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ON REAL SUBMANIFOLDS of \mathbb{C}^2 and \mathbb{C}^3

Alois ŠVEC, Praha

(Preliminary communication)

In what follows, I determine the structure of some real submanifolds of \mathbb{C}^2 and \mathbb{C}^3 which are invariant under a transitive group of holomorphic mappings. The full exposition is to be published in Czech.Math.J. The results were obtained during my stay at the universities of Delhi, Chandigarh and Bombay and at the Tata Inst. of Fundamental Research in Bombay under the Czechoslovak-Indian Cultural Exchange Programme.

1. In \mathbb{C}^m , consider the coordinates (z_1, \dots, z_m) , $z_i = x_i + iy_i$. Let $\iota: \mathbb{C}^m \rightarrow \mathbb{R}^{2m}$ be the usual identification $\iota(z_1, \dots, z_m) = (x_1, y_1, \dots, x_m, y_m)$. In \mathbb{R}^{2m} , we have the well known induced endomorphism $J: \mathbb{R}^{2m} \rightarrow \mathbb{R}^{2m}$, $J^2 = -id.$, given by $J \frac{\partial}{\partial x^i} = \frac{\partial}{\partial y^i}$, $J \frac{\partial}{\partial y^i} = -\frac{\partial}{\partial x^i}$. Denote by Γ the pseudogroup of all local holomorphic diffeomorphisms in \mathbb{C}^m (or $\iota(\Gamma)$ in \mathbb{R}^{2m} resp.), let $\Gamma_0 \subset \Gamma$ be the sub-pseudogroup of maps $x'_i = f_i(x_1, \dots, x_m)$ satisfying

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$$\left| \det \frac{\partial(x'_1, \dots, x'_m)}{\partial(x_1, \dots, x_m)} \right| = 1 .$$

Let $M^m \subset \mathbb{C}^n$ be a real submanifold, let us write again M^m instead of $\iota(M^m)$. Consider a point $p \in M^m$, the tangent space $T_p \equiv T_p(M^m)$, and define τ_p as $T_p \cap J T_p$. Let $v_0 \in \tau_p$. In a neighbourhood $\mathcal{O} \subset M^m$ of p , consider a vector field v such that $v_p = v_0$ and $v_q \in \tau_q$ for each $q \in \mathcal{O}$. The map $L_p^{(1)} : \tau_p \rightarrow T_p / \tau_p$ be given by $L_p^{(1)}(v_0) = \pi_1([v, Jv]_p)$, where $\pi_1 : T_p \rightarrow T_p / \tau_p$ is the projection; $L_p^{(1)}(v_0)$ depends on v_0 only. Let $\mathcal{O}_p \subset T_p$ be the linear hull of the set $\pi_1^{-1}(L_p^{(1)}(\tau_p))$. The map $L_p^{(2)} : \tau_p \rightarrow T_p / \mathcal{O}_p$ be defined by $L_p^{(2)}(v_0) = \pi_2([v, [v, Jv]]_p)$, $\pi_2 : T_p \rightarrow T_p / \mathcal{O}_p$ being the projection; $L_p^{(2)}$ depends only on v_0 as well. $L_p^{(1)}$ and $L_p^{(2)}$ are the so-called Levi maps.

Write $G(M^m) = \{g \in \Gamma \mid g(M^m) = M^m\}$ and $G_p(M^m) = G(M^m) \cap \Gamma_p$.

