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# ON A METHOD OF TWOSIDED EIGENVALUE ESTIMATES FOR ELLIPTIC EQUATIONS OF THE FORM $A u-\lambda B u=0$ 

Karel Rektorys and Zdeněk Vospěl

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The well-known Collatz method developed originally for the case of ordinary differential equations was shown to be applicable - at least theoretically - to the case of sufficiently general elliptic equations of the form $A u-\lambda B u=0$ by K. Rektorys in his book [1]. From the point of view of its practical use, the main difficulty consists in the fact that in the case of partial differential equations the corresponding boundary value problems are to be solved only approximately, as a rule, so that the estimates of eigenvalues - derived on base of exact solutions of these problems - are no more valid, in general. The aim of this paper is to show how to ensure practical applicability of the method also in this case. At the same time, some results of their own interest are derived.

## 1. INTRODUCTION. ASSUMPTIONS. SURVEY OF RESULTS

There is a lot of methods yielding twosided eigenvalue estimates in partial differential equations. However, on the whole, they are rather labourious or applicable only to special cases of operators.

A relatively simple method suitable especially for linear ordinary differential equations of the form

$$
\begin{equation*}
A u-\lambda B u=0 \tag{1.1}
\end{equation*}
$$

with homogeneous boundary conditions not involving the parameter $\lambda$, and for the first ( = least) eigenvalue $\lambda_{1}$, was suggested by L. Collatz many years ago. It consists in the following:

Let $A$, or $B$ be linear ordinary differential operators, of order $2 k$, or $2 l$, respectively, $k>l$, having some properties of symmetry and positiveness on their domains of definition $D_{A}$, or $D_{B}$. (These domains consist of sufficiently smooth functions satisfying
some of the given boundary conditions. We do not go into details here; see [2].) Let $f_{0} \in D_{B}, f_{1} \in D_{A}$ be two (nonzero) functions satisfying

$$
\begin{equation*}
A f_{1}=B f_{0} \tag{1.2}
\end{equation*}
$$

and denote

$$
\begin{equation*}
a_{0}=\left(B f_{0}, f_{0}\right), \quad a_{1}=\left(B f_{0}, f_{1}\right)=\left(A f_{1}, f_{1}\right), \quad a_{2}=\left(B f_{1}, f_{1}\right) \tag{1.3}
\end{equation*}
$$

(the so-called Schwarz constants) and

$$
\begin{equation*}
x_{1}=a_{0} / a_{1}, \quad x_{2}=a_{1} \mid a_{2} \tag{1.4}
\end{equation*}
$$

(the so-called Schwarz quotients). From the properties of the operators $A$ and $B$ it follows, first, that $a_{0}, a_{1}, a_{2}$ are positive, and then almost immediately that

$$
\begin{equation*}
x_{1} \geqq x_{2} \geqq \lambda_{1} . \tag{1.5}
\end{equation*}
$$

Now, provided the first eigenvalue $\lambda_{1}$ is simple and $l_{2}$ is a lower bound for the second eigenvalue $\lambda_{2}$, greater than $\chi_{2}$ (thus

$$
\begin{equation*}
\left.x_{2}<l_{2} \leqq \lambda_{2}\right), \tag{1.6}
\end{equation*}
$$

the following twosided eigenvalue estimate is derived by Collatz:

$$
\begin{equation*}
x_{2}-\frac{x_{1}-x_{2}}{\frac{l_{2}}{x_{2}}-1} \leqq \lambda_{1} \leqq \varkappa_{2} . \tag{1.7}
\end{equation*}
$$

(An appropriate value for $l_{2}$ can be obtained using a propre comparison theorem, see Example 4.1.) Then he improves the accuracy of the estimate (1.7) in the following sense: Starting with the function $f_{0}$ again, he constructs the functions $f_{1}, f_{2}, \ldots, f_{k} \in$ $\in D_{A}$ satisfying

$$
\begin{gather*}
A f_{1}=B f_{0} \\
A f_{2}=B f_{1}  \tag{1.8}\\
\ldots \cdots \cdots \\
A f_{k}=B f_{k-1}
\end{gather*}
$$

He than proves that for the corresponding Schwarz quotients we have

$$
\begin{equation*}
x_{1} \geqq x_{2} \geqq \ldots \geqq x_{k} \geqq \lambda_{1} \tag{1.9}
\end{equation*}
$$

and - in consequence of the last relation (1.8) - that

$$
\begin{equation*}
x_{k+1}-\frac{x_{k}-x_{k+1}}{\frac{l_{2}}{x_{k+1}}-1} \geqq \lambda_{1} \leqq x_{k+1} . \tag{1.10}
\end{equation*}
$$

On many examples he demonstrates, in [2], the efficiency of his method. Then he
extends the obtained results to some simple types of partial differential equations. (Cf. also Collatz [3].)

In the monography [1], K. Rektorys extends the Collatz method to the case of sufficiently general elliptic equations of the form

$$
\begin{equation*}
A u-\lambda B u=0 \tag{1.11}
\end{equation*}
$$

(with linear boundary conditions, not involving $\lambda$ ), under rather natural assumptions whích will be kept throughout the whole paper:

Let $\Omega$ be a bounded region in $E_{N}$ with a Lipschitzian boundary $\dot{\Omega}$. Let $A$ and $B$ be liner differential operators of order $2 k, 2 l$, respectively,

$$
\begin{equation*}
k>l . \tag{1.12}
\end{equation*}
$$

Denote
(1.13) $V_{A}=\left\{v ; v \in W_{2}^{(k)}(\Omega), v\right.$ satisfies, in the sense of traces, the given (homogeneous) boundary conditions which are stable for the operator $A\}$,
$V_{B}=\left\{v ; v \in W_{2}^{(l)}(\Omega), v\right.$ satisfies, in the sense of traces, the given (homogeneous) boundary conditions which are stable for the operator $B\}$.

In the weak formulation the considered eigenvalue problem consists in finding all values of $\lambda$ such that to each of them there exists a nonzero function $u \in V_{A}$ satisfying

$$
\begin{equation*}
((v, u))_{A}-\lambda((v, u))_{B}=0 \quad \forall v \in V_{A} . \tag{1.15}
\end{equation*}
$$

Here $((v, u))_{A},((v, u))_{B}$ are bilinear forms corresponding, in the usual sense, to the operators $A$ and $B$, respectively. (Thus we come formally to (1.15) when multiplying (1.11) by $v \in V_{A}$, integrate over $\Omega$ and use the Green theorem in the familiar way.) Throughout this paper, we assume that the forms $((v, u))_{A},((v, u))_{B}$ are symmetric on $V_{A}, V_{B}$, respectively, i.e. that

$$
\begin{array}{ll}
((v, u))_{A}=((u, v))_{A} & \forall u, v \in V_{A}, \\
((v, u))_{B}=((u, v))_{B} & \forall u, v \in V_{B} \tag{1.17}
\end{array}
$$

(and, consequently, $\forall u, v \in V_{A}$ ) and that they are on $V_{A}, V_{B}$, bounded and $V_{A^{-}}, V_{B^{-}}$ elliptic, i.e. that there exist such positive constants $K_{1}, K_{2}, \alpha, \beta$ (not depending on $u, v$ ) that

$$
\begin{array}{ll}
\left|((v, u))_{A}\right| \leqq K_{1}\|v\|_{V_{A}}\|u\|_{V_{A}} & \forall u, v \in V_{A}, \\
\left|((v, u))_{B}\right| \leqq K_{2}\|v\|_{V_{B}}\|u\|_{V_{B}} \quad \forall u, v \in V_{B}, \tag{1.19}
\end{array}
$$

$$
\begin{array}{ll}
((v, v))_{A} \geqq \alpha\|v\|_{V_{A}}^{2} & \forall v \in V_{A}, \\
((v, v))_{B} \geqq \beta\|v\|_{V_{B}}^{2} & \forall v \in V_{B} . \tag{1.21}
\end{array}
$$

(Here, $\|v\|_{V_{A}}$, or $\|v\|_{V_{B}}$ means $\|v\|_{W_{2}(k) \Omega}$, or $\|v\|_{W_{2}()_{\Omega}}$ for $v \in V_{A}$, or $v \in V_{B}$, respectively.)

When considering the eigenvalue problem for the equation

$$
\begin{equation*}
A u-\lambda u=0 \tag{1.22}
\end{equation*}
$$

(with corresponding boundary conditions) we put, of course, $B=I$ and

$$
\begin{equation*}
((v, u))_{B}=(v, u) \tag{1.23}
\end{equation*}
$$

In the quoted Rektorys monography [1], a thorough treatment of the eigenvalue problem (1.15) is given in Chap. 39: First it is shown that to every $g \in V_{B}$ there exists precisely one function $u \in V_{A}$ such that we have

$$
\begin{equation*}
((v, u))_{A}=((v, g))_{B} \quad \forall v \in V_{A} . \tag{1.24}
\end{equation*}
$$

At the same time

$$
\begin{equation*}
\|u\|_{V_{A}} \leqq c\|g\|_{V_{B}}, \tag{1.25}
\end{equation*}
$$

where $c$ is independent of $v$ and $g$. Consequently

$$
\begin{equation*}
u=T g, \tag{1.26}
\end{equation*}
$$

where the operator $T: V_{B} \rightarrow V_{A}$ is linear (as a consequence of linearity of the operators $A, B$ ) and bounded (according to (1.25)). Because of the Sobolev immersion theorem, this operator can be shown to be completely continuous as an operator from $V_{A}$ into $V_{A}$.

Denote by $\bar{V}_{A}$ the space, elements of which consist of elements of the space $V_{A}$ and in which the scalar product is defined by

$$
\begin{equation*}
(v, u)_{\nabla_{A}}=((v, u))_{A} . \tag{1.27}
\end{equation*}
$$

(Properties of the scalar product are ensured by the properties of the form $((v, u))_{A}$.) Let us note, at this place, that the metrics in $\bar{V}_{A}$ and $V_{A}$ are equivalent because of (1.18) and (1.20). Analogously, let $\bar{V}_{B}$ be the space of all elements from $V_{B}$, with the scalar product

$$
\begin{equation*}
(v, u)_{V_{B}}=((v, u))_{B} . \tag{1.28}
\end{equation*}
$$

The metrics in $\bar{V}_{B}$ and $V_{B}$ are equivalent as well.
In [1] it is shown that the operator $T$ considered as an operator from $\bar{V}_{A}$ into $\bar{V}_{A}$, thus

$$
\begin{equation*}
T: \bar{V}_{A} \rightarrow \bar{V}_{A}, \tag{1.29}
\end{equation*}
$$

is a positive selfadjoint completely continuous operator.
The eigenvalue problem (1.15) can then be written in the following equivalent form:

$$
\begin{equation*}
u-\lambda T u=0 \quad\left(u \in \bar{V}_{A}, u \neq 0\right) \tag{1.30}
\end{equation*}
$$

The operator $T$ having the just mentioned properties, we have especially ([1], Chap. 39):

The eigenvalue problem (1.15) has a countable set of (positive) eigenvalues

$$
\begin{equation*}
\lambda_{1} \leqq \lambda_{2} \leqq \lambda_{3} \leqq \ldots, \quad \lim _{n \rightarrow \infty} \lambda_{n}=+\infty \tag{1.31}
\end{equation*}
$$

The corresponding system

$$
\begin{equation*}
\left.v_{1}, v_{2}, v_{3}, \ldots{ }^{1}\right) \tag{1.32}
\end{equation*}
$$

of orthonormalized (in $\bar{V}_{A}$ ) eigenfunctions is complete in $\bar{V}_{A}$ (and because of equivalence of the metrics in $\bar{V}_{A}$ and $V_{A}$, also in $V_{A}$ ).

