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ROUNDING ERRORS IN ALTERNATING DIRECTION METHODS
FOR PARABOLIC PROBLEMS

H. H. RACHFORD, JR.

Recently, the rounding error growth in solving a Crank-Nicolson difference analogue of a general second order parabolic problem with smooth coefficients in one space variable was analyzed [1]. It was shown that to maintain a fixed bound on rounding-induced errors the word length of the floating mantissa must be increased in proportion to the logarithm of the number of time-distance mesh points as the time and distance steps, k and h , are taken to zero at constant k/h . The present work shows that the analysis can be extended to the p -dimensional case when the computation is done using a stable, consistent, two-level alternating direction procedure. In this case, the required increase in word length is proportional to $\log(p^2 \bar{N} \bar{M}^2)$ where \bar{N} is the maximum number of grid points in any line in R_h , the mesh covering the spatial domain, and \bar{M} is the number of time steps.

Let $L(u) \equiv \sum_{i=1}^p [(\partial/\partial x_i)(\bar{\alpha}(x, t)(\partial u/\partial x_i)) + \xi(x, t)(\partial u/\partial x_i)] + \gamma(x, t)u$, and consider

$$(1) \quad L(u) = \frac{\partial u}{\partial t} + f(x, t)$$

in a bounded region $R \times (0, T]$, where $R \subset \mathbf{R}^p$, $\bar{\alpha}$, ξ , and γ are scalar valued continuous function of $x \in \mathbf{R}^p$ and time, t , $0 < \alpha_0 \leq \bar{\alpha} \leq \alpha_m$, $\gamma \leq 0$, and u is specified such that fourth distance derivatives of u are bounded. We consider the operators

$$(2) \quad -L_h w(P, t) \equiv \bar{\nabla}_i(\bar{\alpha}(P_i^{+1/2}, t) \nabla_i w(P, t)) + \left(\frac{1}{2h_i}\right) \xi(P, t) [w(P_i^+, t) - w(P_i^-, t)] \\ + \gamma(P, t) w(P, t)/p$$

where the grid of points R_h over R is generated by the increment vector $h = (h_1, \dots, h_p)$, $P \in R_h$ is defined by $P = (x_1, \dots, x_i, \dots, x_p)$, $P_i^\pm = (x_1, \dots, x_i \pm h_i, \dots, x_p)$, $P_i^{\pm 1/2} = (x_1, \dots, x_i + h_{i/2}, \dots, x_p)$, $\nabla_i w(P) = [w(P_i^+) - w(P)] h_i^{-1}$ and $\bar{\nabla}_i w(P) = \nabla_i w(P_i^-)$. The Crank-Nicolson difference analogue of (1) becomes

$$(3) \quad w(P, t_{n+1}) + \frac{1}{2}k \sum_{i=1}^p L_{h_i} [w(P, t_{n+1}) + w(P, t_n)] = w(P, t_n) - kf(P, t_n + \frac{1}{2}k),$$

which relates the values of the approximation w at points of $(R_h \cup C_h) \times \{t_n\}$, where $t_n = nk$, $n = 0, 1, \dots, K - 1$, $K = T/k$, and where the points C_h are points on $\partial R \times \{t_n\}$. We let N_h be the number of points of R_h and $\|v\| = (h_1, \dots, h_p \sum_{R_h} v_i^2)^{1/2}$ for all $v \in \mathbf{R}^{N_h}$. The relation (2) is evidently of the form

$$(4) \quad (I + A) w_{n+1} + B w_n = g_n, \quad n = 0, 1, \dots, K - 1,$$

where A and B depend also on n . Letting $\sum_{i=1}^p A_i = A$ and noting that $(I + A_i) w = z$ is readily solved, the alternating direction form of (4) is

$$(5a) \quad (I + A_1) \beta_{n+1}^{(1)} + \sum_{j=2}^p A_j \beta_n + B \beta_n = g_n$$

$$(5b) \quad (I + A_i) \beta_{n+1}^{(i)} = \beta_{n+1}^{(i-1)} + A_i \beta_n, \quad i = 2, \dots, p,$$

and the approximation for u_{n+1}, β_{n+1} is taken to be $\beta_{n+1}^{(p)}$.

