

Bikkar S. Lalli

Oscillatory behaviour of nonlinear differential equations with deviating arguments

Archivum Mathematicum, Vol. 23 (1987), No. 1, 15--22

Persistent URL: <http://dml.cz/dmlcz/107273>

Terms of use:

© Masaryk University, 1987

Institute of Mathematics of the Academy of Sciences of the Czech Republic provides access to digitized documents strictly for personal use. Each copy of any part of this document must contain these *Terms of use*.



This paper has been digitized, optimized for electronic delivery and stamped with digital signature within the project *DML-CZ: The Czech Digital Mathematics Library* <http://project.dml.cz>

OSCILLATORY BEHAVIOUR OF NONLINEAR DIFFERENTIAL EQUATIONS WITH DEVIATING ARGUMENTS*

B. S. LALLI and S. R. GRACE

(Received September 30, 1985)

Abstract. Some oscillation criteria for $L_n x(t) = f(t, x[g_1(t)], \dots, x[g_m(t)])$, $n \geq 2$ are established. Here $L_0 x(t)$, $L_k x(t) = a_k(t) (L_{k-1} x(t))'$, $\left(\cdot = \frac{d}{dt} \right)$, $k = 1, 2, \dots, n$, $a_0 = a_n = 1$. The results generalize those of Werbowksi [Funkcial Ekvac, 25 (1982)]. However, they are not valid for the corresponding ordinary differential equations, which is due to the fact that deviations g_i can destroy oscillations, and also can generate oscillations depending on the "size" of the deviations.

Key words. Oscillatory solutions, differential equations, deviating arguments, non-oscillatory solutions.

1. INTRODUCTION

The purpose of this paper is to establish some results concerning the oscillatory behavior of the equation

$$(1) \quad L_n x(t) = f(t, x[g_1(t)], \dots, x[g_m(t)]), \quad n \geq 2,$$

where

$$L_0 x(t) = x(t), \quad L_k x(t) = a_k(t) (L_{k-1} x(t))', \quad \left(\cdot = \frac{d}{dt} \right), \\ k = 1, 2, \dots, n, \quad a_n = a_0 = 1.$$

Here we study the nonlinear oscillations generated by general deviating arguments g_k . These results are not valid for the corresponding ordinary differential equations. For examples we refer the reader to the papers of the present authors [1–3], Kitamura and Kusano [4], Naito [5], Philos [6], Sficas and Staikos [7, 8] and Werbowksi [9].

In what follows we are primarily interested in the situation in which equation (1) is oscillatory. We have been motivated by the observation that there are very few

* Presented to the Conference EQUADIFF 6, Brno, August 26–30, 1985.

criteria for equation (1), with a general operator L_n , to be oscillatory, though equation (1) and its nonlinear analogue have been the object of intensive investigation in recent years. Our main results in the form of oscillation criteria are given in Sec. 2. These results generalize oscillation theorems of Werbowski [9] for the particular equation

$$x^{(n)} = f(t, x[g_1(t)], \dots, x[g_m(t)]).$$

2. MAIN RESULTS

Consider the equation

$$(1) \quad L_n x(t) = f(t, x[g_1(t)], \dots, x[g_m(t)]),$$

where $L_0 x(t) = x(t)$, $L_k x(t) = a_k(t) (L_{k-1} x(t))'$, $k = 1, 2, \dots, n$, $a_0 = a_n = 1$, $a_i : R_+ = [0, \infty) \rightarrow (0, \infty)$ ($i = 1, 2, \dots, n - 1$), $g_k : R_+ \rightarrow R = (-\infty, \infty)$ with $g_k(t) \rightarrow \infty$ as $t \rightarrow \infty$ ($k = 1, 2, \dots, m$) and $f : R_+ \times R^m \rightarrow R$ as continuous. We assume that:

$$(2) \quad \int \frac{1}{a_i(s)} ds = \infty \quad (i = 1, 2, \dots, n - 1).$$

We further assume that there exist continuous functions $q : R_+ \rightarrow (0, \infty)$ and $F_k : R_+ \rightarrow R_+$ ($k = 1, 2, \dots, m$) such that