The system of functions

$$
\begin{equation*}
\varphi_{n}=v_{n} \sqrt{ } \lambda_{n}, \quad n=1,2, \ldots \tag{1.33}
\end{equation*}
$$

is then orthonormal and complete in the space $\bar{V}_{B}$ (and complete in $V_{B}$ ).
All being prepared in Chap. 39, Rektorys then gets, in Chap. 40, twosided estimates of the Collatz type for the elliptic equation (1.11):

Let $f_{0} \in V_{B}$ be a given nonzero function and let $f_{1} \in V_{A}$ satisfies

$$
\begin{equation*}
\left(\left(v, f_{1}\right)\right)_{A}=\left(\left(v, f_{0}\right)\right)_{B} \quad \forall v \in V_{A} \tag{1.34}
\end{equation*}
$$

(According to (1.26) it means that

$$
\begin{equation*}
f_{1}=T f_{0} \tag{1.35}
\end{equation*}
$$

If all the given data are sufficiently smooth, then $f_{0}$ and $f_{1}$ satisfy

$$
\begin{equation*}
A f_{1}=B f_{0} \tag{1.36}
\end{equation*}
$$

cf. (1.2).) Denote

$$
\begin{align*}
& a_{0}=\left(\left(f_{0}, f_{0}\right)\right)_{B}  \tag{1.37}\\
& a_{1}=\left(\left(f_{1}, f_{0}\right)\right)_{B}=\left(\left(f_{1}, f_{1}\right)\right)_{A}  \tag{1.38}\\
& a_{2}=\left(\left(f_{1}, f_{1}\right)\right)_{B}  \tag{1.39}\\
& x_{1}=a_{0} / a_{1}, \quad x_{2}=a_{1} / a_{2} . \tag{1.40}
\end{align*}
$$

First, Rektorys shows, in a simple way, that

$$
\begin{gather*}
a_{0}>0, \quad a_{1}>0, \quad a_{2}>0  \tag{1.41}\\
x_{1} \geqq \chi_{2} \geqq \lambda_{1} \tag{1.42}
\end{gather*}
$$

Then, using the so-called Temple theorem (see [3]), he proves: If the first eigenvalue

[^0]$\lambda_{1}$ of the problem (1.15) is simple and if $l_{2}$ is such a lower estimate of the second eigenvalue $\lambda_{2}$ that $l_{2}>x_{2}$ (thus
\[

$$
\begin{equation*}
\left.x_{2}<l_{2} \leqq \lambda_{2}\right), \tag{1.43}
\end{equation*}
$$

\]

then

$$
\begin{equation*}
x_{2}-\frac{x_{1}-x_{2}}{\frac{l_{2}}{x_{2}}-1} \leqq \lambda_{1} \leqq x_{2} . \tag{1.44}
\end{equation*}
$$

In this way, the estimate of the Collatz type is obtained for the elliptic eigenvalue problem (1.15).

As mentioned above, when applying this result practically, the following difficulty arises: While in the case of ordinary differential equations one often succeeds in finding an exact solution of the problem (1.2) (or exact solutions of the problems (1.8)), in the case of partial differential equations the analogous problems should be solved approximately, as a rule, so that estimates of the type (1.44) with $x_{1}, x_{2}$ replaced by the numbers $\tilde{x}_{1}, \tilde{x}_{2}$ constructed with the help of approximate solutions, are no more valid, in general.

To get a better insight into this problematics and to be able to answer the question of applicability of estimates of the form (1.44) in this case, we choose here an other approach than that used in [1], not applying the Temple theorem, but using suitable Fourier expansions. In this way, we come, in Chap. 2, to the following results (p. 224):

Let the first eigenvalue $\lambda_{1}$ of the problem (1.15) be simple. Let $f_{0} \in V_{B}$ be not orthogonal, in $V_{B}$, to the corresponding first eigenfunction $v_{1}{ }^{2}$ ) (or, what is the same, to $\varphi_{1}$, cf. (1.33)). Solve, successively, the following boundary value problems (cf. (1.8)):

$$
\begin{align*}
& \left(\left(v, f_{1}\right)\right)_{A}=\left(\left(v, f_{0}\right)\right)_{B}, \\
& \left(\left(v, f_{2}\right)\right)_{A}=\left(\left(v, f_{1}\right)\right)_{B},  \tag{1.45}\\
& \ldots \ldots \ldots \ldots \ldots \ldots \\
& \left(\left(v, f_{k}\right)\right)_{A}=\left(\left(v, f_{k-1}\right)\right)_{B},
\end{align*}
$$

$\forall v \in V_{A}$.
Denote

$$
\begin{align*}
a_{2 n} & =\left(\left(f_{n}, f_{n}\right)\right)_{B}>0,  \tag{1.46}\\
a_{2 n+1} & =\left(\left(f_{n+1}, f_{n}\right)\right)_{B}=\left(\left(f_{n+1}, f_{n+1}\right)\right)_{A}>0,
\end{align*}
$$

$n=0,1,2, \ldots$,

$$
\begin{equation*}
\chi_{k}=a_{k-1} / a_{k}, \quad k=1,2,3, \ldots \tag{1.47}
\end{equation*}
$$

[^1]Then, first,

$$
\begin{gather*}
x_{1} \geqq x_{2} \geqq x_{3} \geqq \ldots \geqq \lambda_{1},  \tag{1.48}\\
\lim _{k \rightarrow \infty} x_{k}=\lambda_{1} \tag{1.49}
\end{gather*}
$$

(Theorem 2.1, p. 224.) Thus, $\lambda_{1}$ can be approximated, with an arbitrary accuracy, by $\chi_{k}$, if $k$ is sufficiently large (the problems (1.45) being solved exactly).

Further, this method yields, in a simple way (without using the Temple theorem) estimates of the form (1.7),

$$
\begin{equation*}
x_{k+1}-\frac{x_{k}-x_{k+1}}{\frac{l_{2}}{x_{k+1}}-1} \leqq \lambda_{1} \leqq x_{k+1}, \tag{1.50}
\end{equation*}
$$

where $l_{2}>x_{k+1}$ is a lower estimate of the second eigenvalue $\lambda_{2}$. (See the same Theorem 2.1.) Especially, for $k=1$, we get (1.44).

In Chap. 3, the case of approximate solution of (1.45) is considered. To fix the idea, the Ritz method is chosen. (However, any method, having similar properties, can be applied. Especially, all the main results of this paper remain valid for the finite element method.) Let $\tilde{f}_{1}$ be the approximate solution of the problem

$$
\begin{equation*}
((v, u))_{A}=\left(\left(v, f_{0}\right)\right)_{B} \quad \forall v \in V_{A}, \tag{1.51}
\end{equation*}
$$

obtained by this method (using $N$ terms of the base), further let $\tilde{f}_{2}$ be the approximate solution of

$$
\begin{equation*}
((v, u))_{A}=\left(\left(v, \tilde{f}_{1}\right)\right)_{B} \quad \forall v \in V_{A}, \tag{1.52}
\end{equation*}
$$

etc. Denoting

$$
\begin{aligned}
\tilde{a}_{2 n} & =\left(\left(\tilde{f}_{n}, \tilde{f}_{n}\right)\right)_{B}, \\
\tilde{a}_{2 n+1} & =\left(\left(\tilde{f}_{n}, \tilde{f}_{n+1}\right)\right)_{B}
\end{aligned}
$$

with $\tilde{f}_{0}=f_{0}$,

$$
\begin{equation*}
\tilde{x}_{k}=\tilde{a}_{k-1} / \tilde{a}_{k}, \tag{1.53}
\end{equation*}
$$

we prove (Theorem 3.1, p. 234): If $\lambda_{1}$ is simple and if $f_{0}$ is not orthogonal, in $\bar{V}_{B}$, to the first eigenfunction $\varphi_{1}$, then

$$
\begin{gather*}
\tilde{\varkappa}_{1} \geqq \tilde{\varkappa}_{2} \geqq \tilde{\varkappa}_{3} \geqq \ldots \geqq \lambda_{1},  \tag{1.54}\\
\lim _{\substack{k \rightarrow \infty \\
N \rightarrow \infty}} \tilde{\chi}_{k}=\lambda_{1} . \tag{1.55}
\end{gather*}
$$

Further it is shown how to modify the estimate (1.50), or (1.44) for this case (see (3.45), or (3.73) with Remark 3.4).

Although this new estimate is not too complicated, a modification of the present method is given in Chap. 4, enabling to find relatively very simple and accurate estimates (as demonstrated on a numerical example). The idea is the following: Let us perform some steps in solving the problems (1.51), (1.52), .... To fix the idea, let $\tilde{f}_{1}$ and $\tilde{f}_{2}$ be found. (The number of steps depends on the required accuracy; an arbitrary accuracy can be obtained by (1.55).) Having $\tilde{f}_{2}$, it may happen that we succeed in finding such a function $\hat{f}_{1}$ that the integral identity

$$
\begin{equation*}
\left(\left(v, \tilde{f}_{2}\right)\right)_{A}=\left(\left(v, \hat{f}_{i}\right)\right)_{B} \quad \forall v \in V_{A} \tag{1.56}
\end{equation*}
$$

is satisfied exactly. (This happens very often, because it is much easier, practically, to find $\hat{f}_{1}$ if $\tilde{f}_{2}$ is known, than conversely, since the order of the operator $B$ is smaller than that of the operator $A$; if, especially, the eigenvalue problem $A u-\lambda u=0$ is solved, so that $B$ is the identity operator, and if the coefficients of the operator $A$ as well as the function $\tilde{f}_{2}$ are sufficiently smooth, then $\hat{f}_{1}=A \tilde{f}_{2}$. Thus, in this case, the function $\hat{f}_{1}$ is obtained by operations of the differentiation only.) Now, because (1.56) is fulfilled exactly, the twosided estimate (1.50) is valid with $\chi^{\prime}$ s constructed from the functions $\hat{f}_{1}, \tilde{f}_{2}$ instead of $f_{1}, f_{2}$. In this way a very simple method of twosided eigenvalue estimates is received, giving, moreover, relatively very exact estimates (cf. Example 4.1, p. 237).

## 2. CONVERGENCE OF THE SEQUENCE $\varkappa_{k}$. ESTIMATES OF THE COLLATZ TYPE

Let the forms $((v, u))_{A},((v, u))_{B}$ satisfy assumptions (1.16)-'(1.21) concerning their symmetry, boundedness and $V_{A^{-}}$or $V_{B}$-ellipticity. Let

$$
\begin{equation*}
v_{1}, v_{2}, v_{3}, \ldots \tag{2.1}
\end{equation*}
$$

be the complete set of eigenfunctions of the problem (1.15), orthonormal in $\bar{V}_{A}$ (on $\bar{V}_{A}$ see (1.27), p. 214), i.e.

$$
\left(\left(v_{i}, v_{j}\right)\right)_{A}=\left\{\begin{array}{lll}
0 & \text { if } \quad i \neq j  \tag{2.2}\\
1 & \text { if } \quad i=j
\end{array}\right.
$$

Then (cf. (1.33))

$$
\begin{equation*}
\varphi_{1}=v_{1} \sqrt{ } \lambda_{1}, \quad \varphi_{2}=v_{2} \sqrt{ } \lambda_{2}, \quad \varphi_{3}=v_{3} \sqrt{ } \lambda_{3}, \ldots \tag{2.3}
\end{equation*}
$$

is a complete set, orthonormal in $\bar{V}_{B}$ i.e.

$$
\left(\left(\varphi_{i}, \varphi_{j}\right)\right)_{B}=\left\{\begin{array}{lll}
0 & \text { if } \quad i \neq j  \tag{2.4}\\
1 & \text { if } \quad i=j
\end{array}\right.
$$

Let the first eigenvalue $\lambda_{1}$ be simple and let $f_{0} \in V_{B}$ be not orthogonal, in $\bar{V}_{B}$, to $v_{1}$, or, what is the same, to $\varphi_{1}$. Solve, successively, the sequence of problems

$$
\begin{gather*}
\left(\left(v, f_{1}\right)\right)_{A}=\left(\left(v, f_{0}\right)\right)_{B}, \\
\left(\left(v, f_{2}\right)\right)_{A}=\left(\left(v, f_{1}\right)\right)_{B},  \tag{2.5}\\
\ldots \ldots \ldots \ldots \ldots \\
\left(\left(v, f_{k}\right)\right)_{A}=\left(\left(v, f_{k-1}\right)\right)_{B}
\end{gather*}
$$

Each of these problems is uniquely solvable (cf. (1.24)-(1.26)). Denote

$$
\begin{align*}
& a_{2 n}=\left(\left(f_{n}, f_{n}\right)\right)_{B},  \tag{2.6}\\
& \left.a_{2 n+1}=\left(\left(f_{n}, f_{n+1}\right)\right)_{B}=\left(\left(f_{n+1}, f_{n+1}\right)\right)_{A},{ }^{3}\right) \tag{2.7}
\end{align*}
$$

$n=0,1,2, \ldots$,

$$
\begin{equation*}
x_{k}=a_{k-1} / a_{k}, \quad k=1,2,3, \ldots \tag{2.8}
\end{equation*}
$$

The first purpose of this chapter is to show that

$$
\begin{equation*}
x_{1} \geqq x_{2} \geqq x_{3} \geqq \ldots \geqq \lambda_{1} \tag{2.9}
\end{equation*}
$$

and that

$$
\begin{equation*}
\lim _{k \rightarrow \infty} \varkappa_{k}=\lambda_{1} . \tag{2.10}
\end{equation*}
$$