The computations using (5) produce not $\{\beta_n\}$ but a sequence $\{\hat{\beta}_n\}$, which differs from $\{\beta_n\}$ due to rounding. We follow the type of analysis of WILKINSON [2] and write $\beta_{n+1}^{(i)} = Q_i d_i$, $\hat{\beta}_{n+1}^{(i)} = \hat{Q}_i \hat{d}_i$, where

$$d_1 = g_n - (B + A - A_1) \beta_n, \quad d_i = \beta_{n+1}^{(i-1)} + A_i \beta_n, \quad i = 2, \dots, p,$$

and

$$\hat{d}_1 = g_n - (B + A - A_1) \hat{\beta}_n + e_1, \quad \hat{d}_i = \hat{\beta}_{n+1}^{(i-1)} + A_i \hat{\beta}_n + e_i, \quad i = 2, \dots, p,$$

where e_i is the error introduced in computing \hat{d}_i from the stated arguments, $Q_i = (I + A_i)^{-1}$, and \hat{Q}_i is a matrix approximating Q_i whose existence and exact form depend upon the procedure used to solve (5).

We assume several quantities relevant to the problem to be solved:

$$(6a) \quad \|(I + A_i)^{-1}\| < 1/\delta, \quad \delta > 0,$$

$$(6b) \quad \max(\|g_n\| + 2\sum_i \|A_i \beta_n\| + \|B \beta_n\|, \|\beta_n\|) \leq \beta,$$

$$(6c) \quad \|R_i\| \leq M(\tau),$$

where $R_i = \hat{Q}_i Q_i^{-1} - I$, and τ is the number of floating base N digits in the mantissa. The existence of β and δ follow from consistency and stability of (5).

From (5), (6), and an examination of $\prod_{i=j}^q \hat{Q}_i - \prod_{i=j}^q Q_i$, we conclude that

$$(7) \quad \|v_{n+1}\| \leq [(1 + M)^p - 1] \delta^{-p} [g_n + \sum_{j=1}^p \|A_j \beta_n\| + \|(B + A) \beta_n\|] + \\ + \varrho(\varrho^p - 1)(\varrho - 1)^{-1} \eta_n + [\|G\| + \|\sum_{j=1}^p (\prod_{i=j}^p \hat{Q}_i - \prod_{i=j}^p Q_i) A_j - \\ - (\prod_{j=1}^p \hat{Q}_j - \prod_{j=1}^p Q_j)(B + A)\|] \|v_n\|$$

where $v_n = \hat{\beta}_n - \beta_n$, $\varrho = (1 + M)/\delta$, η_n is a bound on $\|e_i\|$, and $G \equiv \sum_{j=1}^p \prod_{i=j}^p Q_i A_j - \prod_{k=1}^p Q_k (B + A)$. It will be seen to be important below that G is the matrix such that $\beta_{n+1} = G\beta_n + Hg_n$ from (5); hence, by stability of (5), $\|G\| \leq 1 + C_0k$ for all n .

Using the methods of (2), we find that

$$(8) \quad \eta_n = [(k_1 + S)\beta + (k_2 + \beta\delta^{-p} + \alpha)\|v_n\|] v / (1 - \zeta v),$$

where

$$k_1 = \max \{1 + (1 + v) N_0 [\|B\| + a(p - 1)], [1 + (1 + v) a N_0]\},$$

$$k_2 = \max \{[\|B\| + a(p - 1)] [1 + (1 + v) N_0], a[(1 + v) N_0 + 1]\},$$

and a is a bound on $\|A_i\|$, $v = sN^{1-\tau_1}$, $s = \frac{1}{2}$ or 1 as rounding or chopping occurs in storage, $\tau_1 = \tau - \log_N 1.053$, N_0 is the maximum number of sums taken for any element of any matrix-by-vector multiplication in d_i , $\mu = \varrho^p - \delta^{-p}$, $S = \mu + \delta^{-p}$, $\alpha = \mu Y$, $Y = A \sum_{j=1}^p \|A_j\| + \|B + A\|$, and $\zeta = \varrho(\varrho^p - 1)(\varrho - 1)^{-1}$. It follows from (8) that

$$(9) \quad \|v_n\| \leq \varphi_2(\varphi_1^n - 1)(\varphi_1 - 1)^{-1},$$

where $\varphi_1 = [\|G\| + \alpha + v\zeta(k_2 + \alpha + \beta\delta^{-p})(1 - \zeta v)^{-1}]$ and $\varphi_2 = [\mu + \zeta v(k_1 + S)(1 - \zeta v)^{-1}]\beta$. We assume now that h is fixed and that the computations are carried out so that M decreases at least linearly with v . Expansion of α shows that $\alpha = c_1' M + O(M^2)$ for M small. Thus, if $M = \check{c}_1 v / c_1'$ and we choose $v = \check{c}_1 k$, then $\alpha \leq c_1 k$; hence, $\varphi_1 = 1 + c_3 k + O(k^2)$. Since $\mu = c_4 k + O(k^2)$, $\varphi_2 \leq \beta c_5 k$ for k small, and

$$(10) \quad \|v_n\| \leq c_5 T e^{c_3 T}.$$

This is satisfactory as it is exactly the same result that would obtain were $L(u) = \partial u / \partial t$ an ordinary differential equation in t .