$$(3) \quad (-1)^n f(t, x_1, \dots, x_m) \operatorname{sgn} x_1 \geq q(t) \prod_{i=1}^m F_k(|x_k|) > 0$$

for $t \in R_+$ and $x_k \neq 0$ ($k = 1, 2, \dots, m$);

$$(4) \quad F_k \text{ (} k = 1, 2, \dots, m \text{) are non-decreasing on } R_+;$$

$$(5) \quad F_k(uv) \geq F_k(u) F_k(v) \quad (k = 1, 2, \dots, m) \quad \text{for } u, v \in R_+;$$

$$(6) \quad \int_0^\varepsilon \frac{du}{F(u)} < \infty \quad \text{for some } \varepsilon > 0, \quad \text{where } F(u) = \prod_{i=1}^m F_k(u).$$

The domain $D(L_n)$ for L_n is defined to be the set of all functions $x : R_+ \rightarrow R$ such that $L_j x(t)$, $0 \leq j \leq n$, exist and are continuous on R_+ . By a solution of equation (1) we mean a function $x \in D(L_n)$ which satisfies (1) on R_+ . A nontrivial solution of (1) is called oscillatory if the set of its zeros is unbounded and it is called nonoscillatory otherwise. The following three lemmas will be needed in the Sequel. The first lemma can be found in [6] and the other two appear in [2]

Lemma 1. *Suppose that condition (2) is satisfied. Let $y \in D(L_n)$ be a positive bounded function on the interval $[T, \infty)$, $T \geq t_0$ such that*

$$(-1)^n L_n y(t) \geq 0 \quad \text{for every } t > T.$$

Then

(α) $(-1)^i L_i y(t) > 0$ for every $t \geq T$ ($i = 1, 2, \dots, n - 1$),

(β) For every u and v with $v \geq u \geq T$,

$$y(u) \geq (-1)^{n-1} \left[\int_{u=s_0}^v \frac{1}{a_1(s_1)} \int_{s_1}^v \frac{1}{a_2(s_2)} \dots \int_{s_{n-2}}^v \frac{1}{a_{n-1}(s_{n-1})} ds_{n-1} \dots ds_1 \right] L_{n-1} y(v).$$

Lemma 2. Let condition (2) hold and let $x \in D(L_n)$. If $x(t) L_n x(t)$ is of constant sign and not identically zero for all large t , then there exist $t_x \geq t_0$ and an integer l , $0 \leq l \leq n$ with $n + l$ even for $x(t) L_n x(t) \geq 0$ or $n + l$ odd for $x(t) L_n x(t) \leq 0$ and such that for every $t \geq t_x$

$$l > 0 \text{ implies } x(t) L_k x(t) > 0 \quad (k = 0, 1, \dots, l - 1)$$

and

$$l \leq n - 1 \text{ implies } (-1)^{l+k} x(t) L_k x(t) > 0 \quad (k = l, l + 1, \dots, n - 1).$$

In the following lemma we let

$$\mu_i(t) = \max_{0 \leq t_0 \leq s \leq t} a_i(s) \quad (i = 1, \dots, n - 1)$$

and

(7)
$$\int \frac{1}{\mu_i(s)} ds = \infty,$$

Lemma 3. Let $x \in D(L_n)$ be a positive function on $[t_0, \infty)$. If $\lim_{t \rightarrow \infty} x(t) \neq 0$, and $L_{n-1} x(t) L_n x(t) < 0$ for $t \geq t_1 \geq t_0$, t_1 sufficiently large and $L_n x(t)$ not identically zero for all large t , then there exist a $T \geq t_1$ and a positive constant M such that

(i) $|L_{n-1} x(t)| > 0$

and

(ii)
$$x(t) \geq M \left[\int_T^t \frac{1}{\mu_1(s_1)} \int_T^{s_1} \dots \int_T^{s_{n-2}} \frac{1}{\mu_{n-1}(s_{n-1})} ds_{n-1} \dots ds_1 \right] |L_{n-1} x(t)|.$$

