Commentationes Mathematicae Universitatis Carolinae

Jaroslav Haslinger

A note on a dual finite element method

Commentationes Mathematicae Universitatis Carolinae, Vol. 17 (1976), No. 4, 665--673

Persistent URL: http://dml.cz/dmlcz/105726

Terms of use:

© Charles University in Prague, Faculty of Mathematics and Physics, 1976

Institute of Mathematics of the Academy of Sciences of the Czech Republic provides access to digitized documents strictly for personal use. Each copy of any part of this document must contain these *Terms of use*.



This paper has been digitized, optimized for electronic delivery and stamped with digital signature within the project *DML-CZ: The Czech Digital Mathematics Library* http://project.dml.cz

COMMENTATIONES MATHEMATICAE UNIVERSITATIS CAROLINAE

17.4 (1976)

A NOTE ON A DUAL FINITE ELEMENT METHOD

J. HASLINGER, Praha

Abstract: In [9],[10] the construction of suitable subspaces of linear trial vector-functions, admissible for the dual variational formulation was given as well as the proof of the rate of approximation in C-norm. In the present paper we prove the rate of approximation in L^2 -norm. This fact permits us to obtain the same results as in [9],[10] under the weaker assumptions on the regularity of the solution.

Key words: Finite elements, equilibrium model.

AMS: 65N3Q Ref. Z.: 8.33

A number of articles has been written on the dual finite element method (see [1] - [10] etc.). In [9],[10] the authors presented some results, using the simpliest finite element "equilibrium model", applying the piecewise linear polynomials to the solution of a mixed boundary value problem for one second order elliptic equation without the absolute term. The rate of convergence $O(h^2)$ was proved, provided the exact solution is sufficiently smooth. Let us introduce some notations. Let Ω be a bounded domain in R_2 . By $H^k(\Omega)(k\geq 0)$ integer) we denote the set of real functions, which are square-integrable in Ω together with their generalized derivatives up to the order k.

We write $H^0(\Omega) = L^2(\Omega) \stackrel{\rightarrow}{H}^k(\Omega) = H^k(\Omega) \times H^k(\Omega)$

with the norm

$$\|\vec{v}\|_{k,\Omega} = (\|\mathbf{v}_1\|_{k,\Omega}^2 + \|\mathbf{v}_2\|_{k,\Omega}^2)^{1/2},$$

$$(\vec{v} = (\mathbf{v}_1, \mathbf{v}_2)),$$

where

$$\|\mathbf{v}_{\mathbf{i}}\|_{\mathbf{k},\Omega} = \left(\int_{0}^{\infty} \sum_{|\alpha| \leq 2\kappa} |\mathbf{D}^{\alpha}\mathbf{v}_{\mathbf{i}}|^{2} d\mathbf{x}\right)^{1/2}.$$

Ву

$$|\mathbf{v}|_{\mathbf{j},\Omega} = (\int_{\Omega} \sum_{|\alpha|=\hat{\mathbf{j}}} |\mathbf{D}^{\alpha}\mathbf{v}|^2 d\mathbf{x})^{1/2}$$

we denote the j-th seminorm in $H^{j}(\Omega)$.

 $C^k(\overline{\Omega})$ denote the space of continuous functions, the derivatives of which up to the order k are continuous and continuously extensible onto $\overline{\Omega}$ $(C^0(\overline{\Omega}) = C(\overline{\Omega}))$. We write $\overline{C}^k(\overline{\Omega}) = C^k(\overline{\Omega}) \times C^k(\overline{\Omega})$ with the norm

$$\|\vec{v}\|_{C^{k}(\overline{\Omega})} = \max_{i=1,2} \|v_i\|_{C^{k}(\overline{\Omega})}$$
 and

$$\|\mathbf{A}^{\mathbf{i}}\|_{\mathbf{C}_{\mathbf{K}}^{(\underline{U})}} = \max_{\|\mathbf{x}\| \in \mathcal{Y}} \|\mathbf{D}_{\mathbf{x}} \mathbf{A}^{\mathbf{i}}(\mathbf{x})\|$$