In the second part of this chapter we show that, for every $k=1,2,3, \ldots$, we have

$$
\begin{equation*}
x_{k+1}-\frac{x_{k}-x_{k+1}}{\frac{l_{2}}{x_{k+1}}-1} \leqq \lambda_{1} \leqq x_{k+1} \tag{2.11}
\end{equation*}
$$

where $l_{2}$ is a lower estimate for the second eigenvalue $\lambda_{2}$, greater than $x_{k+1}$.
The proof of (2.9) is simple: We have, for every $t \in(-\infty,+\infty)$,

$$
\begin{gather*}
0 \leqq\left(\left(f_{n}+t f_{n+1}, f_{n}+t f_{n+1}\right)\right)_{B}=\left(\left(f_{n}, f_{n}\right)\right)_{B}+2 t\left(\left(f_{n}, f_{n+1}\right)\right)_{B}+  \tag{2.12}\\
+t^{2}\left(\left(f_{n+1}, f_{n+1}\right)\right)_{B}=a_{2 n}+2 t a_{2 n+1}+t^{2} a_{2 n+2} .
\end{gather*}
$$

Because the quadratic expression in $t$ should be nonnegative for all $t$, its discriminant cannot by positive. Thus

$$
\begin{equation*}
a_{2 n+1}^{2} \leqq a_{2 n} a_{2 n+2}, \tag{2.13}
\end{equation*}
$$

wherefrom, dividing by $a_{2 n+1} a_{2 n+2}$,

$$
\begin{equation*}
x_{2 n+2} \leqq x_{2 n+1} . \tag{2.14}
\end{equation*}
$$

[^2]Similarly

$$
\begin{gathered}
0 \leqq\left(\left(f_{n+1}+t f_{n+2}, f_{n+1}+t f_{n+2}\right)\right)_{A}=\left(\left(f_{n+1}, f_{n+1}\right)\right)_{A}+ \\
+2 t\left(\left(f_{n+1}, f_{n+2}\right)\right)_{A}+t^{2}\left(\left(f_{n+2}, f_{n+2}\right)\right)_{A}=a_{2 n+1}+2 t a_{2 n+2}+t^{2} a_{2 n+3},
\end{gathered}
$$

wherefrom, in the same way as before,

$$
\begin{equation*}
x_{2 n+3} \leqq x_{2 n+2} . \tag{2.15}
\end{equation*}
$$

Moreover, because $f_{n+1} \in V_{A}$, we have

$$
\begin{equation*}
\lambda_{1} \leqq \frac{\left(\left(f_{n+1}, f_{n+1}\right)\right)_{A}}{\left(\left(f_{n+1}, f_{n+1}\right)\right)_{B}}=\frac{a_{2 n+1}}{a_{2 n+2}}=\varkappa_{2 n+2} . \tag{2.16}
\end{equation*}
$$

(2.14), (2.15) and (2.16) yield (2.9).

To prove (2.10) and (2.11), we use Fourier expansions of the functions $f_{n}$ with respect to the orthonormal (in $\bar{V}_{B}$ ) system (2.3).

Let

$$
\begin{equation*}
f_{0}=\sum_{i=1}^{\infty} \alpha_{i} \varphi_{i} \tag{2.17}
\end{equation*}
$$

be the Fourier expansion of the function $f_{0}$ in $\bar{V}_{B}$. Thus

$$
\begin{equation*}
\alpha_{i}=\left(\left(f_{0}, \varphi_{i}\right)\right)_{B}, \quad i=1,2,3, \ldots \tag{2.18}
\end{equation*}
$$

while, according to the assumption,

$$
\begin{equation*}
\alpha_{1}=\left(\left(f_{0}, \varphi_{1}\right)\right)_{B} \neq 0 . \tag{2.19}
\end{equation*}
$$

Moreover,

$$
\begin{equation*}
\sum_{i=1}^{\infty} \alpha_{i}^{2}<+\infty . \tag{2.20}
\end{equation*}
$$

Denote, for a while,

$$
\begin{equation*}
F_{1}=\sum_{i=1}^{\infty} \frac{\alpha_{i}}{\lambda_{i}} \varphi_{i} . \tag{2.21}
\end{equation*}
$$

Because of (2.20) and of $\lambda_{i} \rightarrow+\infty$ for $i \rightarrow \infty$, the series (2.21) is convergent (in $\bar{V}_{B}$ ). We have (cf. (2.3) and the first of the integral identities (2.5))

$$
\begin{align*}
F_{1} & =\sum_{i=1}^{\infty} \frac{\alpha_{i}}{\lambda_{i}} \varphi_{i}=\sum_{i=1}^{\infty} \frac{\left(\left(f_{0}, v_{i} \sqrt{ } \lambda_{i}\right)\right)_{B}}{\lambda_{i}} v_{i} \sqrt{ } \lambda_{i}=  \tag{2.22}\\
& =\sum_{i=1}^{\infty}\left(\left(f_{0}, v_{i}\right)\right)_{B} v_{i}=\sum_{i=1}^{\infty}\left(\left(f_{1}, v_{i}\right)\right)_{A} v_{i}=f_{1},
\end{align*}
$$

since $\left\{v_{i}\right\}$ is a complete orthonormal system in $\bar{V}_{A}$ and the last series in (2.22) is the

Fourier series of the function $f_{1}$, thus converging to $f_{1}$ in $\bar{V}_{A}$ (and the more in $\bar{V}_{B}$ ). Similarly, denoting $\alpha_{i} / \lambda_{i}=\beta_{i}$, so that

$$
f_{1}=\sum_{i=1}^{\infty} \beta_{i} \varphi_{i}
$$

we get

$$
\begin{gathered}
F_{2}=\sum_{i=1}^{\infty} \frac{\alpha_{i}}{\lambda_{i}^{2}} \varphi_{i}=\sum_{i=1}^{\infty} \frac{\beta_{i}}{\lambda_{i}} \varphi_{i}=\sum_{i=1}^{\infty} \frac{\left(\left(f_{1}, v_{i} \sqrt{ } \lambda_{i}\right)\right)_{B}}{\lambda_{i}} v_{i} \sqrt{ } \lambda_{i}= \\
=\sum_{i=1}^{\infty}\left(\left(f_{1}, v_{i}\right)\right)_{B}=\sum_{i=1}^{\infty}\left(\left(f_{2}, v_{i}\right)\right)_{A} v_{i}=f_{2}
\end{gathered}
$$

in $\bar{V}_{A}$ as well as in $\bar{V}_{B}$, and, in general

$$
\begin{equation*}
f_{k}=\sum_{i=1}^{\infty} \frac{\alpha_{i}}{\lambda_{i}^{k}} \varphi_{i} \tag{2.23}
\end{equation*}
$$

(in $\bar{V}_{A}$ as well as in $\bar{V}_{B}$ ).
Putting this result into (2.6) and (2.7), we get

$$
\begin{align*}
a_{2 n} & =\left(\left(f_{n}, f_{n}\right)\right)_{B}=\left(\left(\sum_{i=1}^{\infty} \frac{\alpha_{i}}{\lambda_{i}^{n}} \varphi_{i}, \sum_{j=1}^{\infty} \frac{\alpha_{j}}{\lambda_{j}^{n}} \varphi_{j}\right)\right)_{B}=\sum_{i=1}^{\infty} \frac{\alpha_{i}^{2}}{\lambda_{i}^{2 n}},  \tag{2.24}\\
a_{2 n+1} & =\left(\left(f_{n+1}, f_{n+1}\right)\right)_{A}=\left(\left(\sum_{i=1}^{\infty} \frac{\alpha_{i}}{\lambda_{i}^{n+1}} \varphi_{i}, \sum_{j=1}^{\infty} \frac{\alpha_{j}}{\lambda_{j}^{n+1}} \varphi_{j}\right)\right)_{A}=  \tag{2.25}\\
& =\sum_{i, j=1}^{\infty} \frac{\alpha_{i}}{\lambda_{i}^{n+1}} \frac{\alpha_{j}}{\lambda_{j}^{n+1}} \sqrt{ } \lambda_{i} \sqrt{ } \lambda_{j}\left(\left(v_{i}, v_{j}\right)\right)_{A}=\sum_{i=1}^{\infty} \frac{\alpha_{i}^{2}}{\lambda_{i}^{2 n+1}} .
\end{align*}
$$

Thus

$$
\begin{gather*}
a_{k}=\sum_{i=1}^{\infty} \frac{\alpha_{i}^{2}}{\lambda_{i}^{k}}, \quad k=0,1,2, \ldots  \tag{2.26}\\
x_{k}=\left(\sum_{i=1}^{\infty} \frac{\alpha_{i}^{2}}{\lambda_{i}^{k-1}}\right) /\left(\sum_{i=1}^{\infty} \frac{\alpha_{i}^{2}}{\lambda_{l}^{k}}\right), \quad k=0,1,2, \ldots \tag{2.27}
\end{gather*}
$$

Now, to prove (2.10) it is sufficient to write

$$
\begin{equation*}
x_{k}=\frac{\frac{1}{\lambda_{1}^{k-1}} \sum_{i=1}^{\infty} \alpha_{i}^{2}\left(\frac{\lambda_{1}}{\lambda_{i}}\right)^{k-1}}{\frac{1}{\lambda_{1}^{k}} \sum_{i=1}^{\infty} \alpha_{i}^{2}\left(\frac{\lambda_{1}}{\lambda_{i}}\right)^{k}}=\lambda_{1} \frac{\alpha_{1}^{2}+\sum_{i=2}^{\infty} \alpha_{i}^{2}\left(\frac{\lambda_{1}}{\lambda_{i}}\right)^{k-1}}{\alpha_{1}^{2}+\sum_{i=2}^{\infty} \alpha_{i}^{2}\left(\frac{\lambda_{1}}{\lambda_{i}}\right)^{k}} \tag{2.28}
\end{equation*}
$$

whence it immediately follows

$$
\begin{equation*}
\lim _{k \rightarrow \infty} x_{k}=\lambda_{1} \tag{2.29}
\end{equation*}
$$

because $\alpha_{1} \neq 0$ and $\lambda_{1}<\lambda_{2} \leqq \lambda_{3} \leqq \ldots$ holds, so that the sums of both the series on the right hand side of (2.28) can be made arbitrarily small if $k$ is sufficiently large.

Remark 2.1. In the preceding text we assumed that the least eigenvalue $\lambda_{1}$ was simple and that $f_{0}$ was not orthogonal, in $\bar{V}_{B}$, to the first eigenfunction $\varphi_{1}$, i.e. that

$$
\begin{equation*}
\alpha_{1}=\left(\left(f_{0}, \varphi_{1}\right)\right)_{B} \neq 0 . \tag{2.30}
\end{equation*}
$$

To derive both (2.9) and (2.10), the assumption of simplicity of $\lambda_{1}$ is superfluous: When deriving (2.14), (2.15), this assumption was nowhere used. The same holds for (2.16). Moreover, only $f_{0} \neq 0$ was sufficient to be required. To examine (2.29), let us assume that the least eigenvalue is of multiplicity $s$, so that

$$
\begin{equation*}
\lambda_{1}=\lambda_{2}=\ldots \lambda_{s}<\lambda_{s+1} \tag{2.31}
\end{equation*}
$$

and

$$
\begin{equation*}
\varphi_{1}, \varphi_{2}, \ldots, \varphi_{s} \tag{2.32}
\end{equation*}
$$

are corresponding eigenfunctions orthonormalized in $\bar{V}_{B}$. Let $f_{0}$ be not ortogonal to each of the functions (2.32), so that at least one of the numbers

$$
\alpha_{i}=\left(\left(f_{0}, \varphi_{i}\right)\right)_{B}, \quad i=1,2, \ldots, s
$$

is different from zero. Then (cf. (2.28))

$$
\begin{equation*}
x_{k}=\lambda_{1} \frac{\alpha_{1}^{2}+\ldots+\alpha_{s}^{2}+\sum_{i=s+1}^{\infty} \alpha_{i}^{2}\left(\frac{\lambda_{1}}{\lambda_{i}}\right)^{k-1}}{\alpha_{1}^{2}+\ldots+\alpha_{s}^{2}+\sum_{i=s+1}^{\infty} \alpha_{i}^{2}\left(\frac{\lambda_{1}}{\lambda_{i}}\right)^{k}}, \tag{2.33}
\end{equation*}
$$

whence

$$
\begin{equation*}
\lim _{k \rightarrow \infty} x_{k}=\lambda_{1} \tag{2.34}
\end{equation*}
$$

as before.
If $\lambda_{1}$ is simple and if

$$
\begin{equation*}
\alpha_{1}=\left(\left(f_{0}, \varphi_{1}\right)\right)_{B}=0 \tag{2.35}
\end{equation*}
$$

then (2.9) remains true, but (2.10), i.e. (2.29), does no more hold. For example, if then $\lambda_{2}$ is simple ${ }^{4}$ ) and

$$
\alpha_{2}=\left(\left(f_{0}, \varphi_{2}\right)\right)_{B} \neq 0,
$$

[^3]it follows from (2.27) that
$$
\varkappa_{k}=\lambda_{1} \frac{\alpha_{2}^{2}+\sum_{i=3}^{\infty} \alpha_{i}^{2}\left(\frac{\lambda_{2}}{\lambda_{i}}\right)^{k-1}}{\alpha_{2}^{2}+\sum_{i=3}^{\infty} \alpha_{i}^{2}\left(\frac{\lambda_{2}}{\lambda_{i}}\right)^{k}},
$$
whence
\[

$$
\begin{equation*}
\lim _{k \rightarrow \infty} x_{k}=\lambda_{2} . \tag{2.36}
\end{equation*}
$$

\]

If is easy to examine what happens in other cases.
Let us turn to the proof of (2.11).
Let $\lambda_{1}$ be simple and $\alpha_{1}=\left(\left(f_{0}, \varphi_{1}\right)\right)_{B} \neq 0$. Let $l_{2}$ be a lower estimate of $\lambda_{2}$ greater then $\chi_{k+1}$. According to (2.9) the right-hand side inequality in (2.11) is ensured. We thus have to prove the validity of the left-hand one.

