k| - |\langle t_k(y) - (t_k)_{0,1} - \pi_k, \nu_k \rangle| \right] dy \\ &\leq \rho^{-n} \int_{B(0,1)} \left[ |t_k(y) - (t_k)_{0,1} - \pi_k| - |\langle t_k(y) - (t_k)_{0,1} - \pi_k, \nu_k \rangle| \right] dy \\ &\leq \rho^{-n} \varepsilon_k \rightarrow 0, \text{ as } k \rightarrow \infty. \end{aligned}$$

and therefore

$$(2.28) \quad \int_{B(0,\rho)} \left[ |t(y) - \pi| - |\langle t(y) - \pi, \nu \rangle| \right] dy = 0, \quad 0 < \rho < 1,$$

so that  $t(y)$  lies on a straight line

$$(2.29) \quad t(y) = \pi_1 + g(y)\nu,$$

where  $\pi_1 = \pi - \langle \pi, \nu \rangle \nu$ ,  $|\pi_1|^2 \leq 4M^2$  and  $g(y) = \langle t(y), \nu \rangle$ . Introducing (2.29) in (2.25), we conclude that  $g$  is a solution of the elliptic equation

$$\int_{B(0,1)} a_{ij}(y) D_j g D_i \varphi dy = 0, \quad \varphi \in C_0^\infty(B(0,1)),$$

where  $a_{ij}(y) = d_{ij}^{rs}(x^0, b + \pi_1 + g(y)\nu)\nu^r\nu^s$  are bounded measurable coefficient satisfying (2.3) and (2.4). Introducing (2.29) in (2.26), we conclude that  $g$  is a solution of the elliptic equation

$$\int_{B(0,1)} a_{ij} D_j g D_i \varphi dy = 0, \quad \varphi \in C_0^\infty(B(0,1)),$$

where  $a_{ij} = d_{ij}^{rs}(x^0)\nu^r\nu^s$  are bounded constant coefficients with the same qualities as in previous situation.

In both cases (a) and (b) it follows from Lemma 2.1 that  $g$  is Hölder continuous in  $B(0, 1/2)$  and we have inequality (2.5). In particular

$$\begin{aligned} \int_{B(0,\tau)} |t(y) - (t)_{0,\tau}|^2 dy &= \int_{B(0,\tau)} |\pi_1 + \nu g(y) - \pi_1 - \nu(g)_{0,\tau}|^2 dy \\ &= \int_{B(0,\tau)} |g(y) - (g)_{0,\tau}|^2 dy \leq 14Q^2 M^2 (2\tau)^{2\alpha} \omega_n^2 \leq \frac{\varepsilon_0^2}{2} \end{aligned}$$

which contradicts (2.27).

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