At first, we recall main results from [9]. Let K be a nom-degenerate triangle with vertices a_1, a_2, a_3 and set $a_4 = a_1$. For $\vec{\forall} \in \vec{H}^1(K)$ we define the outward flux

$$T_{\overrightarrow{\mathbf{v}}} = \overrightarrow{\mathbf{v}}|_{\mathbf{a}_{1} \mathbf{a}_{1+1}} \cdot \overrightarrow{\mathbf{n}}^{(1)} = \overrightarrow{\mathbf{v}}_{1} \mathbf{n}_{1}^{(1)} + \overleftarrow{\mathbf{v}}_{2} \mathbf{n}_{2}^{(1)},$$

where $\overrightarrow{n}^{(i)} = (n_1^{(i)}, n_2^{(i)}) \in \mathbb{R}_2$ is the outward unit normal to ∂K on $a_i a_{i+1}$, \overline{v}_i are the traces of v_i on $a_i a_{i+1}$. By $P_k(M)$ $(k \ge 0$ integer) we denote the set of all polynomials of the order at most k, defined on the set $M \subseteq \mathbb{R}_2$. Let

 λ (i), λ (i) be the basic linear functions of the side $a_i a_{i+1}$, i.e.

-
$$\lambda_{k}^{(i)} \in P_{1}(a_{i}a_{i+1}), k = 1, 2;$$

$$- \lambda_{1}^{(i)}(a_{i}) = 1, \quad \lambda_{1}^{(i)}(a_{i+1}) = 0;$$
$$- \lambda_{1}^{(i)}(a_{i}) = 0, \quad \lambda_{2}^{(i)}(a_{i+1}) = 1$$

and let us denote
$$\int_{a_i a_{i+1}}^{a_i a_i} uv ds = [u, v]_i$$
, $u, v \in L^2(a_i a_{i+1})$.

In [9] we proved

Theorem 1. Let $\vec{u} \in \vec{H}^1(K)$. Then the equations

(j)
$$[T_{i}\vec{x}, \lambda_{k}^{(i)}]_{i} = \alpha_{i} [\lambda_{1}^{(i)}, \lambda_{k}^{(i)}]_{i} + \beta_{i} [\lambda_{2}^{(i)}, \lambda_{k}^{(i)}]_{i}$$
 (k = 1,2)

(jj)
$$\iint \vec{u}(a_i) \cdot \vec{n}^{(i)} = \infty_i, \iint \vec{u}(a_{i+1}) \cdot \vec{n}^{(i)} = \beta_i$$

define an operator
$$\Pi \in \mathcal{L}(\overrightarrow{\mathbb{H}}^{1}(K), (P_{1}(K))^{2}) \cap \mathcal{L}(\overrightarrow{C}(K), (P_{1}(K))^{2}).$$

In [9] properties of Π were studied. Let us denote $\mathfrak{M}(K) = \{ \overrightarrow{v} = (v_1, v_2), v_j \in P_1(K), j = 1, 2; \text{ div } \overrightarrow{v} = 0 \}$

 $U(K) = \{ \overrightarrow{\nabla} \in \overrightarrow{H}^{1}(K), \text{ div } \overrightarrow{\nabla} = 0 \}$

We proved:

(1)
$$\Pi \in \mathcal{L}(U(K), \mathcal{M}(K))$$

^{1) £ (}X,Y) denotes the space of linear bounded mappings of X into Y.

(3)
$$\|\vec{\nabla} - \vec{\nabla}\|_{\overrightarrow{C}(\mathbb{K})} \leq 4(1 + \frac{6\sqrt{2}}{\sin \alpha}) h^2 \|\vec{\nabla}\|_{\overrightarrow{C}^2(\mathbb{K})}$$

 $\forall \vec{\nabla} \in \overrightarrow{C}^2(\mathbb{K}).$

where h = diam K and ∞ is the minimal interior angle of K (analogously in R_n for n > 2, see [10]).

Our aim is to prove the following Theorem 2. Let $\overrightarrow{v} \in \overrightarrow{H}^{j}(K)$, j = 1,2. Then

(4)
$$\|\vec{\mathbf{v}} - \Pi \vec{\mathbf{v}}\|_{0,K} \leq c \cdot \frac{\hbar^{j}}{\sin \alpha} |\vec{\mathbf{v}}|_{j,K}$$

where h = diam K, ∞ is the minimal interior angle of K and c is an absolute constant.