Let

$$
\begin{equation*}
\chi_{k+1}>\lambda_{1} . \tag{2.37}
\end{equation*}
$$

(If $x_{k+1}=\lambda_{1}$, there is nothing to prove, because $x_{k}-x_{k+1} \geqq 0$ and $l_{2} / x_{k+1}>1$.) Then (cf. (2.26))

$$
\begin{gather*}
x_{k+1} \frac{\chi_{k}-\lambda_{1}}{x_{k+1}-\lambda_{1}}=\frac{a_{k-1}-\lambda_{1} a_{k}}{a_{k}-\lambda_{1} a_{k+1}}=  \tag{2.38}\\
=\frac{\sum_{i=1}^{\infty} \frac{\alpha_{i}^{2}}{\lambda_{i}^{k-1}}-\lambda_{1} \sum_{i=1}^{\infty} \frac{\alpha_{i}^{2}}{\lambda_{i}^{k}}}{\sum_{i=1}^{\infty} \frac{\alpha_{i}^{2}}{\lambda_{i}^{k}}-\lambda_{1} \sum_{i=1}^{\infty} \frac{\alpha_{i}^{2}}{\lambda_{i}^{k+1}}=\frac{\sum_{i=2}^{\infty} \frac{\alpha_{i}^{2}}{\lambda_{i}^{k-1}}\left(1-\frac{\lambda_{1}}{\lambda_{i}}\right)}{\sum_{i=2}^{\infty} \frac{\alpha_{i}^{2}}{\lambda_{i}^{k}}\left(1-\frac{\lambda_{1}}{\lambda_{i}}\right)} .} .
\end{gather*}
$$

Now, for $i \geqq 2$, we have $\lambda_{i}^{k} \geqq \lambda_{2} \lambda_{i}^{k-1}$. Thus

$$
\begin{equation*}
x_{k+1} \frac{x_{k}-\lambda_{1}}{x_{k+1}-\lambda_{1}} \geqq \frac{\sum_{i=2}^{\infty} \frac{\alpha_{i}^{2}}{\lambda_{i}^{k-1}}\left(1-\frac{\lambda_{1}}{\lambda_{i}}\right)}{\sum_{i=2}^{\infty} \frac{x_{i}^{2}}{\lambda_{2} \lambda_{i}^{k-1}}\left(1-\frac{\lambda_{1}}{\lambda_{i}}\right)}=\lambda_{2} \geqq l_{2} \tag{2.39}
\end{equation*}
$$

Further

$$
\begin{equation*}
\frac{x_{k}-\lambda_{1}}{x_{k+1}-\lambda_{1}}=\frac{\chi_{k}-\chi_{k+1}}{x_{k+1}-\lambda_{1}}+1 . \tag{2.40}
\end{equation*}
$$

(2.39) and (2.40) yield

$$
\frac{x_{k}-x_{k+1}}{x_{k+1}-\lambda_{1}} \geqq \frac{l_{2}}{x_{k+1}}-1
$$

and finally,

$$
\begin{equation*}
\frac{x_{k}-x_{k+1}}{\frac{l_{2}}{x_{k+1}}-1} \geqq x_{k+1}-\lambda_{1} \tag{2.41}
\end{equation*}
$$

what is nothing else than the left-hand side inequality in (2.11).
In this way, (2.11) is proved. Note that here the assumption on $\lambda_{1}$ to be simple is essential (we require that $\chi_{k+1}<I_{2}$ and, at the same time, we have $\lambda_{1} \leqq x_{k+1}$ and $l_{2} \leqq \lambda_{2}$ ).

Let us summarize the results received in this chapter into the following
Theorem 2.1. Let the forms $((v, u))_{A},((v, u))_{B}$ satisfy assumptions (1.16)-(1.21) (concerning their symmetry, boundedness and ellipticity in $V_{A}$, resp. $V_{B}$ ). Let the first eigenvalue $\lambda_{1}$ of the problem (1.15) be simple ${ }^{5}$ ). Let $f_{0} \in V_{B}$ be not ortogonal, in $\bar{V}_{B}{ }^{6}$, ${ }^{6}$ ) to the first eigenfunction $\varphi_{1}$. Let $f_{1}, f_{2}, f_{3}, \ldots$ be solutions of the boundary value problems (2.5), let $a_{k}, x_{k}$ be defined by (2.6)-(2.8). Then we have

$$
\begin{gather*}
x_{1} \geqq x_{2} \geqq x_{3} \geqq \ldots \geqq \lambda_{1},  \tag{2.42}\\
\lim _{k \rightarrow \infty} \varkappa_{k}=\lambda_{1} \tag{2.43}
\end{gather*}
$$

and the following twosided estimate for $\lambda_{1}$ is valid:

$$
\begin{equation*}
x_{k+1}-\frac{x_{k}-x_{k+1}}{\frac{l_{2}}{x_{k+1}}-1} \leqq \lambda_{1} \leqq x_{k+1}, \tag{2.44}
\end{equation*}
$$

where $l_{2}$ is a lower bound ${ }^{7}$ ) for the second eigenvalue $\lambda_{2}$, greater then $\chi_{k+1}$, thus satisfing

$$
x_{k+1}<l_{2} \leqq \lambda_{2} .
$$

In this way, a twosided eigenvalue estimate of the Collatz typ is received. No Temple theorem has been used.

[^4]
## 3. APPROXIMATE SOLUTIONS. THE SEQUENCE $\left\{\tilde{x}_{k}\right\}$ AND ITS PROPERTIES

The aim of this chapter is to make clear what happens if the "iterative"problems (2.5) are solved approximately. To be concrete, let us use the Ritz method. The same results are obtained when using some other method (e.g. the finite element method) with properties similar to those which are summarized at the beginning of this chapter for the Ritz method.

Let

$$
\begin{equation*}
w_{1}, w_{2}, w_{3}, \ldots \tag{3.1}
\end{equation*}
$$

be a complete (linearly independent) system in $\bar{V}_{A}$. Let us choose the first $N$ functions

$$
\begin{equation*}
w_{1}, w_{2}, \ldots, w_{N} \tag{3.2}
\end{equation*}
$$

from this system and denote by $S_{N}$ the $N$-dimensional subspace of $\bar{V}_{A}$, constituted by these functions. Let us solve the problem of finding such a function $u \in \bar{V}_{A}$ that

$$
\begin{equation*}
((v, u))_{A}=((v, f))_{B} \quad v \in \bar{V}_{A} . \tag{3.3}
\end{equation*}
$$

The solution $u$ minimizes, in $\bar{V}_{A}$, the functional

$$
\begin{equation*}
F v=((v, v))_{A}-2((v, f))_{B} . \tag{3.4}
\end{equation*}
$$

As well known, the Ritz method consist in finding such a function

$$
\begin{equation*}
\tilde{u}_{N}=\sum_{i=1}^{N} a_{N i} w_{i} \tag{3.5}
\end{equation*}
$$

which minimizes this functional in $S_{N}$. It can be shown that $\tilde{u}_{N}$ is the orthogonal projection, in $\bar{V}_{A}$, of $u$ into $S_{N}$, i.e. that

$$
\begin{equation*}
\tilde{u}_{N}=P_{N} u, \tag{3.6}
\end{equation*}
$$

where $P_{N}$ is the corresponding projector. Obviously,

$$
\begin{equation*}
\left\|\tilde{u}_{N}\right\|_{\boldsymbol{V}_{\mathcal{A}}} \leqq\|u\|_{\boldsymbol{V}_{\mathcal{A}}} \tag{3.7}
\end{equation*}
$$

(Remind that $\|h\|_{V_{A}}=\sqrt{ }((h, h))_{A}$.) If an orthonormalized in $V_{A}$ system $\left\{z_{i}\right\}$ is used instead of $(3,1)$, i.e. if

$$
\begin{equation*}
\left(\left(z_{i}, z_{k}\right)\right)_{A}=\delta_{i k}, \tag{3.8}
\end{equation*}
$$

then

$$
\begin{equation*}
u=\sum_{i=1}^{\infty}\left(\left(z_{i}, u\right)\right)_{A} z_{i}=\sum_{i=1}^{\infty}\left(\left(z_{i}, f\right)\right)_{B} z_{i} \tag{3.9}
\end{equation*}
$$

(according to (3.3)), while

$$
\begin{equation*}
\tilde{u}_{N}=\sum_{i=1}^{N}\left(\left(z_{i}, f\right)\right)_{B} z_{i} . \tag{3.10}
\end{equation*}
$$

The system $\left\{z_{i}\right\}$ can be obtained from the system (3.1) using the familiar Schmidt
orthonormalization in $\bar{V}_{A}$. The function (3.5) with $a_{N i}$ found by the Ritz method can then be written in the form $\left.(3.10)^{8}\right)$.

Now, let us solve the problems (2.5), p. 219, approximately using the Ritz method with the base functions (3.2). Let

$$
\begin{align*}
& \left\{\tilde{f}_{n}\right\},  \tag{3.11}\\
& \left\{\tilde{f}_{n}\right\} \tag{3.12}
\end{align*}
$$

be sequences of such functions that $\tilde{f}_{n+1}$ is the approximate solution of the problem

$$
\begin{equation*}
((v, u))_{A}=\left(\left(v, \tilde{f}_{n}\right)\right)_{B} \quad \forall v \in V_{A} \tag{3.13}
\end{equation*}
$$

( $n=0,1,2, \ldots, \tilde{f}_{0}=f_{0}$ ), obtained by the Ritz method, while $f_{n+1}$ is its exact solution, i.e.

$$
\begin{equation*}
\left(\left(v, f_{n+1}\right)\right)_{A}=\left(\left(v, \tilde{f}_{n}\right)\right)_{B} \quad \forall v \in V_{A} \tag{3.14}
\end{equation*}
$$

$\left(n=0,1,2, \ldots, f_{0}=f_{0}, \bar{f}_{1}=f_{1}\right)$.
We shall assume, as before, that $\lambda_{1}$ is simple and that $f_{0}$ is not orthogonal, in $\bar{V}_{B}$, to the first eigenfunction $\varphi_{1}$, i.e. that

$$
\begin{equation*}
\left(\left(f_{0}, \varphi_{1}\right)\right)_{B} \neq 0 \tag{3.15}
\end{equation*}
$$

(Cf. (2.19).) In particular, $f_{0} \neq 0$. It will follow from Remark 3.3 (see also Theorem 3.1) that for all sufficiently large $N$, the functions (3.11) and (3.12) are different from zero. We shall always assume $N$ so large to quarantee this property.