The question of real interest arises when $h/k = c$ while $k \rightarrow 0$. A suitable ordering of $P \in R_h$ yields A_i as a diagonal set of m tridiagonal blocks, each irreducible for h_i sufficiently small, where m is the number of physical rows of points of R_h in R associated with the i th direction. Thus, the solution of $(I + A_i)w = z$ is the solution of m independent tridiagonal systems of the form

$$(11) \quad \begin{pmatrix} b_1, c_1, 0, \dots, 0, 0 \\ a_2, b_2, c_2, \dots, 0, 0 \\ \dots \\ 0, 0, 0, \dots, a_j, b_j \end{pmatrix} \begin{pmatrix} w_1 \\ \cdot \\ \cdot \\ w_j \end{pmatrix} \equiv \Gamma_s w = r_i \bar{d} = d; \quad s = 1, \dots, m,$$

where \bar{d} is an m -segment of z and r_i is a normalizing factor so that for h_i

sufficiently small

- (12) i) $\delta + |a_j| + |c_j| < b_j(1 - 4v - 3v^2 - v^3); j = 1, \dots, J,$
 ii) $-1 \leq a_i, c_j < 0; j = 1, \dots, J - 1; i = 2, \dots, J,$ the left hand equality holding for some row of some $\Gamma_s; s = 1, \dots, m,$
 iii) $a_1 = c_J = 0,$
 iv) $\delta > 0.$

It is easy to see that $\|\Gamma_s\|_\infty < \delta^{-1},$ hence, $\delta = 1$ suffices for (6a). Analysis of the floating point operations involved in (11) shows [1] indeed that \hat{Q}_i does exist with M of (6c) given by

$$M = (15 + 2\|\Gamma\|_\infty) v\delta^{-1} + O(v\delta^{-1})^2.$$

Taking $v = c_2 h_j k^2, h_j \leq h_i,$ assuming $h_i/k = c$ fixed as $k \rightarrow 0$ leads to $v\delta^{-1} = \alpha_m c_2 k^2 / 2c + O(k^3),$ where $\alpha_m = \max_{P \in R_n} \bar{\alpha}(P_i^{\pm 1/2}).$ For k small, φ_1 and φ_2 of (9) now satisfy: $\varphi_1 \leq 1 + c'_3 k,$ and $\varphi_2 \leq c'_5 k^2$ for any $c'_i > c_0 + 69\alpha_m^2 p^2 c_2 c^{-3},$ and $c'_5 > c_2 c^{-1} \alpha_m \beta p(12p - \frac{11}{2}).$

The following theorem follows from the analysis outlined above.

Theorem. *Let (1) be solved in a hypercube using (5) which is assumed to be stable and consistent with c_0 independent of $p.$ Computation is performed with τ -digit floating- N arithmetic. If $N^{-\tau} = \hat{c}_2 h_j p^{-2} k^2, h_j \leq h_i, i = 1, 2, \dots, p, h_j = ck,$ and if $\hat{\beta}_n$ and β_n are the computed and exact solutions for (5), respectively, then as $k \rightarrow 0$*

$$\|\hat{\beta}_n - \beta_n\| \leq k c_s'' T e^{c''_3 T},$$

where $c_s'' > c_0 + 73s N \bar{\alpha}_M^2 \hat{c}_2 c^{-3}, c_s'' > 1.053sN \hat{c}_2 c^{-1} \bar{\alpha}_M \beta [12 - 11(2p)^{-1}]$ and s is $\frac{1}{2}$ or 1 as rounding or truncation occurs, respectively.

Although the analysis has ignored the variations of A and B with $n,$ we need only note that the bounds may be interpreted over all $n,$ and that stability implies $\|G_n\| \leq \leq 1 + C_0 k$ independent of n to complete the proof. Further, the analysis does not assume symmetry of $A_i,$ but only the inequalities (12). Thus, for any shape region approximated with difference relations of positive type we shall expect the theorem to hold.

References

- [1] *Rachford, H. H. Jr., Rounding Errors in Parabolic Problems, Part I. The one space variable case, to appear.*
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