Before the proof we introduce some notations and we recall the well-known facts. Let \hat{K} be the triangle with the following vertices: $Q_1 = (0,0)$, $Q_2 = (1,0)$, $Q_3 = (0,1)$. One can easily show that there exist the unique affine mapping $F: R_2 \longrightarrow R_2$, $F(\hat{x}) = B\hat{x} + b$, $B \in \mathcal{L}(R_2, R_2)$ regular, $b \in R_2$ such that $F(\hat{K}) = K$. Let h be the diameter of K and G the diameter of a circle inscribed in K (\hat{h} , \hat{G} have the same meaning for \hat{K}). In [11] was proved that

(5)
$$\|\mathbf{B}\| \leq \frac{h}{\hat{e}}$$
, $\|\mathbf{B}^{-1}\| \leq \frac{h}{\varrho}$

and

(5')
$$\frac{1}{2 \operatorname{tg} \frac{\infty}{2}} \leq \frac{h}{9} \leq \frac{2}{\sin \infty}$$
 (∞ is the same as in th.2).

Lemma 1. Let Π be defined through (j),(jj). Then

(6)
$$\| \prod \vec{\mathbf{v}} \|_{0,K} \leq \frac{\hat{\mathbf{c}}}{\sin \alpha} [\det \mathbf{E}]^{1/2} \| \hat{\vec{\mathbf{v}}} \|_{1,\hat{K}} \quad \forall \vec{\mathbf{v}} \in \hat{\mathbf{H}}^{1}(K),$$

where $\overrightarrow{\nabla} = \overrightarrow{\nabla} \circ F = (\overrightarrow{v_1} \circ F, \overrightarrow{v_2} \circ F)$, \widehat{c} is an absolute constant. <u>Proof</u>: using Fubini's theorem:

$$\| \prod \overrightarrow{\nabla} \|_{o,K} = |\det B|^{1/2} \| \widehat{\prod \overrightarrow{\nabla}} \|_{o,\widehat{K}} \le 2 \det |B|^{1/2}$$

$$(\operatorname{mes} \widehat{K})^{1/2} \|\widehat{\Pi} \overrightarrow{\nabla}\|_{\widehat{\mathcal{C}}(\widehat{K})} = \sqrt{2} |\det B|^{1/2} \|\Pi \overrightarrow{\nabla}\|_{\widehat{\mathcal{C}}(K)}.$$

Let $a_i a_{i+1} = F(I)$, where I is a side of \hat{K} , which is determined by (0,0),(1,0) and let $F|_{I}$ be the restriction of F on I. Then it holds:

$$\widehat{\mathbf{T}_{\mathbf{i}}\mathbf{v}} = \widehat{\overline{\mathbf{v}}}_{\mathbf{1}}\mathbf{n}_{\mathbf{1}}^{(\mathbf{i})} + \widehat{\overline{\mathbf{v}}}_{\mathbf{2}}\mathbf{n}_{\mathbf{2}}^{(\mathbf{i})} \qquad (\widehat{\overline{\mathbf{v}}}_{\mathbf{i}} = \overline{\mathbf{v}}_{\mathbf{i}} \circ \mathbf{F} \mid \mathbf{I}).$$

Hence

$$\begin{split} &\left|\left[\mathbf{T}_{i}\overrightarrow{\mathbf{v}},\ \lambda_{k}^{(i)}\right]_{i}\right| = \left|\int_{a_{i}a_{i+1}}\mathbf{T}_{i}\overrightarrow{\mathbf{v}}\ \lambda_{k}^{(i)}\ \mathrm{d}\mathbf{s}\right| = \mathbf{q}_{i}\left|\int_{0}^{1}\widehat{\mathbf{T}_{i}}\overrightarrow{\mathbf{v}}\ \hat{\lambda}_{k}^{(i)}\mathrm{d}\hat{\mathbf{s}}\right| \leq \\ & \leq \mathbf{q}_{i}\left(\int_{0}^{1}|\widehat{\mathbf{T}_{i}}\overrightarrow{\mathbf{v}}|^{2}\mathrm{d}\hat{\mathbf{s}}\right)^{1/2} \leq \hat{\beta}\ \mathbf{q}_{i}\ \|\widehat{\mathbf{v}}\|_{1,\hat{K}}, \end{split}$$