Denote

$$
\begin{align*}
& \tilde{a}_{2 n}=\left(\left(\tilde{f}_{n}, \tilde{f}_{n}\right)\right)_{B},  \tag{3.16}\\
& \tilde{a}_{2 n+1}=\left(\left(\tilde{f}_{n}, \tilde{f}_{n+1}\right)\right)_{B}, \tag{3.17}
\end{align*}
$$

$n=0,1,2, \ldots$ We have, according to (3.14), written for $v=\tilde{f}_{n+1}$ :

$$
\tilde{a}_{2 n+1}=\left(\left(\tilde{f}_{n}, \tilde{f}_{n+1}\right)\right)_{B}=\left(\left(\tilde{f}_{n+1}, \bar{f}_{n+1}\right)\right)_{A}
$$

Now, $\tilde{f}_{n+1}$ is of the form (3.9), $\tilde{f}_{n+1}$ of the form (3.10), both with $f=\tilde{f}_{n}$. Thus

$$
\begin{equation*}
\left(\left(\bar{f}_{n+1}, \tilde{f}_{n+1}\right)\right)_{A}=\left(\left(\tilde{f}_{n+1}, \tilde{f}_{n+1}\right)\right)_{A} \tag{3.18}
\end{equation*}
$$

because $z_{i}$ are orthonormal in $\vec{V}_{A}$. From $\tilde{f}_{n} \neq 0, \tilde{f}_{n+1} \neq 0$ and from (3.16)-(3.18) it follows

$$
\begin{equation*}
\tilde{a}_{2 n}>0, \quad \tilde{a}_{2 n+1}>0, \quad n=0,1,2, \ldots \tag{3.19}
\end{equation*}
$$

We thus can define

$$
\begin{equation*}
\tilde{x}_{k}=\tilde{a}_{k-1} \mid \tilde{a}_{k}, \quad k=1,2,3, \ldots \tag{3.20}
\end{equation*}
$$

[^5]Now, it is easy to prove that

$$
\begin{equation*}
\tilde{x}_{1} \geqq \tilde{x}_{2} \geqq \tilde{x}_{3} \geqq \ldots \geqq \lambda_{1} . \tag{3.21}
\end{equation*}
$$

In fact, the inequality

$$
\tilde{x}_{2 n+2} \leqq \tilde{x}_{2 n+1},
$$

$n=0,1,2, \ldots$ can be derived in the same way as the inequality (2.14), p. 219. Further,

$$
\tilde{a}_{2 n+1}=\left(\left(\tilde{f}_{n+1}, \tilde{f}_{n+1}\right)\right)_{A}
$$

as we have just proved, and

$$
\tilde{a}_{2 n+2}=\left(\left(\tilde{f}_{n+1}, \tilde{f}_{n+1}\right)\right)_{B}=\left(\left(\tilde{f}_{n+1}, \bar{f}_{n+2}\right)\right)_{A}=\left(\left(\tilde{f}_{n+1}, \tilde{f}_{n+2}\right)\right)_{A},
$$

because $\tilde{f}_{n+1}$ is of the form (3.10) with $f=\tilde{f}_{n}$ and $\tilde{f}_{n+2}$, or $\tilde{f}_{n+2}$ is of the form (3.9), or (3.10), respectively, with $f=\tilde{f}_{n+1}$. Thus we can use precisely the same procedure as when proving (2.15). Because

$$
\tilde{x}_{2 n+2}=\frac{\tilde{a}_{2 n+1}}{\tilde{a}_{2 n+2}}=\frac{\left(\left(\tilde{f}_{n+1}, \tilde{f}_{n+1}\right)\right)_{A}}{\left(\left(\tilde{f}_{n+1}, \tilde{f}_{n+1}\right)\right)_{B}} \geqq \lambda_{1},
$$

the proof of (3.21) is finished.
Further, we shall prove that not only the analogue (3.21) of (2.9) is valid, but that also the analogue of (2.10) holds:

$$
\begin{equation*}
\lim _{\substack{k \rightarrow \infty \\ N \rightarrow \infty}} \tilde{x}_{k}=\lambda_{1} . \tag{3.22}
\end{equation*}
$$

However, the proof of this assertion is not so simple as the proof of (3.21), and it is left to Remark 3.3.

We proceed now to give an analogue of the twosided estimate (2.11), p. 219. First we show that, $k$ being fixed, it is possible to make $\left|x_{k}-\tilde{x}_{k}\right|$ arbitrarily small if $N$ in the Ritz method is sufficiently large. To this purpose, we show the same assertion for $\left\|f_{p}-\tilde{f}_{p}\right\|_{V_{B}}$ if $p$ is fixed.

Let us remind, first, that when solving the problem (1.24), p. 221,
(i) a constant $c>0$ exists, independent of $g$ and $v$, such that we have

$$
\begin{equation*}
\|u\|_{V_{A}} \leqq c\|g\|_{V_{B}} \tag{3.23}
\end{equation*}
$$

(cf. (1.25), p. 221);
(ii) using the Ritz method, to every $\eta>0$ an $N_{0}$ can be found such that

$$
\begin{equation*}
\left\|\tilde{u}_{N}-u\right\|_{V_{A}}<\eta \tag{3.24}
\end{equation*}
$$

for every $N>N_{0}$. (Here, $\tilde{u}_{N}$ is the approximate solution received by the Ritz method when using the functions (3.2).)

Further, note that (see (1.18), (1.20), (3.7))

$$
\begin{equation*}
\left\|\tilde{u}_{N}\right\|_{V_{A}} \leqq \frac{1}{\sqrt{ } \alpha}\left\|\tilde{u}_{N}\right\|_{V_{A}} \leqq \frac{1}{\sqrt{\alpha}}\|u\|_{V_{A}} \leqq \frac{\sqrt{ } K_{1}}{\sqrt{ } \alpha}\|u\|_{V_{A}} \leqq \frac{\sqrt{ } K_{1}}{\sqrt{\alpha}} c\|g\|_{V_{B}}=\bar{c}\|g\|_{V_{B}} \tag{3.25}
\end{equation*}
$$ where the constant

$$
\begin{equation*}
\bar{c}=\frac{\sqrt{ } K_{1}}{\sqrt{ } \alpha} c \tag{3.26}
\end{equation*}
$$

does not depend on $g$.
Let, as before, $\lambda_{1}$ be simple, let $f_{0}$ satisfy (3.15). Let, again, $f_{1}, f_{2}, f_{3}, \ldots, f_{p}$ be (exact) solutions of the first $p$ "iterative" problems (2.5). Let $\hat{f}_{i}$ be the Ritz approximation of $f_{i}$, i.e. the approximate solution of the problem

$$
((v, u))_{A}=\left(\left(v, f_{i-1}\right)\right)_{B} \quad \forall v \in V_{A}
$$

received by the Ritz method, taking the first $N_{i}$ terms of the base (3.1). (Thus

$$
\begin{equation*}
\hat{f}_{i}=P_{N_{i}} T f_{i-1}, \quad i=1, \ldots, p \tag{3.27}
\end{equation*}
$$

in the sense of $\left.(3.6 .)^{9}\right)$ Let, as before, $\tilde{f}_{i}, i=1, \ldots, p$, be the Ritz approximation of the solution of the problem

$$
((v, u))_{A}=\left(\left(v, \tilde{f}_{i-1}\right)\right)_{B} \quad \forall v \in V_{A} .
$$

Let $\eta>0$ be given and let $N_{i}, i=1, \ldots, p$, be so large that

$$
\begin{equation*}
\left\|f_{i}-\hat{f}_{i}\right\|_{V_{A}}<\eta . \tag{3.28}
\end{equation*}
$$

Such $N_{i}$ always exist (see (3.24)). Moreover, if we denote

$$
\begin{equation*}
N=\max \left(N_{1}, \ldots, N_{p}\right) \tag{3.29}
\end{equation*}
$$

(3.28) remains true if we substitute $N$ for each of $N_{i}$. (This is a well-known property of the Ritz method, based on (3.9).)

Performing the Ritz method with this $N$, we get according to (3.28) and (3.25) (note that $\tilde{f}_{1}=\hat{f}_{1}$ )

$$
\begin{gather*}
\left\|f_{p}-\tilde{f}_{p}\right\|_{V_{B}} \leqq\left\|f_{p}-\tilde{f}_{p}\right\|_{V_{A}} \leqq\left\|f_{p}-\hat{f}_{p}\right\|_{V_{A}}+\left\|\hat{f}_{p}-\tilde{f}_{p}\right\|_{V_{A}} \leqq  \tag{3.30}\\
\leqq \eta+\bar{c}\left\|f_{p-1}-\tilde{f}_{p-1}\right\|_{V_{B}} \leqq \eta+\bar{c}\left(\eta+\bar{c}\left\|f_{p-2}-\tilde{f}_{p-2}\right\|_{V_{B}}\right) \leqq \ldots \leqq \\
=\eta+\bar{c}\left\{\eta+\bar{c}\left[\eta+\ldots+\bar{c}\left\|f_{1}-\tilde{f}_{1}\right\|_{V_{B}}\right]\right\}= \\
=\eta\left(1+\bar{c}+\bar{c}^{2}+\ldots+\bar{c}^{p-1}\right)=\eta C_{p},
\end{gather*}
$$

with

$$
\begin{equation*}
C_{p}=1+\bar{c}+\bar{c}^{2}+\ldots+\bar{c}^{p-1} \tag{3.31}
\end{equation*}
$$

[^6]Thus $p$ being given, to arbitrary $\varrho>0$ such an $N$ can be found that

$$
\begin{equation*}
\left\|f_{q}-\tilde{f}_{q}\right\|_{B}<\varrho \tag{3.32}
\end{equation*}
$$

(even that

$$
\begin{equation*}
\left.\left\|f_{q}-\tilde{f}_{q}\right\|_{A}<\varrho\right) \tag{3.33}
\end{equation*}
$$

for all $q=1,2, \ldots, p$.
Now, from the form of $a_{2 n}, a_{2 n+1}, x_{k}$ and $\tilde{a}_{2 n}, \tilde{a}_{2 n+1}, \tilde{x}_{k}$ (cf. (3.16), (3.17), (3.20)) it immediately follows (choosing $\varrho$ sufficiently small) that $k$ being given, to every $\zeta>0$ such an $N$ can be found that

$$
\begin{equation*}
\left|x_{k}-\tilde{x}_{k}\right|<\zeta . \tag{3.34}
\end{equation*}
$$

Now, the sequence of $\varkappa_{k}$ satisfies (2.43),

$$
\begin{equation*}
\lim _{k \rightarrow \infty} x_{k}=\lambda_{1} \tag{3.35}
\end{equation*}
$$

Thus choosing $\varepsilon>0$ and denoting $\varepsilon / 2=\zeta$, it is possible, first, to find such a $k$ that

$$
\left|x_{k}-\lambda_{1}\right|<\zeta,
$$

and then to find such an $N$ that

$$
\left|x_{k}-\tilde{x}_{k}\right|<\zeta .
$$

Thus we have:
Proposition 3.1. If $k$ is given, then to every $\varepsilon>0$ it is possible to find such an $N$ that using the Ritz method with the first $N$ terms of the base, we have

$$
\begin{equation*}
\left|\tilde{\chi}_{k}-\lambda_{1}\right|<\varepsilon . \tag{3.36}
\end{equation*}
$$

Remark 3.1. In Remark 3.3 we give a substantially stronger assertion, even that

$$
\lim _{\substack{k \rightarrow \infty \\ N \rightarrow \infty}} \tilde{x}_{k}=\lambda_{1}
$$

(see also Theorem 3.1).
Remark 3.2. When deriving inequality (3.34), it was possible, using (3.30) and the formulae for $a_{2 n}, a_{2 n+1}, \chi_{k}, \tilde{a}_{2 n}, \tilde{a}_{2 n+1}, \tilde{x}_{k}$, to give an explicite estimate for $\left|\chi_{k}-\tilde{\chi}_{k}\right|$. We did not do it, because our aim was to show only that $\tilde{x}_{k}$ can be made arbitrarily close to $\lambda_{1}$ if $k$ and $N$ are sufficiently large, and to establish in this way the usefulness of carrying out our iterational process. To get the error-estimate when stopping the process after $k$ steps we can go on in a considerably simpler way:

Thus let the functions $\tilde{f}_{0}=f_{0}, \tilde{f}_{1}, \ldots, \tilde{f}_{k-1}$ be known. As described above, $\tilde{f}_{k}$ is the approximate solution of the problem

$$
((v, u))_{A}=\left(\left(v, \tilde{f}_{k-1}\right)\right)_{B} \quad \forall v \in V_{A},
$$

while $\bar{f}_{k}$ is its exact solution, thus satisfying

$$
\left(\left(v, \bar{f}_{k}\right)\right)_{A}=\left(\left(v, \tilde{f}_{k-1}\right)\right)_{B} \quad \forall v \in V_{A}
$$

If $\vec{f}_{k}$ be known, we could write down the tvosided eigenvalue estimate in the form (1.44),

$$
\begin{equation*}
x_{2}-\frac{x_{1}-x_{2}}{\frac{l_{2}}{x_{2}}-1} \leqq \lambda_{1} \leqq x_{2}, \tag{3.37}
\end{equation*}
$$

taking $\tilde{f}_{k-1}$ for the outcoming function $f_{0}$ and $\bar{f}_{k}$ for $f_{1}$, i.e. writing

$$
\begin{equation*}
x_{1}=a_{0} / a_{1}, \quad x_{2}=a_{1} / a_{2} \tag{3.38}
\end{equation*}
$$

with

$$
\begin{equation*}
a_{0}=\left(\left(\tilde{f}_{k-1}, \tilde{f}_{k-1}\right)\right)_{B}, \quad a_{1}=\left(\left(\tilde{f}_{k-1}, \bar{f}_{k}\right)\right)_{B}, \quad a_{2}=\left(\left(\bar{f}_{k}, \bar{f}_{k}\right)\right)_{B} . \tag{3.39}
\end{equation*}
$$