For convenience we use the following notations in the sequel. For any $T \geq t_0 \geq 0$ and all $t \geq T$ we let

$$D_k = \{t \in R_+ : g_k(t) < t\}, \quad D = D_1 \cap D_2 \cap \dots \cap D_m, \quad D_T = D \cap [T, \infty).$$

$$w(t, T) = \int_T^t \frac{1}{\mu_1(s_1)} \int_T^{s_1} \dots \int_T^{s_{n-2}} \frac{1}{\mu_{n-1}(s_{n-1})} ds_{n-1} \dots ds_1$$

and

$$\alpha(u, v) = \int_{u=s_0}^v \frac{1}{a_1(s_1)} \int_{s_1}^v \dots \int_{s_{n-2}}^v \frac{1}{a_{n-1}(s_{n-1})} ds_{n-1} \dots ds_1, \quad \text{for } v \geq u \geq T.$$

Theorem 1. Let conditions (2)–(6) hold. If

$$(8) \quad \int_D q(t) \prod_{k=1}^m F_k(\alpha[g_k(t), t]) dt = \infty,$$

then every bounded solution of (1) is oscillatory.

Proof. Let $x(t)$ be a bounded nonoscillatory solution of (1) and let $x(t) \neq 0$ for $t \geq t_0$. Then there exists a $t_1 \geq t_0$ such that $x[g_k(t)] \neq 0$ ($k = 1, \dots, m$) for $t \geq t_1$. Thus, by (1) and (3) we have $(-1)^n x(t) L_n x(t) > 0$ for $t \geq t_1$. Then from Lemma 1 it follows that

$$(-1)^i x(t) L_i x(t) > 0 \quad (i = 0, 1, \dots, n)$$

for $t \geq t_2 \geq t_1$ and

$$|x(t)| \geq \alpha(t, s) |L_{n-1}x(s)|, \quad \text{for } s \geq t \geq t_2.$$

Therefore for $t \in D_T$, $T \geq t_2$, we obtain

$$(g) \quad |x[g_k(t)]| \geq \alpha[g_k(t), t] |L_{n-1}x(t)| \quad (k = 1, 2, \dots, m).$$

From (1), in view of (3)–(5) and (9) we get for $t \in D_T$

$$\begin{aligned} |L_n x(t)| &\geq q(t) \prod_{k=1}^m F_k(|x[g_k(t)]|) \geq q(t) \prod_{k=1}^m F_k(\alpha[g_k(t), t] |L_{n-1}x(t)|) \geq \\ &\geq q(t) \prod_{k=1}^m F_k(|L_{n-1}x(t)|) \prod_{k=1}^m F_k(\alpha[g_k(t), t]). \end{aligned}$$

Thus

$$\begin{aligned} \int_{D_T} q(t) \prod_{k=1}^m F_k(\alpha[g_k(t), t]) dt &\leq \int_{D_T} \frac{|L_n x(t)|}{F(|L_{n-1}x(t)|)} dt \leq \\ &\leq \int_T^\infty \frac{|L_n x(t)|}{F(|L_{n-1}x(t)|)} dt \leq \int_0^\varepsilon \frac{dy}{F(y)} < \infty, \end{aligned}$$

where $\varepsilon = |L_{n-1}x(T)|$, which contradicts (8).

Similarly we can prove the following theorem.

Theorem 2. Let condition (2) hold, and assume that there exists continuous functions $q_k : R_+ \rightarrow (0, \infty)$ and $F_k : R_+ \rightarrow R_+$ ($k = 1, 2, \dots, m$) such that

$$(10) \quad (-1)^n f(t, x_1, \dots, x_m) \operatorname{sgn} x_1 \geq \sum_{k=1}^m q_k(t) F_k(|x_k|) > 0$$

for $t \in R_+$ and $x_k \neq 0$ ($k = 1, \dots, m$). If for some i_0 ($1 \leq i_0 \leq m$) the following conditions hold:

$$(11) \quad F_{i_0} \text{ is non-decreasing on } R_+;$$

$$(12) \quad F_{i_0}(uv) \geq F_{i_0}(u) F_{i_0}(v) \quad \text{for } u, v \in R_+;$$

$$(13) \quad \int_0^\varepsilon \frac{du}{F_{i_0}(u)} < \infty \quad \text{for some } \varepsilon > 0;$$

$$(14) \quad \int_{D_{i_0}} q_{i_0}(t) F_{i_0}(w[g_{i_0}(t), t]) dt = \infty,$$

then all bounded solutions of (1) are oscillatory.