where q_i is the length of $a_i a_{i+1}$, $\hat{\lambda}_k^{(i)} = \lambda_k^{(i)}$. $\mathbb{F}|_{\mathbb{I}}$ and $\hat{\beta}$ is the norm of the mapping $\gamma: \overline{\mathbb{H}}^1(\mathbb{K}) \longrightarrow \overline{\mathbb{L}}^2(\partial \mathbb{K})$ such that $\gamma \overrightarrow{v} = (\overline{v}_1, \overline{v}_2)$ (\overline{v}_i are the traces of v_i on $\partial \mathbb{K}$). A direct calculation yields that

$$\det A^{(i)} = \frac{1}{12} q_i^2,$$

where $A^{(i)}$ is the matrix of the system (j). Using Cramer's rule we obtain

$$|\alpha_{\mathbf{i}}| \leq \hat{\mathbf{c}} \|\hat{\overrightarrow{\mathbf{v}}}\|_{1,\hat{\mathbf{K}}}, \quad |\beta_{\mathbf{i}}| \leq \hat{\mathbf{c}} \|\hat{\overrightarrow{\mathbf{v}}}\|_{1,\hat{\mathbf{K}}}.$$

From (jj) and Cramer's rule it follows e.g. for $\prod \vec{v}(a_2) = (w_1(a_2), w_2(a_2))$:

$$|\mathbf{w}_{1}(\mathbf{a}_{2})| = |\det \begin{pmatrix} \beta_{1}, \mathbf{n}_{2}^{(1)} \\ \alpha_{2}, \mathbf{n}_{2}^{(2)} \end{pmatrix}, \det (\vec{\mathbf{n}}^{(1)}, \vec{\mathbf{n}}^{(2)}) \leq$$

$$\leq \hat{c} \frac{1}{\sin \alpha} \|\hat{\vec{v}}\|_{1,\hat{K}}$$

because the det $(\vec{n}^{(1)}, \vec{n}^{(2)})$ is equal to the sinus of the angle between $\vec{n}^{(1)}, \vec{n}^{(2)}$. Similar estimates hold for the remaining values of \vec{w} at the vertices. The assertion of our lemma now follows from the fact that $(\vec{n}, \vec{v}) \in (P_1(K))^2$.

Proof of Theorem 2: for j = 2 (analogously for j = 1). It holds:

(7)
$$\|\vec{\mathbf{v}} - \Pi\vec{\mathbf{v}}\|_{0,K} = \sup_{\vec{\mathbf{v}} \neq 0} \frac{(\vec{\mathbf{v}} - \Pi\vec{\mathbf{v}}, \vec{\mathbf{v}})}{\mathbf{v}}$$
.

Let us denote

(8)
$$f(\vec{v}) = (\vec{v} - \vec{v}, \vec{g})_{o, \vec{K}} = |\det B| (\hat{\vec{v}} - \vec{D}, \hat{\vec{g}})_{o, \hat{\vec{K}}} = |\det B| \hat{\vec{v}} =$$

where $\hat{\vec{v}} = (\hat{v}_1, \hat{v}_2)$, $\hat{v}_i = v_i \circ F$. Let us examine the functional \hat{f} . From (2) and (8):

(9)
$$\hat{\mathbf{f}}(\hat{\vec{\mathbf{v}}}) = 0 \quad \forall \hat{\vec{\mathbf{v}}} \in (P_1(K))^2$$

Now

$$\begin{aligned} (10) \quad |\hat{f}(\hat{\vec{\tau}})| & \leq \|\hat{\vec{g}}\|_{o,\hat{K}} \|\hat{\vec{\tau}} - \widehat{\Pi \vec{v}}\|_{o,\hat{K}} \leq \|\hat{\vec{g}}\|_{o,\hat{K}} (\|\hat{\vec{v}}\|_{1,\hat{K}} + \|\widehat{\Pi \vec{v}}\|_{o,\hat{K}}). \end{aligned}$$