With the help of (3.38), the inequalities (3.37) can be rewritten in the form

$$
x_{2} \frac{l_{2}-x_{1}}{l_{2}-x_{2}} \leqq \lambda_{1} \leqq x_{2}
$$

or

$$
\begin{equation*}
\frac{a_{1} l_{2}-a_{0}}{a_{2} l_{2}-a_{1}} \leqq \lambda_{1} \leqq \frac{a_{1}}{a_{2}} \tag{3.40}
\end{equation*}
$$

Now, we do not know $\bar{f}_{k}$, but only its Ritz approximation $\tilde{f}_{k}$, received with an error $\varepsilon$,

$$
\begin{equation*}
\left\|\bar{f}_{k}-\tilde{f}_{k}\right\|_{\nabla_{B}} \leqq \varepsilon \tag{3.41}
\end{equation*}
$$

(How to get error estimates using the Ritz method see e.g. [1], especially Chaps 11 and 21.) Before substituting $\tilde{f}_{k}$ for $\bar{f}_{k}$ into (3.39) note that

$$
\begin{gather*}
\left|\left(\left(\tilde{f}_{k-1}, \bar{f}_{k}\right)\right)_{B}-\left(\left(\tilde{f}_{k-1}, \tilde{f}_{k}\right)\right)_{B}\right|=\left|\left(\left(\tilde{f}_{k-1}, \bar{f}_{k}-\tilde{f}_{k}\right)\right)_{B}\right| \leqq\left\|\tilde{f}_{k-1}\right\|_{V_{B}} \varepsilon,  \tag{3.42}\\
\left|\left(\left(\bar{f}_{k}, \bar{f}_{k}\right)\right)_{B}-\left(\left(\tilde{f}_{k}, \tilde{f}_{k}\right)\right)_{B}\right|=\left|\left(\left(\bar{f}_{k}, \bar{f}_{k}-\tilde{f}_{k}\right)\right)_{B}-\left(\left(\tilde{f}_{k}, \tilde{f}_{k}-\bar{f}_{k}\right)\right)_{B}\right| \leqq  \tag{3.43}\\
\leqq\left(\left\|\tilde{f}_{k}\right\| \nabla_{\nabla_{B}}+\varepsilon\right) \varepsilon+\left\|\tilde{f}_{k}\right\|_{V_{B}} \varepsilon=\left(2\left\|\tilde{f}_{k}\right\|_{V_{B}}+\varepsilon\right) \varepsilon .
\end{gather*}
$$

Thus denoting

$$
\begin{equation*}
\tilde{a}_{0}=\left(\left(\tilde{f}_{k-1}, \tilde{f}_{k-1}\right)\right)_{B}, \quad \tilde{a}_{1}=\left(\left(\tilde{f}_{k-1}, \tilde{f}_{k}\right)\right)_{B}, \quad \tilde{a}_{2}=\left(\left(\tilde{f}_{k}, \tilde{f}_{k}\right)\right)_{B}, \tag{3.44}
\end{equation*}
$$

we have

$$
\tilde{a}_{0}=a_{0}, \quad a_{1} \geqq \tilde{a}_{1}-\left\|\tilde{f}_{k-1}\right\|_{\boldsymbol{V}_{B}} \varepsilon, \quad a_{2} \leqq \tilde{a}_{2}+\left(2\left\|\tilde{f}_{k}\right\|_{\boldsymbol{V}_{\boldsymbol{B}}}+\varepsilon\right) \varepsilon
$$

Substituting into (3.40) and noting that

$$
\tilde{a}_{1} / \tilde{a}_{2} \geqq \lambda_{1}
$$

(cf. (3.21)), we get finally the following relatively simple twosided eigenvalue estimate

$$
\begin{equation*}
\frac{\left(\tilde{a}_{1}-\left\|\tilde{f}_{k-1}\right\|_{\boldsymbol{V}_{B}} \varepsilon\right) l_{2}-\tilde{a}_{0}}{\left[\tilde{a}_{2}+\left(2\left\|\tilde{f}_{k}\right\|_{\boldsymbol{V}_{B}}+\varepsilon\right) \varepsilon\right] l_{2}+\left\|\tilde{f}_{k-1}\right\|_{\boldsymbol{V}_{B}} \varepsilon-\tilde{a}_{1}} \leqq \lambda_{1} \leqq \tilde{a}_{1} / \tilde{a}_{2} . \tag{3.45}
\end{equation*}
$$

Here, $\tilde{a}_{\mathrm{l}}, \tilde{a}_{1}, \tilde{a}_{2}$ are given by (3.44), $l_{2}$ is a lower estimate of the second eigenvalue
$\lambda_{2}$, greater then $\tilde{\varkappa}_{2}=\tilde{a}_{1} / \tilde{a}_{2}, \varepsilon$ is the error caused by using the Ritz method when solving the problem

$$
((v, u))_{A}=\left(\left(v, \tilde{f}_{k-1}\right)\right)_{B} \quad \forall v \in V_{A}
$$

(see (3.41); how to get $\varepsilon$, see the text following (3.41)), $\|\cdot\|_{V_{B}}=\sqrt{ }((., .))_{B}$.
Remark 3.3. (Proof of the relation

$$
\begin{equation*}
\left.\lim _{\substack{k \rightarrow \infty \\ N \rightarrow \infty}} \tilde{x}_{k}=\lambda_{1} .\right) \tag{3.46}
\end{equation*}
$$

Let us remind, first, that $\tilde{f}_{p}, \tilde{f}_{p+1}$ being known, we have

$$
\begin{equation*}
\tilde{a}_{2 p}=\left(\left(\tilde{f}_{p}, \tilde{f}_{p}\right)\right)_{B}, \quad \tilde{a}_{2 p+1}=\left(\left(\tilde{f}_{p}, \tilde{f}_{p+1}\right)\right)_{B}, \quad \tilde{a}_{2 p+2}=\left(\left(\tilde{f}_{p+1}, \tilde{f}_{p+1}\right)\right)_{B} \tag{3.47}
\end{equation*}
$$

and

$$
\begin{equation*}
\tilde{\chi}_{2 p+1}=\frac{\tilde{a}_{2 p}}{\tilde{a}_{2 p+1}}, \quad \tilde{\varkappa}_{2 p+2}=\frac{\tilde{a}_{2 p+1}}{\tilde{a}_{2 p+2}} . \tag{3.48}
\end{equation*}
$$

From (3.47) and (3.48) we have immediately:
Proposition 3.2. To every $\varepsilon>0$ there exists such an $\eta>0$ that if

$$
\begin{gather*}
\tilde{f}_{p}=c\left(\varphi_{1}+\sigma_{1}\right) \text { with } \sigma_{1} \perp \varphi_{1} \text { in } \bar{V}_{B} \text { and }\left\|\sigma_{1}\right\|_{V_{B}}<\eta,  \tag{3.49}\\
\tilde{f}_{p+1}=\frac{c K}{\lambda_{1}}\left(\varphi_{1}+\sigma_{2}\right) \text { with } \sigma_{2} \perp \varphi_{1} \text { in } \bar{V}_{B} \text { and }\left\|\sigma_{2}\right\|_{V_{B}}<\eta,  \tag{3.50}\\
|K-1|<2 \eta, \tag{3.51}
\end{gather*}
$$

then

$$
\begin{equation*}
\left.\left|\tilde{\chi}_{2 p+1}-\lambda_{1}\right|<\varepsilon, \quad\left|\tilde{\varkappa}_{2 p+2}-\lambda_{1}\right|<\varepsilon .{ }^{10}\right) \tag{3.52}
\end{equation*}
$$

${ }^{10}$ ) Roughly speaking, if $\tilde{f}_{p} \approx c \varphi_{1}, \tilde{f}_{p+1} \approx\left(c / \lambda_{1}\right) \varphi_{1}$, then $\tilde{x} \approx \lambda_{1}$. In fact, we have

$$
\begin{gathered}
\tilde{\chi}_{2 p+1}=\frac{\tilde{a}_{2 p}}{\tilde{a}_{2 p+1}}=\frac{\left(\left(\tilde{f}_{p}, \tilde{f}_{p}\right)\right)_{B}}{\left(\left(\tilde{f}_{p}, \tilde{f}_{p+1}\right)\right)_{B}}=\frac{c^{2}\left(\left(\varphi_{1}+\sigma_{1}, \varphi_{1}+\sigma_{1}\right)\right)_{B}}{\frac{c^{2} K}{\lambda_{1}}\left(\left(\varphi_{1}+\sigma_{1}, \varphi_{1}+\sigma_{2}\right)\right)_{B}}=\frac{\lambda_{1}}{K} \frac{\left\|\varphi_{1}\right\|_{V_{B}}^{2}+\left\|\sigma_{1}\right\|_{V_{B}}^{2}}{\left\|\varphi_{1}\right\|_{V_{B}}^{2}+\left(\left(\sigma_{1}, \sigma_{2}\right)\right)_{B}} \\
\tilde{x}_{2 p+1}-\lambda_{1}=\lambda_{1}\left(\frac{1}{K} \frac{1+\left\|\sigma_{1}\right\|_{\nabla_{B}}^{2}}{1+\left(\left(\sigma_{1}, \sigma_{2}\right)\right)_{B}}-1\right)
\end{gathered}
$$

(because $\left\|\varphi_{1}\right\|_{\boldsymbol{r}_{B}}=1$ ) and
$\lambda_{1}\left(\frac{1}{1+2 \eta} \frac{1}{1+\eta^{2}}-1\right) \leqq \lambda_{1}\left(\frac{1}{K} \frac{1+\left\|\sigma_{1}\right\|_{V_{B}}^{2}}{1+\left(\left(\sigma_{1}, \sigma_{2}\right)\right)_{B}}-1\right) \leqq \lambda_{1}\left(\frac{1}{1-2 \eta} \frac{1+\eta^{2}}{1-\eta^{2}}-1\right)$.
Similar inequalities are received for $\tilde{x}_{2 p+2}-\lambda_{1}$. Wherefrom Proposition 3.2 immediately follows.

Here, $\varphi_{1}$ is the first of the eigenfunctions orthonormalized in $\bar{V}_{B}$ (see (1.33)).
Because $\lambda_{1}<\lambda_{2}$ is always assumed, it is well to be seen that $\eta$ may be choosen so small that, moreover,

$$
\begin{equation*}
1-\sqrt{ }\left(\lambda_{1} / \lambda_{2}\right)-2 \eta>0 . \tag{3.53}
\end{equation*}
$$

First, we can really achieve that $\tilde{f}_{p}$ be of the form (3.49) choosing $p$ and $N$ in the Ritz method sufficiently large: In fact, as shown in the preceding chapter, starting with a function $f_{0} \in V_{B}$ such that

$$
\begin{equation*}
f_{0}=\sum_{i=1}^{\infty} \alpha_{i} \varphi_{i} \tag{3.54}
\end{equation*}
$$

we have

$$
\begin{equation*}
f_{1}=T f_{0}=\sum_{i=1}^{\infty}\left(\alpha_{i} \mid \lambda_{i}\right) \varphi_{i} . \tag{3.55}
\end{equation*}
$$

The assumption that $f_{0}$ is not orthogonal, in $\bar{V}_{B}$, to $\varphi_{1}$ ensures that

$$
\begin{equation*}
\alpha_{i}=\left(\left(f_{0}, \varphi_{1}\right)\right)_{B} \neq 0 . \tag{3.56}
\end{equation*}
$$

It follows, because $\lambda_{1}<\lambda_{2}$ and

$$
\begin{equation*}
\sum_{i=1}^{\infty} \alpha_{i}^{2}=\left\|f_{0}\right\|_{V_{B}}^{2}<+\infty \tag{3.57}
\end{equation*}
$$

that $f_{p}$ is arbitrarily close (in $\bar{V}_{B}$ ) to

$$
\begin{equation*}
\frac{\alpha_{1}}{\lambda_{1}^{p}} \varphi_{1} \tag{3.58}
\end{equation*}
$$

if $p$ is sufficiently large. Now, this $p$ being kept fixed, the $N$ in the Ritz method can be choosen so large that $f_{p}$ and $\tilde{f}_{p}$ are arbitrarily close (see (3.32), p. 229). Thus $\tilde{f}_{p}$ can be made arbitrarily close to the function (3.58). More precisely, $\eta>0$ being given, $p$ and $N$ can be found such that $f_{p}$ is of the form (3.49). (With $c \approx \alpha_{1} \mid \lambda_{1}^{p}$; however, this is unessential for what follows.) This result remains true (for $p$ fixed) even if we increase $N$, because from the well-known property of the Ritz method it follows that the more will then $f_{p}$ and $\tilde{f}_{p}$ be close.

Now it is sufficient to prove that $\tilde{f}_{p}$ being of the form (3.49), $\tilde{f}_{p+1}$ will be of the form (3.50).