Remarks

1. If $a_i = 1$ ($i = 1, \dots, n - 1$), then our Theorems 1 and 2 and Theorems 1 and 2 in [9] are the same.

2. As in [3], if

$$(*) \quad \lim_{t \rightarrow \infty} \frac{1}{\alpha_1(t)} \sum_{i=0}^k c_i \alpha_i(t) > 0, \quad \alpha_0(t) = 1,$$

for every choice of the constants c ; with $c_k > 0$ ($k = 1, 2, \dots, n - 1$), where

$$\alpha_1(t) = \int_c^t \frac{1}{a_1(s)} ds, \quad \alpha_2(t) = \int_c^t \frac{1}{a_1(s_1)} \int_c^{s_1} \frac{1}{a_2(s_2)} ds_2 ds_1,$$

and

$$\alpha_k(t) = \int_c^t \frac{1}{a_1(s_1)} \int_c^{s_1} \dots \int_c^{s_{k-1}} \frac{1}{a_k(s_k)} ds_k \dots ds_1 \quad (k = 3, \dots, n - 1),$$

$t \geq c \geq 0$, then the conclusion of both Theorem 1 and 2 can be replaced by the statement that „every solution $x(t)$ of (1) with the property that $\frac{x(t)}{\alpha_1(t)} \rightarrow 0$ as $t \rightarrow \infty$ is oscillatory“. Thus using (*) we can enlarge the class of oscillatory solutions of (1). In case $a_i = 1$ ($i = 1, \dots, n - 1$), the condition (*) is obviously verified and thus the class of bounded solutions of (1) can be replaced by the class of solutions x of (1) such that $\frac{x(t)}{t} \rightarrow 0$ as $t \rightarrow \infty$. This fact improves Theorems 1 and 2 in [9].

3. If $n = 1$, then condition (5) can be disregarded, and hence Theorems 1 and 2 are extensions of some of the results in [4].

For illustration we consider the following example:

Example. Consider the equation

$$(15) \quad (\sqrt{t}x)' = x^{2/3} \left[t - \frac{1}{t} \right] \operatorname{sgn} x \left[t - \frac{1}{t} \right], \quad t > 1.$$

From Theorem 1, it follows that all bounded solutions of (15) are oscillatory, since $\int_1^\infty q(s) F(\alpha[g(s), s]) ds = \int_1^\infty \left[2\sqrt{s} \left(1 - \left[1 - \frac{1}{s^2} \right]^{1/2} \right) \right]^{2/3} ds \geq \int_1^\infty \left(\frac{2\sqrt{s}}{s^2} \right)^{2/3} ds = \infty$

We note that Theorems 1 and 2 in [9] are not applicable since $a_1(t) \neq 1$. Also Theorem 3 in [6] is not applicable, since condition (C_3) in [6] fails (i.e.)

$$\int_1^\infty \frac{g'(s)}{a_1[g(s)]} \int_{g(s)}^s q(s_1) ds_1 ds = \int_1^\infty [s^{-7/2} + s^{-3/2}] \left[1 - \frac{1}{s^2} \right]^{-1/2} ds < \infty.$$

Theorem 3. *Let the assumptions of Theorem 1 hold. In addition, let for T sufficiently large*

$$(16) \quad \int q(s) \prod_{k=1}^m F_k(w[h_k(s), T]) ds = \infty,$$

where

$$h_k(t) = \begin{cases} g_k(t) & \text{for } n = 2, \\ \min(t, g_k(t)) & \text{for } n > 2. \end{cases}$$

Then for n odd, all solutions of (1) are oscillatory, while for n even, every solution x of (1) is either oscillatory or $\lim_{t \rightarrow \infty} |L_i x(t)| = \infty$ ($i = 0, 1, \dots, n-1$) monotonically.