2. Consider the case $n = 3$, $m = 4$ and the pseudo-group Γ . Suppose $\dim \tau_p = 2$, $L_p^{(1)} \neq 0$, $L_p^{(2)} \neq 0$ at each point $p \in M^4$. If $G(M^4)$ is transitive on M^4 , $G(M^4)$ is a Lie group and $\dim G(M^4) \leq 5$. Let us consider a manifold M^4 with $\dim G(M^4) = 5$ and the manifold N^4 given by

$$(1) \quad \bar{x}_2 - x_2 = i(\bar{x}_1 - x_1)^2, \quad \bar{x}_3 - x_3 = (\bar{x}_1 - x_1)^3.$$

If $p \in M^4$, $q \in N^4$ are arbitrary points, there is a neighbourhood $\mathcal{O} \subset M^4$ of p and a $\gamma \in \Gamma$ such that $\gamma(\mathcal{O}) \subset N^4$, $\gamma(p) = q$, i.e., M^4 and N^4 are locally Γ -equivalent. The group $G(N^4)$ is

$$(2) \quad \begin{aligned} x'_1 &= ax_1 + b + ci, \\ x'_2 &= 4acx_1 + a^2x_2 + d + 2c^2i, \\ x'_3 &= -12ac^2x_1 - 6a^2cx_2 + a^3x_3 + f - 4c^3i \end{aligned}$$

where $a, b, c, d, f \in \mathbb{R}$.

3. Consider the case $n = 2, m = 3$ and the pseudogroup Γ_p . Then $\dim \tau_p = 2$; suppose $L_p^{(1)} \neq 0$ at each point $p \in M^3$. If $G_p(M^3)$ is transitive on M^3 , then it is a Lie group with $\dim G_p(M^3) \leq 4$. Consider the manifolds N_κ^3, N_R^3, N_0^3 given successively by

$$(3) \quad x_1 \bar{x}_1 + x_2 \bar{x}_2 = \kappa^2 \quad (\kappa > 0),$$

$$(4) \quad x_1 \bar{x}_2 + \bar{x}_1 x_2 = 2R \quad (R > 0),$$

$$(5) \quad i(x_2 - \bar{x}_2) = (x_1 - \bar{x}_1)^2.$$

Let $\dim G_p(M^3) = 4$. Then there is exactly one manifold among the manifolds N_κ^3, N_R^3, N_0^3 - denote it by N^3 - with the following property:

Choose $p \in M^3, q \in N^3$, then there is a neighbourhood $\mathcal{O} \subset M^3$ of p and a $\gamma \in \Gamma_p$ such that $\gamma(p) = q$,

$\gamma(O) \subset N^3$. The groups $G_b(N_k^3)$, $G_b(N_R^3)$ and $G_b(N_0^3)$ are given by

$$(6) \quad \begin{aligned} x'_1 &= \alpha x_1 - \beta x_2, \\ x'_2 &= e^{ia} (\bar{\beta} x_1 + \bar{\alpha} x_2), \end{aligned}$$

where $\alpha, \beta \in \mathbb{C}$, $\alpha \bar{\alpha} + \beta \bar{\beta} = 1$, $a \in \mathbb{R}$;

$$(7) \quad \begin{aligned} x'_1 &= e^{if} (ax_1 + ibx_2), \\ x'_2 &= e^{if} (icx_1 + dx_2), \end{aligned}$$

where $a, b, c, d, f \in \mathbb{R}$, $ad + bc = 1$;

$$(8) \quad \begin{aligned} x'_1 &= e^{ia} x_1 + b + ci, \\ x'_2 &= 4e^{ia} cx_1 + i(1 - e^{2ia})x_1^2 + x_2 + d + 2c^2i, \end{aligned}$$

where $a, b, c, d \in \mathbb{R}$.

If $\dim G_b(M^3) = 3$ and $\dim [g, g] \leq 2$, g being the Lie algebra of $G_b(M^3)$, then M^3 is locally Γ_b -equivalent (in the above sense) with one of the manifolds \tilde{N}_k^3 given by

$$(9) \quad (x_1 - \bar{x}_1)^2 + k(x_2 - \bar{x}_2)^2 = 1, \quad 0 \neq k \in \mathbb{R}.$$

$G_b(\tilde{N}_k^3)$ is given by

$$(10) \quad \begin{aligned} x'_1 &= ax_1 - kbx_2 + c, \\ x'_2 &= bx_1 + ax_2 + d, \end{aligned}$$

where $a, b, c, d \in \mathbb{R}$. $a^2 + kb^2 = 1$.

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