Let us choose such an $N_{0}$ in the Ritz method $\left(N_{0} \geqq N\right)$ that the orthogonal (in $\bar{V}_{A}$ ) projection $P_{N_{0}} \varphi_{1}$ on the subspace $\bar{V}_{N_{0}}$ spanned by the first $N_{0}$ functions (3.1) be sufficiently close to $\varphi_{1}$. More precisely, that we have

$$
\begin{equation*}
P_{N_{0}} \varphi_{1}=k \varphi_{1}+\gamma, \tag{3.59}
\end{equation*}
$$

where

$$
\begin{equation*}
|k-1|<\eta, \quad\|\gamma\|_{\boldsymbol{V}_{B}} \leqq c=\left(1-\sqrt{ }\left(\lambda_{1} \mid \lambda_{0}\right)-2 \eta\right) \eta \tag{3.60}
\end{equation*}
$$

(cf. (3.53)). Solving the problem

$$
((v, u))_{A}=\left(\left(v, \tilde{f}_{p}\right)\right)_{B} \quad \forall v \in V_{A}
$$

by the Ritz method, we have (cf. (3.6))

$$
\begin{equation*}
\tilde{f}_{p+1}=P_{N_{0}} T \tilde{f}_{p} \tag{3.61}
\end{equation*}
$$

However,

$$
T \varphi_{1}=\frac{\varphi_{1}}{\lambda_{1}}
$$

and

$$
P_{N_{0}} T \varphi_{1}=\frac{1}{\lambda_{1}}\left(k \varphi_{1}+\gamma\right)
$$

according to (3.59). Further (we have $\sigma_{1} \perp \varphi_{1}$ in $\bar{V}_{B}$ )

$$
\sigma_{1}=\sum_{i=2}^{\infty} \delta_{i} \varphi_{i}, \quad \delta_{i}=\left(\left(\sigma_{1}, \varphi_{i}\right)\right)_{B}, \quad i=2,3, \ldots, \sum_{i=2}^{\infty} \delta_{i}^{2}<\eta^{2}
$$

according to (3.49). Thus

$$
\begin{gather*}
T \sigma_{1}=\sum_{i=2}^{\infty} \frac{\delta_{i}}{\lambda_{i}} \varphi_{i}=\sum_{i=2}^{\infty} \frac{\delta_{i}}{\sqrt{ } \lambda_{i}} v_{i} \\
\left\|T \sigma_{1}\right\|_{V_{A}}^{2}=\sum_{i=2}^{\infty} \frac{\delta_{i}^{2}}{\lambda_{i}} \leqq \frac{\eta^{2}}{\lambda_{2}} \\
\left\|P_{N_{0}} T \sigma_{1}\right\|_{V_{A}} \leqq\left\|T \sigma_{1}\right\|_{V_{A}} \leqq \frac{\eta}{\sqrt{ } \lambda_{2}} \\
\left\|P_{N_{0}} T \sigma_{1}\right\|_{V_{B}} \leqq \frac{1}{\sqrt{ } \lambda_{1}}\left\|P_{N_{0}} T \sigma_{1}\right\|_{V_{A}} \leqq \frac{\eta}{\sqrt{ }\left(\lambda_{1} \lambda_{2}\right)} \tag{3.62}
\end{gather*}
$$

because for all $v \in V_{A}$ we have

$$
\frac{((v, v))_{A}}{((v, v))_{B}} \geqq \lambda_{1} .
$$

Thus if we denote $P_{N_{0}} T \sigma_{1}=\tau$, we have according to (3.49)
(3.63) $\quad \tilde{f}_{p+1}=P_{N_{0}} T \tilde{f}_{p}=c\left(P_{N_{0}} T \varphi_{1}+P_{N_{0}} T \sigma_{1}\right)=c\left(\frac{1}{\lambda_{1}}\left(k \varphi_{1}+\gamma\right)+\tau\right)=$

$$
=\frac{c}{\lambda_{1}}\left(k \varphi_{1}+\gamma+\lambda_{1} \tau\right)
$$

where

$$
\begin{equation*}
\left\|\lambda_{1} \tau\right\|_{V_{B}} \leqq \eta \sqrt{\frac{\lambda_{1}}{\lambda_{2}}} \tag{3.64}
\end{equation*}
$$

in consequence of (3.62).
Denote by $\gamma_{1}$, resp. $\tau_{1}$ the orthogonal projection, in $\bar{V}_{B}$, of $\gamma$, resp. $\tau$ on the subspace generated by the function $\varphi_{1}$, thus

$$
\gamma=\gamma_{1}+\gamma_{2}, \quad \tau=\tau_{1}+\tau_{2}, \quad \gamma_{1} \perp \gamma_{2}, \quad \tau_{1} \perp \tau_{2} \quad \text { in } \quad \bar{V}_{B} .
$$

Because of (3.60), (3.64) we have

$$
\begin{align*}
\left\|\gamma_{1}+\lambda_{1} \tau_{1}\right\|_{V_{B}} \leqq(1-2 \eta) \eta  \tag{3.65}\\
\left\|\gamma_{2}+\lambda_{1} \tau_{2}\right\|_{V_{B}} \leqq(1-2 \eta) \eta
\end{align*}
$$

According to (3.63) we then get

$$
\begin{equation*}
\tilde{f}_{p+1}=\frac{c}{\lambda_{1}}\left[\left(k \varphi_{1}+\gamma_{1}+\lambda_{1} \tau_{1}\right)+\left(\gamma_{2}+\lambda_{1} \tau_{2}\right)\right]=\frac{c}{\lambda_{1}} K\left(\varphi_{1}+\sigma_{2}\right), \tag{3.66}
\end{equation*}
$$

where

$$
\begin{equation*}
\sigma_{2} \perp \varphi_{1} \quad \text { in } \quad \bar{V}_{B} \quad \text { and } \quad\left\|\sigma_{2}\right\|_{V_{B}}<\eta \tag{3.67}
\end{equation*}
$$

since

$$
\begin{equation*}
1-2 \eta<K<1+2 \eta \tag{3.68}
\end{equation*}
$$

according to the first inequality (3.60) and the first inequality of (3.65), and because of the second inequality (3.65).
Thus if $\tilde{f}_{p}$ is of the form (3.49), $\tilde{f}_{p+1}$ is of the form (3.50). It follows that a similar result is obtained for $\tilde{f}_{p+1}$ and $\tilde{f}_{p+2}$, etc.

In consequence of Proposition 3.2, the proof of (3.45) is finished.
At the same time it follows that all the $\tilde{f}_{i}$ are nonzero functions if the number of the terms in the Ritz method is sufficiently large.

Let us summarize the results of Chap. 3 into the following theorem:
Theorem 3.1. Let the forms $((v, u))_{A},((v, u))_{B}$ satisfy assumptions (1.16)-(1.21) (concerning their symmetry, boundedness end ellipticity in $V_{A}$, resp. $V_{B}$ ). Let the first eigenvalue $\lambda_{1}$ be simple. Let $f_{0} \in V_{B}$ be not orthogonal, in $\bar{V}_{B}$, to the first eigenfunction $\varphi_{1}$ and let $\tilde{f}_{i}(i=1,2, \ldots)$ be approximate solutions of the problems

$$
\begin{equation*}
((v, u))_{A}=\left(\left(v, \tilde{f}_{i-1}\right)\right)_{B} \quad \forall v \in V_{A} \tag{3.69}
\end{equation*}
$$

$\left(\tilde{f}_{0}=f_{0}\right)$ received by the Ritz method ${ }^{11}$ ), taking the first $N$ terms of the base (3.1).

[^7]Then:
(i) For all $N$ sufficiently large no $\tilde{f}_{i}$ is a zero function,

$$
\tilde{a}_{2 p}=\left(\left(\tilde{f}_{p}, \tilde{f}_{p}\right)\right)_{B}>0, \quad \tilde{a}_{2 p+1}=\left(\left(\tilde{f}_{p}, \tilde{f}_{p+1}\right)\right)_{B}>0,
$$

so that the quotients

$$
\tilde{x}_{k}=\frac{\tilde{a}_{k-1}}{\tilde{a}_{k}}
$$

are well-defined and positive for all $k=1,2, \ldots$.
(ii) We have

$$
\begin{gather*}
\tilde{x}_{1} \geqq \tilde{x}_{2} \geqq \ldots \geqq \lambda_{1},  \tag{3.70}\\
\lim _{\substack{k \rightarrow \infty \\
N \rightarrow \infty}} \tilde{x}_{k}=\lambda_{1} . \tag{3.71}
\end{gather*}
$$

(iii) Let us stop the process (3.6) after i steps and denote, for this case only,

$$
\tilde{a}_{0}=\left(\left(\tilde{f}_{i-1}, \tilde{f}_{i-1}\right)\right)_{B}, \quad \tilde{a}_{1}=\left(\left(\tilde{f}_{i-1}, \tilde{f}_{i}\right)\right)_{B}, \quad \tilde{a}_{2}=\left(\left(\tilde{f}_{i}, \tilde{f}_{i}\right)\right)_{B} .
$$

Then if for the exact solution $\bar{f}_{i}$ of the problem (3.69) and its Ritz approximation $\tilde{f}_{i}$ the relation

$$
\begin{equation*}
\left\|\bar{f}_{i}-\tilde{f}_{i}\right\|_{\boldsymbol{V}_{B}}<\varepsilon \tag{3.72}
\end{equation*}
$$

holds ${ }^{12}$ ) and if $l_{2}$ is a lower estimate of the eigenvalue $\lambda_{2}$, greater then $\tilde{\varkappa}_{2}=\tilde{a}_{1} / \tilde{a}_{2}$, the following twosided estimate is valid:

$$
\begin{equation*}
\frac{\left(\tilde{a}_{1}-\left\|\tilde{f}_{i-1}\right\|_{V_{B}} \varepsilon\right) l_{2}-\tilde{a}_{0}}{\left[\tilde{a}_{2}+\left(2\left\|\tilde{f}_{i}\right\|_{V_{B}}+\varepsilon\right) \varepsilon\right] l_{2}+\left\|\tilde{f}_{i-1}\right\|_{V_{B}} \varepsilon-\tilde{a}_{1}} \leqq \lambda_{1} \leqq \frac{\tilde{a}_{1}}{\tilde{a}_{2}} . \tag{3.73}
\end{equation*}
$$

Remark 3.4. (A remark of practical nature.) The assumptions of the theorem are rather natural. To get the needed information, one applies, as a rule, a suitable comparison theorem: The given problem is compared with a "similar" problem, or with "similar" problems; most often the given differential equation is compared with differential equations of the same kind, but with constant coefficients (and with the same boundary conditions). If these "similar" problems are directly solvable and this is often the case - we get, on base of the comparison theorem, the needed (rough) estimates for $\lambda_{1}$ and $\lambda_{2}$. (See Example 4.1, p. 237.) In this way, the simplicity of $\lambda_{1}$ follows immediately, as a rule. If, moreover, the system of eigenfunctions $\psi_{n}$ of such a "similar" problem is known, it is convevient to use it as a base for the Ritz method. (For details and for the theoretical background see, e.g., [1].) Choosing then $f_{0}=\psi_{1}$, it is sufficient, as a rule, to take only a few terms of this system to ensure the functions $\tilde{f}_{i}$ to be nonzero ones.

[^8]The number of steps in the iterative process depends on the accuracy required. The relation (3.71) shows that it is advisable to carry out more then one step. After stopping this process, (3.73) gives the desired twosided estimate. How to determine $\varepsilon$ in (3.72), see e.g. [1], especially Chaps 11 and 21.

## 4. A MODIFICATION OF THE METHOD. AN EXAMPLE

Although the twosided eigenvalue estimate (3.73) is relatively simple, its construction may appear rather labourious in some cases. This concerns especially the often tedious way how to get $\varepsilon$ in (3.72). We thus show a modification of the described method which may appear considerably more suitable to get the desired twosided estimate.