Proof. Suppose that equation (1) has a nonoscillatory solution $x(t) \neq 0$ for $t \geq t_0$. Since $\lim_{t \rightarrow \infty} g_k(t) = \infty$ ($k = 1, \dots, m$), there exists a $t_1 \geq t_0$ such that $x[g_k(t)] \neq 0$ for $t \geq t_1$. Then it follows from (1) and (3) that $(-1)^n x(t) L_n x(t) > 0$ for $t \geq t_1$. And from Lemma 2 it follows, that there exist an even integer $l \in \{0, 1, \dots, n\}$ and a number $t_2 \in [t_1, \infty)$ such that

$$(17) \quad \begin{aligned} x(t) L_i x(t) &> 0 & (i = 0, 1, \dots, l), \\ (-1)^{l+i} x(t) L_i x(t) &> 0 & (i = l+1, \dots, n), \end{aligned}$$

for $t \geq t_2$. From Theorem 1 it follows that the case $l = 0$ is impossible. Therefore (17) hold for $l \in \{2, \dots, n\}$. Let n be odd. Then $n > 2$ and $l \in \{2, \dots, n-1\}$. We shall prove that the case $l \in \{2, \dots, n-1\}$ is also impossible. From Lemma 3 for $l \in \{2, \dots, n-1\}$ we have

$$|x(t)| \geq Mw[t, t_3] |L_{n-1} x(t)|, \quad (M > 0),$$

for all large $t \geq t_3 \geq t_2$. Since $|x(t)|$ is increasing and $|L_{n-1} x(t)|$ is decreasing, from the above inequality we obtain

$$(18) \quad \begin{aligned} |x[g_k(t)]| &\geq |x[h_k(t)]| \geq Mw[h_k(t), t_3] |L_{n-1} x[h_k(t)]| \geq \\ &\geq Mw[h_k(t), t_3] |L_{n-1} x(t)| \quad (k = 1, 2, \dots, m), \end{aligned}$$

for $t \geq T \geq t_3$.

Then from (1), (3)–(5) and (18) we get for $t \geq T$

$$\begin{aligned} |L_n x(t)| &\geq q(t) \prod_{k=1}^m F_k(Mw[h_k(t), t_3] |L_{n-1} x(t)|) \geq \\ &\geq q(t) F(M |L_{n-1} x(t)|) \prod_{k=1}^m F_k(w[h_k(t), t_3]), \end{aligned}$$

which gives

$$q(t) \prod_{k=1}^m F_k(w[h_k(t), t_3]) \leq \frac{|L_n x(t)|}{F(M |L_{n-1} x(t)|)}.$$

Integrating the last inequality from T to ∞ we have

$$\int_T^\infty q(s) \prod_{k=1}^m F_k(w[h_k(s), t_3]) ds \leq \frac{1}{M} \int_0^\varepsilon \frac{du}{F(u)} < \infty, \quad \varepsilon = M |L_{n-1}x(T)|,$$

which contradicts assumption (16). Therefore for n odd, x is oscillatory. Let n be even. Then the inequalities (17) hold for an even integer $l \in \{2, \dots, n\}$. As in the proof of first part, we can prove that the case $l \in \{2, \dots, n - 2\}$ is impossible. Therefore (17) holds for $l = n$, i.e.

$$(19) \quad x(t) L_i x(t) > 0 \quad (i = 0, 1, \dots, n),$$

for $t \geq t_2$. We shall prove that $\lim_{t \rightarrow \infty} |L_i x(t)| = \infty$ ($i = 0, 1, \dots, n - 1$). From (19), by using an argument similar to the one used in [2, Theorem 1] it follows that there exist a $T \geq t_2$ and a positive constant c such that

$$(20) \quad |x[g_k(t)]| \geq c \int_T^{g_k(t)} \frac{1}{a_1(s_1)} \int_T^{s_1} \dots \int_T^{s_{n-2}} \frac{1}{a_{n-1}(s_{n-1})} ds_{n-1} \dots ds_1 \geq cw[g_k(t), T], \quad (k = 1, 2, \dots, m).$$