Using (6) we estimate $\|\widehat{\nabla}\|_{0,\hat{K}}$:

$$\|\widehat{\nabla v}\|_{0,\hat{K}} = |\det B|^{-1/2} \|\widehat{\nabla v}\|_{0,K} \leq \frac{\hat{c}}{\sin\alpha} \|\widehat{\hat{v}}\|_{1,\hat{K}}.$$

From this and (10):

$$(11) ||\widehat{f}(\widehat{\psi})| \leq ||\widehat{g}||_{0,\widehat{K}} (1 + \frac{\widehat{c}}{\sin \alpha})||\widehat{\psi}||_{1,\widehat{K}} \leq$$

$$\leq |\det B|^{-1/2}||\widehat{g}||_{0,K} (1 + \frac{\widehat{c}}{\sin \alpha})||\widehat{\psi}||_{2,\widehat{K}}.$$

Using (11) and Bramble-Hilbert lemma (see [11],[12]) we obtain:

$$(12) \quad |\widehat{f}(\widehat{\overrightarrow{v}})| \leq c \left| \det B \right|^{-1/2} \|\widehat{\overrightarrow{s}}\|_{0,K} \left(1 + \frac{\widehat{c}}{\sin \infty}\right) |\widehat{\overrightarrow{v}}|_{2,\widehat{K}}$$

where c is an absolute constant. Using the well-known fact that (see [11])

$$|\hat{\vec{v}}|_{2,\hat{K}} \leq ||B||^2 |\det B|^{-1/2} |\vec{v}|_{2,K}$$

and (8),(12):

$$|f(\vec{\mathbf{v}})| \leq c(1 + \frac{\hat{c}}{\sin \alpha}) \|\mathbf{B}\|^2 \|\vec{\mathbf{g}}\|_{0,K} |\vec{\mathbf{v}}|_{2,K}$$

From this, (5), (5') and (7) we obtain the assertion of our theorem.

For details how to use Theorem 2, see [9],[10].

References

[1] B. Fraeijs de VEUBEKE: Displacement and equilibrium models in the finite element method, Stress Analysis, ed. by O.C. Zienkiewicz and G. Holister, J. Wiley, 1965, 145-197.

- [2] B. Fræeijs de VEUBEKE, O.C. ZIENKIEWICZ: Strain energy bounds in finite-element analysis by slab analogies, J. Strain Analysis 2(1967), 265-271.
- [3] V.B.Jr. WATWOOD, B.J. HARTZ: An equilibrium stress field model for finite element solution of two-dimensional elastostatic problems, Int.J. Solids Structures 4(1968), 857-873.
- [4] B. Fraeijs de VEUBEKE, M. HOGGE: Dual analysis for heat conduction problems by finite elements, Int. J. Numer. Meth. Eng.(1972), 65-82.
- [5] J.P. AUBIN, H.G. BURCHARD: Some aspects of the method of the hypercicle applied to elliptic variational problems, Numer. Sol. Part. Dif. Eqs. II, Synspade (1970), 1-67.
- [6] J. VACEK: Dual variational principles for an elliptic partial differential equation, Apl. mat. 18 (1976), 5-27.
- [7] G. GRENACHER: A posteriori error estimates for elliptic partial differential equations. Inst. Fluid Dynamics and Appl. Math., Univ. Maryland, TN-EN-T 43, July 1972.
- [8] J.M. THOMAS: Méthode des éléments finis équilibre pour les problèmes elliptiques du 2-ème ordre. To appear.
- [9] J. HASLINGER; I. HLAVAČEK: Convergence of a finite element method based on the dual variational formulation, Apl. mat. 21(1976), 43-65.
- [10] J. HASLINGER; I. HLAVAČEK: Convergence of a dual finite element method in R_n, Comment. Math. Univ. Carolinae 16(1975), 369-486.
- [11] P.G. CIARLET, P.A. RAVIART: General Lagrange and Hermite interpolation in Rⁿ with applications to finite element method, Arch. Rat. Mech. Anal. 46(1972),177-199.

[12] J.H. BRAMBLE, M. ZLAMAL: Triangular elements in the finite element method, Math. Comp. 24(1970), 809-820.

Matematicko-fyzikální fakulta Karlova universita Malostranské nám.25,11000 Praha 1 Československo

(Oblatum 19.5.1976)