Thus let us have the functions $\left.f_{0}, \tilde{f}_{1}, \ldots, \tilde{f}_{i}^{13}\right)$. Now, instead of constructing the estimate (3.73), let us try to find a function $\hat{f}_{i-1}$ which is the exact solution of the problem

$$
\begin{equation*}
\left(\left(v, \tilde{f}_{i}\right)\right)_{A}=\left(\left(v, \hat{f}_{i-1}\right)\right)_{B} \quad \forall v \in V_{A} . \tag{4.1}
\end{equation*}
$$

We often succeed in finding such a function, because, roughly speaking, (4.1) means to solve the problem

$$
\begin{equation*}
B \hat{f}_{i-1}=A \tilde{f}_{i} \tag{4.2}
\end{equation*}
$$

with $\tilde{f}_{i}$ known, and this problem is considerably simpler to solve than the "inverse" problem, because the order of the operator $B$ is smaller than that of the operator $A^{14}$ ). If, especially, $B$ is the identity operator and if all the data are sufficiently smooth, $\hat{f}_{i-1}$ is received only by differentiation ${ }^{15}$ ). Now, because (4.1) is fulfilled exactly, not only approximately, we can apply the estimate (1.44) with $f_{0}=\hat{f}_{i-1}$, $f_{1}=\tilde{f}_{i}$. Thus denoting

$$
\begin{gather*}
\hat{a}_{0}=\left(\left(\hat{f}_{i-1}, \hat{f}_{i-1}\right)\right)_{B}, \quad \hat{a}_{1}=\left(\left(\hat{f}_{i-1}, \tilde{f}_{i}\right)\right)_{B}, \quad \hat{a}_{2}=\left(\left(\tilde{f}_{i}, \tilde{f}_{i}\right)\right)_{B},  \tag{4.3}\\
\hat{x}_{1}=\hat{a}_{0} / \hat{a}_{1}, \quad \hat{x}_{2}=\hat{a}_{1} / \hat{a}_{2},
\end{gather*}
$$

we have under the same assumptions as before ( $\lambda_{1}$ simple, $\hat{\boldsymbol{x}}_{2}<I_{2} \leqq \lambda_{2}$ )

$$
\begin{equation*}
\hat{x}_{2}-\frac{\hat{x}_{1}-\hat{x}_{2}}{\frac{l_{2}}{\hat{x}_{2}}-1} \leqq \lambda_{1} \leqq \hat{x}_{2} . \tag{4.4}
\end{equation*}
$$

[^9]Example 4.1. Let us solve the eigenvalue problem

$$
\begin{equation*}
A u-\lambda B u=0, \quad u \neq 0, \tag{4.5}
\end{equation*}
$$

with

$$
\begin{gather*}
A=(9+\cos y) \frac{\partial^{4}}{\partial x^{4}}+18 \frac{\partial^{4}}{\partial x^{2} \partial y^{2}}+(9-\cos x) \frac{\partial^{4}}{\partial y^{4}}  \tag{4.6}\\
B=-\Delta=-\left(\frac{\partial^{2}}{\partial x^{2}}+\frac{\partial^{2}}{\partial y^{2}}\right) \tag{4.7}
\end{gather*}
$$

on the square

$$
G=(0, \pi) \times(0, \pi)
$$

with the boundary conditions

$$
\begin{equation*}
u=0, \frac{\partial^{2} u}{\partial v^{2}}=0 \quad \text { on the boundary } \Gamma \tag{4.8}
\end{equation*}
$$

Here (the second of the conditions (4.8) being unstable)

$$
\begin{align*}
& V_{A}=\left\{v ; v \in W_{2}^{(2)}(G), v=0 \text { on } \Gamma \text { in the sence of traces }\right\},  \tag{4.9}\\
& V_{B}=\left\{v ; v \in W_{2}^{(1)}(G), v=0 \text { on } \Gamma \text { in the sense of traces }\right\} . \tag{4.10}
\end{align*}
$$

If we multiply (4.5) by $v \in V_{A}$, integrate over $G$ and use formally the Green theorem in the usual way (to get symmetric forms), (4.5) turns into

$$
\begin{equation*}
((v, u))_{A}=\lambda((v, u))_{B} \quad \forall v \in V_{A}, \quad u \neq 0, \tag{4.11}
\end{equation*}
$$

with

$$
\begin{equation*}
((v, u))_{A}=\int_{G}\left\{(9+\cos y) \frac{\partial^{2} u}{\partial x^{2}} \frac{\partial^{2} v}{\partial x^{2}}+18 \frac{\partial^{2} u}{\partial x \partial y} \frac{\partial^{2} v}{\partial x \partial y}+(9-\cos x) \frac{\partial^{2} u}{\partial y^{2}} \frac{\partial^{2} v}{\partial y^{2}}\right\} \mathrm{d} x \mathrm{~d} y \tag{4.12}
\end{equation*}
$$

$$
\begin{equation*}
((v, u))_{B}=\int_{G}\left(\frac{\partial u}{\partial x} \frac{\partial v}{\partial x}+\frac{\partial u}{\partial y} \frac{\partial v}{\partial y}\right) \mathrm{d} x \mathrm{~d} y \tag{4.13}
\end{equation*}
$$

The form (4.12), resp. (4.13) is on $V_{A}$, resp. $V_{B}$ symmetric, bounded and $V_{A^{-}}$, resp. $V_{B}$-elliptic. This can be established precisely in the same way as in [1]. Chaps 22 and 23.

Use of the comparison theorem:
The problem

$$
\begin{equation*}
A_{1} u-\alpha B_{1} u=0 \tag{4.14}
\end{equation*}
$$

where

$$
\begin{gather*}
A_{1}=8 \frac{\zeta^{4}}{\partial x^{4}}+18 \frac{\partial^{4}}{\partial x^{2} \partial y^{2}}+8 \frac{\partial^{4}}{\partial y^{4}},  \tag{4.15}\\
B_{1}=-\Delta,
\end{gather*}
$$

with the same boundary conditions (4.8) on $\Gamma$, has smaller eigenvalues. Here the system of eigenfunctions (not orthonormalized) is known:

$$
\begin{align*}
& \psi_{1}=\sin x \sin y, \\
& \psi_{2}=\sin 2 x \sin y,  \tag{4.17}\\
& \psi_{3}=\sin x \sin 2 y,
\end{align*}
$$

The value of $\alpha_{1}$ follows immediately:

$$
(8+18+8) \sin x \sin y-2 \alpha_{1} \sin x \sin y=0, \quad \alpha_{1}=17 .
$$

Similarly, we get $\alpha_{2}=41.6$.
If we compare our problem with a similar problem

$$
A_{2} u-\beta B_{2} u=0,
$$

where

$$
\begin{gathered}
A_{2}=10 \frac{\partial^{4}}{\partial x^{4}}+18 \frac{\partial^{4}}{\partial x^{2} \partial y^{2}}+10 \frac{\partial^{4}}{\partial y^{4}} \\
B_{2}=-\Delta,
\end{gathered}
$$

with the same boundary conditions, we get in a quite analogous way upper estimates for $\lambda_{1}$ and $\lambda_{2}$ :

$$
\beta_{1}=19, \quad \beta_{2}=48.4
$$

Thus we have

$$
\begin{equation*}
17 \leqq \lambda_{1} \leqq 19, \quad 41.6 \leqq \lambda_{2} \leqq 48.4 . \tag{4.18}
\end{equation*}
$$

Especially it follows that $\lambda_{1}$ is simple. At the same time, we have a lower bound $41 \cdot 6$ for $\lambda_{2}$.

Choose in the Ritz method the system (4.17) for the base (this is possible, see [1], Chap. 20) and choose $f_{0}=\psi_{1}=\sin x \sin y$. Let, first, $N=1$, so that we look for $\tilde{f}_{i}$ in the form

$$
\tilde{f}_{i}=k \psi_{1}=k \sin x \sin y .
$$

The Ritz system reduces here to

$$
\left(\left(\psi_{1}, \psi_{1}\right)\right)_{A} k_{11}=\left(\left(f_{0}, \psi_{1}\right)\right)_{B}=\left(\left(\psi_{1}, \psi_{1}\right)\right)_{B} .
$$

A simple computation leads to the equation

$$
9 k_{11}=1 / 2,
$$

i.e.

$$
\tilde{f}_{1}=\frac{1}{18} \sin x \sin y .
$$

Now, it is possible to find the error $\varepsilon$ (see (3.72)) and use the estimate (3.73). Instead of this, we show that it is possible to find in a simple way such a function $\hat{f}_{0}$ for which

$$
B \hat{f}_{0}=A \tilde{f}_{1}
$$

Performing $A \tilde{f}_{1}$, we get
(4.19) $B \hat{f}_{0}=\frac{1}{18}[(9+\cos y) \sin x \sin y+18 \sin x \sin y+(9-\cos x) \sin x \sin y]=$

$$
=2 \sin x \sin y+\frac{1}{36} \sin x \sin 2 y-\frac{1}{36} \sin 2 x \sin y .
$$

From (4.19) and from the form of the operator $B$ it follows that $\hat{f}_{0}$ will be of the form

$$
\hat{f}_{0}=k_{1} \psi_{1}+k_{2} \psi_{2}+k_{3} \psi_{3} .
$$

A simple computation then leads to the result

$$
\hat{f}_{0}=\sin x \sin y+1 / 180 \sin x \sin 2 y-1 / 180 \sin 2 x \sin y .
$$

Now, we apply (4.3) with $i=1$. We get

$$
\hat{x}_{1}=18.0027, \quad \hat{x}_{2}=18 .
$$

We can take $l_{2}=\alpha_{2}=41.6$ (see 4.18)) and get finally

$$
18-\frac{0 \cdot 002 \overline{7}}{\frac{41.6}{18}-1} \leqq \lambda_{1} \leqq 18,
$$

wherefrom

$$
17.997 \overline{8} \leqq \lambda_{1} \leqq 18
$$

Thus we have obtained by our method a very satisfactory result performing only one iterative step and taking even one term of the base in the Ritz method.

## References

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# O JEDNÉ METODĚ DVOUSTRANNÝCH ODHADU゚ VLASTNÍCH ČÍSEL ELIPTICKÝCH DIFERENCIÁLNÍCH ROVNIC TVARU $A u-\lambda B u=0$ 

## Karel Rektorys a Zdeněk Vospěl

Collatzova metoda dvoustranných odhadů vlastních čísel typu (1.7), resp. (1.10), koncipovaná pro obyčejné diferenciálnı rovnice, byla rozsiiriena na případ dostatečně obecných eliptických rovnic tvaru $A u-\lambda B u=0 \mathrm{~K}$. Rektorysem v jeho monografii [1]. Zatímco však v případě obyčejných rovnic se často podaří řešit okrajové problémy (1.8) přesně, je v případě parciálních rovnic zpravidla třeba užít přibližných metod (Ritzovy metody, metody konečných prvků apod.). Tím ovšem nedostaneme přesné hodnoty Schwarzových kvocientů $\varkappa_{k}$, nýbrž jen přibližné hodnoty $\tilde{x}_{k}$. Zmíněné dvoustranné odhady s těmito $\tilde{x}_{k}$, dosazenými za $\chi_{k}$, pak obecně neplatí. Cílem práce je ukázat použitelnost uvedené metody i v tomto případě.
Proto autoři použili poněkud jiného postupu než jakého se užívá v knize [1] a dokázali nejprve větu 2.1 (str. 224), týkající se vlastností Schwarzových kvocientů a dvoustranných odhadủ Collatzova typu (odvozených bez užití Templeovy věty). V kap. 3 pak ukázali (viz větu 3.1, str. 234), že „přibližné" Schwarzovy kvocienty $\tilde{\chi}_{k}$ mají podobné vlastnosti a že při přibližném řešení zmíněných okrajových problémů lze místo odhadu (2.44) (s přesnými Schwarzovými kvocienty) použít odhadu (3.73).

Přestože tento odhad není nijak komplikovaný, činí někdy potiže praktické určení odhadu čísla $\varepsilon$ (chyby přibližného řešení). Proto je v kap. 4 uvedena určitá modifikace uvažované metody, která vede často k cíli podstatně jednodušší cestou. Zároveň je uveden numerický příklad ukazující praktické užití této metody a demonstrující její přesnost.

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[^0]:    ${ }^{1}$ ) The usual "licence" is chosen for the ordering of eigenvalues in order that the correspondence between (1.31) and (1.32) be one-to-one.

[^1]:    ${ }^{2}$ ) This assumption does not represent a substantial restriction, in practice, see Remark 3.4, p. 235 .

[^2]:    ${ }^{3}$ ) Because of (2.5). It follows that $a_{i}>0, i=0,1,2, \ldots$

[^3]:    ${ }^{4}$ ) Or not, cf. (2.33).

[^4]:    ${ }^{5}$ ) See, however, Remark 2.1.
    ${ }^{6}$ ) On $\bar{V}_{A}$ and $\bar{V}_{B}$ see p. 213.
    ${ }^{7}$ ) Received, as a rule, using an appropriate comparison theorem.

[^5]:    ${ }^{8}$ ) This fact is mentioned from theoretical reasons only, see (3.18), etc.

[^6]:    ${ }^{9}$ ) The functions $\hat{f}_{i}$ play only an auxiliary role here, they are not constructed, actually.

[^7]:    ${ }^{11}$ ) Or by an other method with similar properties, e.g. by the finite element method.

[^8]:    ${ }^{12}$ ) (3.72) can always be achieved for an arbitrary $\varepsilon>0$ if only $N$ is sufficiently large.

[^9]:    ${ }^{13}$ ) In practice, $i=1$ or $i=2$ is often sufficient.
    ${ }^{14}$ ) Moreover, the corresponding twosided estimate obtained in this way is very accurate, see [4]. See also Example 4.1.
    ${ }^{15}$ ) If finite element method is used, this step requires application of smoother spline functions.