Integrating (1) from T to t , we obtain

$$\begin{aligned} |L_{n-1}x(t)| &= |L_{n-1}x(T)| + \int_T^t |f(s, x[g_1(s)], \dots, x[g_m(s)])| ds \geq \\ &\geq F(c) \int_T^t q(s) \prod_{k=1}^m w[g_k(s), T] ds. \end{aligned}$$

From the above inequality and (16) we derive $\lim_{t \rightarrow \infty} |L_i x(t)| = \infty$ ($i = 0, 1, \dots, n - 1$) monotonically.

In exactly the same way we can prove the following theorem.

Theorem 4. *Suppose that the assumptions of Theorem 2 are satisfied in $n \geq 2$. In addition let for T sufficiently large*

$$\int q_{i_0}(s) F_{i_0}(w[h_{i_0}(s), T]) ds = \infty,$$

where h_{i_0} is as in Theorem 3. Then the conclusion of Theorem 3 holds.

Remark. If $a_i = 1$ ($i = 1, \dots, n - 1$), then our Theorems 3 and 4 and Theorems 3 and 4 of Werbowski [9] are the same.

For illustration we consider the following example:

Example. The equation

$$(21) \quad (\sqrt{i}(\sqrt{i}(\sqrt{ix})))' = 3 \cdot (2)^{-1/3} t^{-7/6} x^{1/3} [t/2], \quad t > 0,$$

has a nonoscillatory solution $x(t) = t^2$ satisfying $|L_i x(t)| \rightarrow \infty$ as $t \rightarrow \infty$ ($i = 0, 1, 2, 3$). i.e. the conclusion of Theorem 3 holds. We may note that Theorem 3 in [9] is not applicable to (21) since $a_i(t) \neq 1$ ($i = 1, 2, 3$).

Remark. The analogous results as these obtained in this paper for the case of superlinear equations seem impossible. To see this we consider the equation

$$(22) \quad (e^{-t}x)' = 2x^3 \left[\frac{2}{3}t \right].$$

It is easy to check that all conditions of Theorem 1 are satisfied (condition (6) is replaced by $\int_t^\infty \frac{du}{F(u)} < \infty$). However (22) has a bounded nonoscillatory solution $x = e^{-t}$.

REFERENCES

- [1] S. R. Grace and B. S. Lalli, *A note on Ladas' paper: Oscillatory effect of retarded actions*, J. Math. Anal. Appl., 88 (1982), 257–264.
- [2] S. R. Grace and B. S. Lalli, *Oscillatory and asymptotic behavior of solutions of differential equations with deviating arguments*, J. Math. Anal. Appl., 104 (1984), 79–94.
- [3] S. R. Grace and B. S. Lalli, *On oscillation of solutions of n^{th} order delay differential equations*, J. Math. Anal. Appl., 91 (1983), 328–339.
- [4] Y. Kitamura and T. Kusano, *Oscillation of first order nonlinear differential equations with deviating arguments*, Proc. Amer. Math. Soc., 78 (1980), 64–68.
- [5] M. Naito, *Oscillations of differential inequalities with retarded arguments*, Hiroshima Math. J., 5 (1975), 187–192.
- [6] Ch. G. Philos, *Bounded oscillations generated by retardations for differential equations of arbitrary order*, Utilitas Math., 15 (1979), 161–182.
- [7] Y. G. Sficas and V. A. Staikos, *Oscillations of differential equations with deviating arguments* Funkcial Ekvac., 19 (1976), 35–43.
- [8] Y. G. Sficas and V. A. Staikos, *The effect of retarded actions on nonlinear oscillations*, Proc. Amer. Math. Soc., 46 (1974), 259–264.
- [9] J. Werbowski, *Oscillations of nonlinear differential equations caused by deviating arguments*, Funkcial Ekvac., 25 (1982), 295–301.

S. R. Grace
Faculty of Engineering
Cairo University
Egypt

B. S. Lalli
Department of Mathematics
University of Saskatchewan
Saskatoon, Saskatchewan
S7N 0W0 Canada